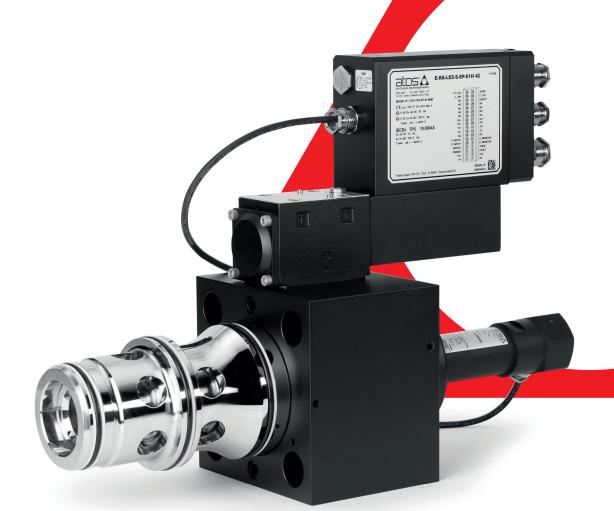
Гидравлика пропорциональная взрывозащищенная ATOS

Технические характеристики



Алматы (7273)495-231 Ангарск (3955)60-70-56 Архангельск (8182)63-90-72 Астрахань (8512)99-46-04 Барнаул (3852)73-04-60 Белгород (4722)40-23-64 Благовещенск (4162)22-76-07 Брянск (4832)59-03-52 Владивосток (423)249-28-31 Владикавказ (8672)28-90-48 Владимир (4922)49-43-18 Волгоград (844)278-03-48 Вологда (8172)26-41-59 Ворогда (8172)26-41-59 Воронеж (473)204-51-73 Екатеринбург (343)384-55-89 Иваново (4932)77-34-06 Ижевск (3412)26-03-58 Иркутск (395)279-98-46 Казань (843)206-01-48 Калининград (4012)72-03-81 Калуга (4842)92-23-67 Кемерово (3842)65-04-62 Киров (8332)68-02-04 Коломна (4966)23-41-49 Кострома (4942)77-07-48 Краснодар (861)203-40-90 Красноярск (391)204-63-61 Курск (4712)77-13-04 Курган (3522)50-90-47 Липецк (4742)52-20-81

Магнитогорск (3519)55-03-13 Москва (495)268-04-70 Мурманск (8152)59-64-93 Набережные Челны (8552)20-53-41 Нижний Новгород (831)429-08-12 Новокузнецк (3843)20-46-81 Ноябрьск (3496)41-32-12 Новосибирск (383)227-86-73 Омск (3812)21-46-40 Орел (4862)44-53-42 Оренбург (3532)37-68-04 Пенза (8412)22-31-16 Петрозаводск (8142)55-98-37 Псков (8112)59-10-37 Пермь (342)205-81-47

Ростов-на-Дону (863)308-18-15 Рязань (4912)46-61-64 Самара (846)206-03-16 Саранск (8342)22-96-24 Санкт-Петербург (812)309-46-40 Саратов (845)249-38-78 Севастополь (8692)22-31-93 Симферополь (3652)67-13-56 Смоленск (4812)29-41-54 Сочи (862)225-72-31 Ставрополь (8652)20-65-13 Сыктывкар (8212)25-95-17 Тамбов (4752)50-40-97 Сургут (3462)77-98-35 Тверь (4822)63-31-35

Тольятти (8482)63-91-07 Томск (3822)98-41-53 Тула (4872)74-02-29 Тюмень (3452)66-21-18 Ульяновск (8422)24-23-59 Улан-Удэ (3012)59-97-51 Уфа (347)229-48-12 Хабаровск (4212)92-98-04 Чебоксары (8352)28-53-07 Челябинск (351)202-03-61 Череповец (8202)49-02-64 Чита (3022)38-34-83 Якутск (4112)23-90-97 Ярославль (4852)69-52-93

Россия (495)268-04-70

Казахстан (772)734-952-31

Киргизия (996)312-96-26-47



Ex-d

		Size	Qmax [l/min]	Table	Pag
SERVOPROPORTIONAL D	PIRECTIONALS				
zero overlap with LVDT tra	nsducer				
DLHZA-TES, DLKZA-TES	direct, sleeve execution, on-board driver	06 ÷ 10	50 ÷ 100	FX150	9
DLHZA-T, DLKZA-T	direct, sleeve execution, off-board driver	06 ÷ 10	50 ÷ 100	FX140	21
DHZA-TES, DKZA-TES	direct, on-board driver	06 ÷ 10	60 ÷ 150	FX135	27
DPZA-LES	piloted, on-board driver, 2 LVDT transducers	10 ÷ 27	180 ÷ 800	FX235	37
LIQZA-LES	3 way cartridge, piloted, on-board driver, 2 LVDT transducers	25 ÷ 80	500 ÷ 5000	FX380	49
LIQZA-L	3 way cartridge, piloted, off-board driver, 2 LVDT transducers	25 ÷ 80	500 ÷ 5000	FX370	59
HIGH PERFORMANCE DIF positive overlap with LVD1					
DHZA-TES, DKZA-TES	direct, on-board driver	06 ÷ 10	60 ÷ 150	FX130	65

-, -					
DHZA-T, DKZA-T	direct, off-board driver	06 ÷ 10	60 ÷ 150	FX120	77
DPZA-LES	piloted, on-board driver, 2 LVDT transducers	10 ÷ 27	180 ÷ 800	FX230	83
DPZA-T	piloted, off-board driver, 1 LVDT transducer	10 ÷ 32	180 ÷ 1000	FX220	95
LIQZA-LES	2 way ISO cartridge, piloted, on-board driver, 2 LVDT transducers	25 ÷ 100	1200 ÷ 16000	FX360	103
LIQZA-L	2 way ISO cartridge, piloted, off-board driver, 2 LVDT transducers	25 ÷ 100	1200 ÷ 16000	FX350	113

DIRECTIONAL VALVES

positive overlap without transducer

DHZA-AES, DKZA-AES	direct, on-board driver	06 ÷ 10	60 ÷ 120	FX110	121
DHZA-A, DKZA-A	direct, off-board driver	06 ÷ 10	60 ÷ 120	FX100	133
DPZA-AES	piloted, on-board driver	10 ÷ 32	180 ÷ 1500	FX210	141
DPZA-A	piloted, off-board driver	10 ÷ 32	180 ÷ 1500	FX200	153

HIGH PERFORMANCE PRESSURE VALVES

relief, direct or piloted, on-board driver	06 ÷ 32	4 ÷ 600	FX030	161
reducing, direct or piloted, on-board driver	06 ÷ 20	12 ÷ 300	FX060	173
relief ISO cartridge, piloted, on-board driver	16 ÷ 80	200 ÷ 4500		
reducing ISO cartridge, piloted, on-board driver	16 ÷ 40	160 ÷ 800	FX320	185
compensator ISO cartridge, piloted, on-board driver	16 ÷ 50	200 ÷ 2000		
	reducing, direct or piloted, on-board driver relief ISO cartridge, piloted, on-board driver reducing ISO cartridge, piloted, on-board driver	reducing, direct or piloted, on-board driverO6 ÷ 20relief ISO cartridge, piloted, on-board driver16 ÷ 80reducing ISO cartridge, piloted, on-board driver16 ÷ 40	reducing, direct or piloted, on-board driver06 ÷ 2012 ÷ 300relief ISO cartridge, piloted, on-board driver16 ÷ 80200 ÷ 4500reducing ISO cartridge, piloted, on-board driver16 ÷ 40160 ÷ 800	reducing, direct or piloted, on-board driver06 ÷ 2012 ÷ 300FX060relief ISO cartridge, piloted, on-board driver16 ÷ 80200 ÷ 4500reducing ISO cartridge, piloted, on-board driver16 ÷ 40160 ÷ 800FX320

PRESSURE VALVES without transducer RZMA-AES, AGMZA-AES relief, direct or piloted, on-board driver 06 ÷ 32 4 ÷ 600 197 FX020 06 ÷ 32 4 ÷ 600 RZMA-A, AGMZA-A relief, direct or piloted, off-board driver FX010 209 HZMA-A relief, piloted, off-board driver, modular 06 40 RZGA-AES, AGRCZA-AES reducing, direct or piloted, on-board driver 06 ÷ 20 12 ÷ 300 FX050 217 12 ÷ 300 RZGA-A, AGRCZA-A reducing, direct or piloted, off-board driver 06 ÷ 20 FX040 227 40 ÷ 100 HZGA-A, KZGA-A reducing, piloted, off-board driver, modular 06 ÷ 10 200 ÷ 4500 LIMZA-AES relief ISO cartridge, piloted, on-board driver 16 ÷ 80 160 ÷ 800 LIRZA-AES reducing ISO cartridge, piloted, on-board driver 16 ÷ 40 FX310 235 LICZA-AES compensator ISO cartridge, piloted, on-board driver 16 ÷ 50 200 ÷ 2000 LIMZA-A relief ISO cartridge, piloted, off-board driver 16 ÷ 80 200 ÷ 4500 LIRZA-A reducing ISO cartridge, piloted, off-board driver 16 ÷ 40 160 ÷ 800 FX300 247 LICZA-A compensator ISO cartridge, piloted, off-board driver 16 ÷ 50 200 ÷ 2000 for pilot lines, without transducer DHRZA-AES 06 FX080 255 3 way reducing, direct, on-board driver 24 DHRZA-A 3 way reducing, direct, off-board driver 06 24 FX070 263 **FLOW VALVES** pressure compensated QVHZA-TES, QVKZA-TES direct, on-board driver, LVDT transducer 06 ÷ 10 45 ÷ 90 FX430 269 QVHZA-T, QVKZA-T direct, off-board driver, LVDT transducer 06 ÷ 10 45 ÷ 90 FX420 279

Size

06 ÷ 10

06 ÷ 10

45 ÷ 90

45 ÷ 90

FX410

FX400

285

295

Qmax [l/min]

Table

Pag

ELECTRONIC DRIVERS

QVHZA-AES, QVKZA-AES

QVHZA-A, QVKZA-A

off-board digital, DIN-rail EN 60715

E-BM-TES/A, E-BM-LES/	GS240	301	
E-BM-TEB/A, E-BM-LEB/	A for directional and flow valves with LVDT transducers	GS230	309
E-BM-AES/A	for valves without transducer, fieldbus	GS050	315
E-BM-AS/A	for valves without transducer	G030	321

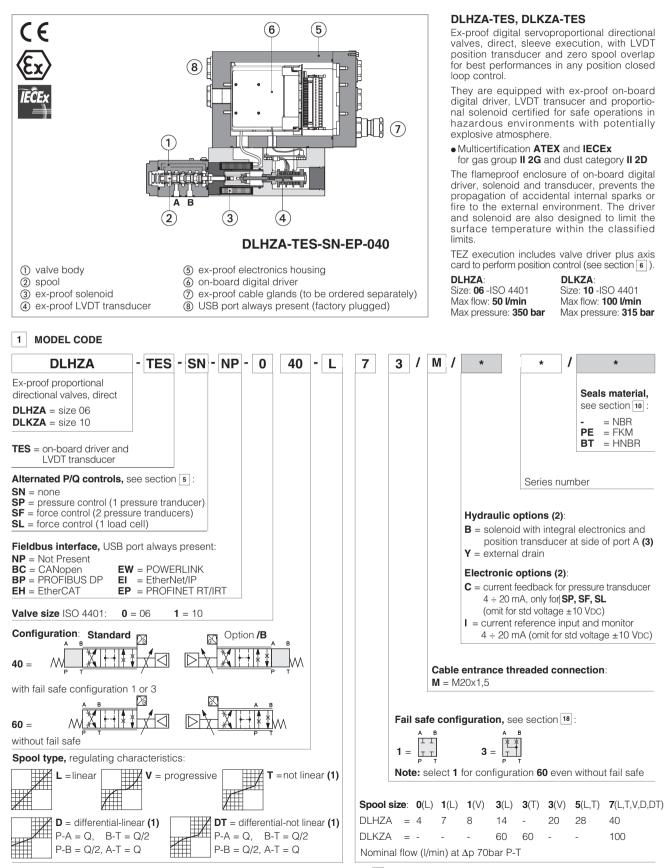
direct, on-board driver, without transducer

direct, off-board driver, without transducer

atos°A

Ex-proof digital servoproportional directional valves sleeve execution

direct, with on-board driver, LVDT transducer and zero spool overlap - ATEX and IECEx



(1) Only for configuration 40 (2) For possible combined options, see section 16

2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.



WARNING: the below operation must be performed in a safety area Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)
E-SW-*/PQ	support:	valves with SP, SF,	SL alternated control (e	e.g. E-SW-BASIC/PQ)
	a: drivers	USB port is not i	solated! For E-C-SB-	-USB/M12 cable, the use

of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 ALTERNATED P/Q CONTROLS - see tech. table FX500

S* options add the closed loop control of pressure (SP) or force (SF and SL) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions. An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers

An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers for SF or 1 load cell for SL). The alternated pressure control (SP) is possible only for specific installation conditions.

6 AXIS CONTROLLER - see tech. table FX610

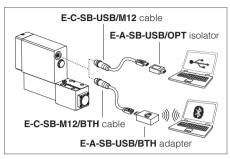
Digital servoproportional with integral electronics **TEZ** include valve's driver plus axis controller, performing position closed loop of any hydraulic actuator equipped with analog, encoder or SSI position transducer. Alternated pressure or force closed loop control can be set by software additionally to the position control.

Atos also supplies complete servoactuators integrating servocylinder, digital servoproportional valve and axis controller, fully assembled and tested. For more information consult Atos Technical Office.

7 GENERAL CHARACTERISTICS

Assembly position	Any position							
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100							
MTTFd valves according to EN ISO 13849	150 years, see technical table P007							
Ambient temperature range	Standard = -20° C \div +60°C /PE option = -20° C \div +60°C /BT option = -40° C \div +60°C							
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$							
Surface protection	Zinc coating with black passivation - salt spray test (ISO 9227) > 200 h							
Compliance	Explosion proof protection, see section 11 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"							
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006							

USB or Bluetooth connection



8 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model				DLHZA					DLKZA												
Pressure limit	S	[bar]												ts P , A , B = 315; 50 with external drain /Y)							
Spool type			L0	L1	V1	L3	V3	L5	T5	L7	T 7	V7	D7	DT7	L3	Т3	L7	T 7	V7	D7	DT7
Nominal flow	[l/min]																			1	
		at $\Delta p = 30$ bar	2,5	4,5	8	9	13	18	3		26		26-	÷13	4	0		60		60	÷33
∆р Р-Т		at $\Delta p = 70$ bar	4	7	12	14	20	28	}		40		40-	÷20	6	0		100		100)÷50
	max p	ermissible flow	5	9	16	18	26	32	2		50		50-	÷28	7	0		100		100)÷50
∆p max P-T		[bar]	120	120	120	120	120	100	0		100		1(00	9	0		70		7	70
Leakage [cm ³	³/min] at F	^D = 100 bar (1)	<100	<200	<100	<300	<150	<500 <	<200	<900	<200	<200	<700	<200	<1000	<400	<1500	<400	<400	<1200)<400
Response tim	ne	[ms] (2)						≤ 1	3									≤20			
Hysteresis	[% of r	max regulation]						≤0,	,1									≤0,1			
Repeatibility	[% of r	max regulation]		± 0,1							± 0,1										
Thermal drift								zer	o poi	nt dis	place	ement	< 1%	at ∆T	= 40	°C					

(1) referred to spool in neutral position and 50°C oil temperature

(2) 0-100% step signal

9 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal Rectified and filtered	: +24 VDC : VRMS = 20 ÷ 32 VMAX	(ripple max 10 % VPP)							
Max power consumption	35 W									
Analog input signals	Voltage: range ±10 V Current: range ±20 r	/DC (24 VMAX tollerant) nA	Input impedance Input impedance							
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards SO 13732-1 and EN982 must be taken into account								
Monitor outputs		Dutput range: voltage ±10 VDC @ max 5 mA current ±20 mA @ max 500 Ω load resistance								
Enable input	Range: 0 ÷ 5 VDC (OFF	Range: $0 \div 5$ VDC (OFF state), $9 \div 24$ VDC (ON state), $5 \div 9$ VDC (not accepted); Input impedance: Ri > 10 k Ω								
Fault output	Output range: 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)									
Pressure transducer power supply	+24VDC @ max 100 r	mA (E-ATRA-7 see tech	table GX800)							
Alarms	Solenoid not connecte valve spool transduce		preak with current refere	nce signal, over/under temperature,						
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland								
Duty factor	Continuous rating (ED	=100%)								
Tropicalization	Tropical coating on el	ectronics PCB								
Additional characteristics	Short circuit protection of solenoid's current supply; spool position control (SN) or pressure/force control (SP, SF, SL) by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply									
Electromagnetic compatibility (EMC)	According to Directive	e 2014/30/UE (Immunity	: EN 61000-6-2; Emissio	n: EN 61000-6-3)						
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158						
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX						

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

10 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	I temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$					
Recommended viscosity		20 ÷100 mm²/s - max allowed ra	ange 15 ÷ 380 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard			
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524			
Flame resistant without wa	ater	FKM	100 10000				
Flame resistant with water	(1)	NBR, HNBR HFC ISO 12922					

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

11 CERTIFICATION DATA

Valve type	DLHZA, DLKZA									
Certifications	Multicertification Group II									
		ATEX IECEx								
Solenoid certified code		OZA-TES								
Type examination certificate (1)	• ATEX: TUV IT 18 ATEX 068 X	ATEX: TUV IT 18 ATEX 068 X IECEx: IECEx TPS 19.0004X								
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C Db									
Temperature class	T6	Т5	T4							
Surface temperature	≤ 85 °C	≤ 100 °C	≤ 135 °C							
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +55 °C	-40 ÷ +70 °C							
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079-31 EN 60079-1 IEC 60079-1									
Cable entrance: threaded connection	M = M20x1,5									

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

12 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm² **Grounding:** section of external ground wire = 4 mm²

12.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

13 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

14 HYDRAULIC OPTIONS

B = Solenoid, integral electronics and position transducer at side of port A of the main stage. For hydraulic configuration vs reference signal, see 17.1

Y = Option /Y is mandatory if the pressure in port T exceeds 210 bar

15 ELECTRONIC OPTIONS

 I = It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

C = Only for **SP**, **SF**, **SL**

Option /C is available to connect pressure (force) transducers with 4 ÷ 20 mA current output signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

16 POSSIBLE COMBINED OPTIONS

For SN: /BI, /BY, /IY

For SP, SF, SL: /BI, /BY, /IY, /CI, /BCI, CIY, BCIY

17.1 Regulation diagrams

1 = Linear spools L

2 = Differential - linear spool D7

3 = Differential non linear spool DT7

4 = Non linear spool T5 (only for DLHZA)

5 = Non linear spool T3 (only for DLKZA) and T7 6 = Progressive spool V

T5 and T7 spool types are specific for fine low flow control in the range from 0 to 60% (T5) and 0 to 40% (T3 and T7) of max spool stroke.

The non linear characteristics of the spool is compensated by the electronic driver, so the final valve regulation is resulting linear respect the reference signal (dotted line).

DT7 has the same characteristic of T7 but it is specific for applications with cylinders with area ratio 1:2

Note

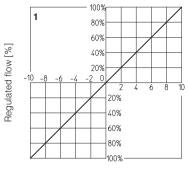
Hydraulic configuration vs. reference signal:

Standard

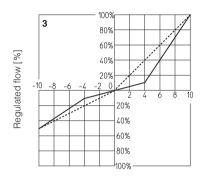
 $\begin{array}{c} 0 \div +10 \text{ V} \\ 12 \div 20 \text{ mA} \end{array} \right\} P \rightarrow A \text{ / } B \rightarrow T$ Reference signal $\begin{array}{c} 0 \div -10 \ V \\ 12 \div 4 \ mA \end{array} \Big\} P \longrightarrow B \ / \ A \longrightarrow T$ Reference signal

option /B

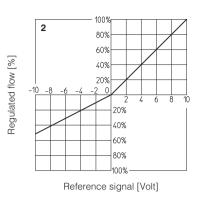
 $\begin{array}{c} 0 \div +10 \text{ V} \\ 12 \div 20 \text{ mA} \end{array} \right\} P \rightarrow B / A \rightarrow T$ Reference signal $\begin{array}{c} 0 \div -10 \ V \\ 12 \div 4 \ mA \end{array} \Big\} P \rightarrow A \ / \ B \rightarrow T$ Reference signal

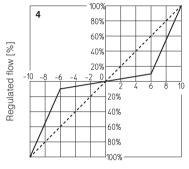




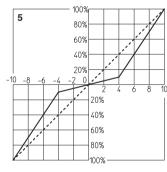


Reference signal [Volt]



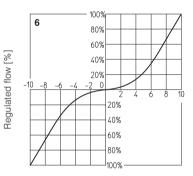


Reference signal [Volt]



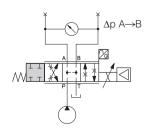
Regulated flow [%]

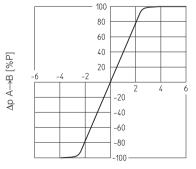
Reference signal [Volt]

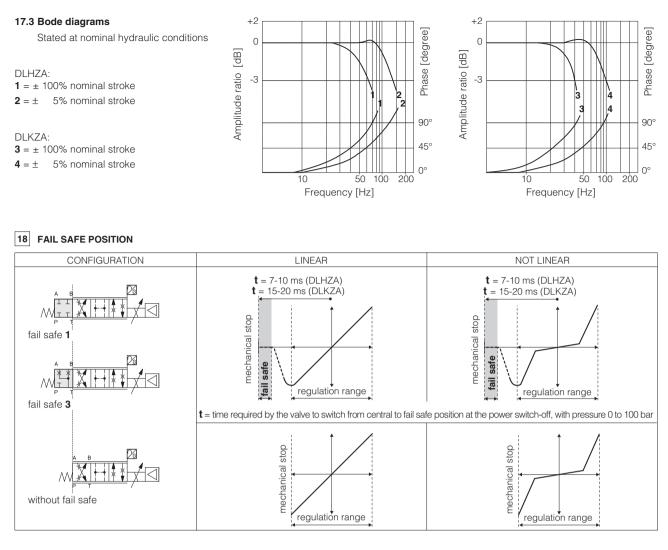


Reference signal [Volt]

17.2 Pressure gain







Fail safe connections		$\mathbf{P} \to \mathbf{A}$	$\mathbf{P} \rightarrow \mathbf{B}$	$\textbf{A} \rightarrow \textbf{T}$	$\textbf{B} \rightarrow \textbf{T}$
Leakage [cm³/min] at P = 100 bar (1)	Fail safe 1	50	70	70	50
	Fail safe 3	50	70	-	-
Elow [I/min] ()	Fail safe 3	-	-	15÷30	10÷20
Flow [I/min] (2) DLKZA	i all sale s	-	-	40÷60	25÷40

(1) Referred to spool in fail safe position and 50°C oil temperature

(2) Referred to spool in fail safe position at $\Delta p = 35$ bar per edge

19 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

19.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

19.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

19.3 Flow reference input signal (Q_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDc.

19.4 Pressure or force reference input signal (F_INPUT+) - only SP, SF, SL

Functionality of F_INPUT+ signal (pin 12), is used as reference for the driver pressure/force closed loop (see tech. table FX500). Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range 0 $\div 24$ VDc.

19.5 Flow monitor output signal (Q_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA.

19.6 Pressure or force monitor output signal (F_MONITOR) - only for SP, SF, SL

The driver generates an analog output signal proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

19.7 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

19.8 Fault output signal (FAULT)

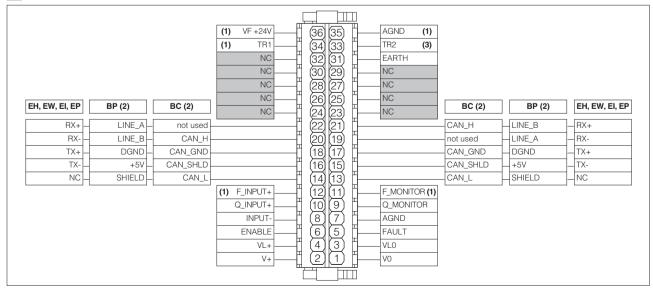
Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

19.9 Remote pressure/force transducer input signal - only for SP, SF, SL

Analog remote pressure transducers or load cell can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see table FX500).

20 TERMINAL BOARD OVERVIEW



(1) connections available only SP, SF, SL

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

(3) connection available only SF

21 ELECTRONIC CONNECTIONS

21.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 VDc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
•	7	AGND	Analog ground	Gnd - analog signal
A	8	INPUT-	Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
	9	Q_MONITOR	Flow monitor output signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND Defaults are: ± 10 Vpc for standard and 4 \div 20 mA for /l option	Output - analog signal Software selectable
	10	Q_INPUT+	Flow reference input signal: ±10 Vbc / ±20 mA maximum range Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	11	F_MONITOR	Pressure/Force monitor output signal: ± 10 Vbc / ± 20 mA maximum range, referred to AGND (1) Defaults are: ± 10 Vbc for standard and 4 $\div 20$ mA for /I option	Output - analog signal Software selectable
	12	F_INPUT+	Pressure/Force reference input signal: ±10 Vbc / ±20 mA maximum range (1) Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /l option	
	31	EARTH	Internally connected to driver housing	

Driver view

ſø

(female)

CABLE ENTRANCE

52

6

2

З

PIN

13

15 17

19

21

1

4

(1) Available only for SP, SF, SL

21.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	1	+5V_USB	Power supply
	2	ID	Identification
B	3	GND_USB	Signal zero data line
	4	D-	Data line -
	5	D+	Data line +

21.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
C1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

21.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

21.5 EH, EW, EI, EP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	ТХ-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
<u> </u>	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

(B)

0

SIGNAL

CAN_L

CAN_GND

not used

CAN_H

CAN_SHLD Shield

٥

0

Bus line (low)

Bus line (high)

Signal zero data line

Pass-through connection (1)

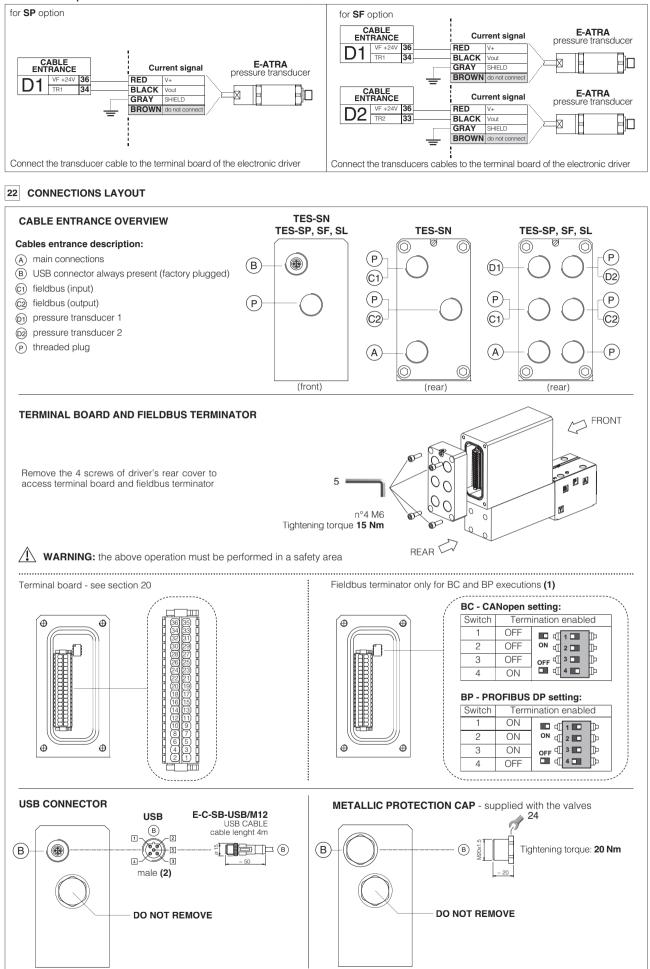
TECHNICAL SPECIFICATIONS

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

21.6 Remote pressure transducer connector - only for SP, SF, SL

CABLE	PIN SIGNAL		TECHNICAL SPECIFICATIONS	NOTES	SP, SL - Single	transducer (1)	SF - Double transducers (1)		
ENTRANCES	FIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	Voltage	Current	Voltage	Current	
	33	TR2	2nd signal transducer ±10 Vbc / ±20 mA maximum range	Input - analog signal Software selectable	/	/	Connect	Connect	
וט	34	TR1	1st ignal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect	Connect	Connect	
ר2	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/	Connect	/	
	36	VF +24V	Power supply +24VDC	Output - power supply	Connect	Connect	Connect	Connect	

E-ATRA remote pressure transducer connection - see tech table GX800



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

22.1 Cable glands and threaded plug for TES-SN - see tech table KX800 $\,$

Communication interfaces		be ordere gland		ed plug	Cable entrance overview	Notes
Interfaces				entrance	Overview	
NP	1	A	none	none		Cable entrance A is open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

22.2 Cable glands and threaded plug for TES-SP, SL - see tech table KX800

Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	2	D1 A	none	none		Cable entrance A, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	3	D1 C1 A	1	C2	00 00 00 00 00 00 00	Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	4	D1 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged

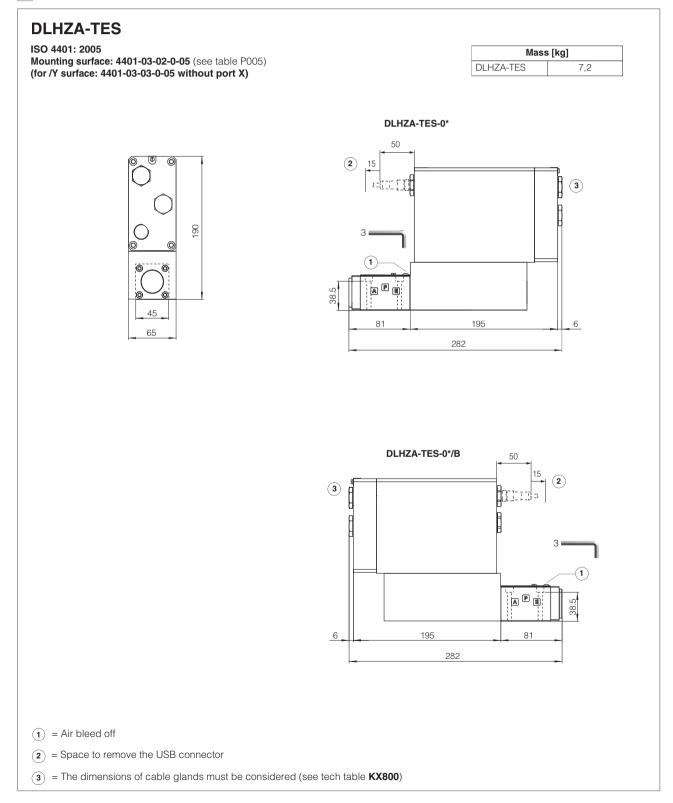
22.3 Cable glands and threaded plug for TES-SF - see tech table KX800

Communication			ed separat	ely	Cable entrance	
interfaces		gland entrance	Thread quantity	ed plug entrance	overview	Notes
NP	3	D1 D2 A	none	none		Cable entrance A, D1, D2 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	4	D1 - D2 C1 A	1	C2	000 000 000 000	Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	5	D1 - D2 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged

23 FASTENING BOLTS AND SEALS

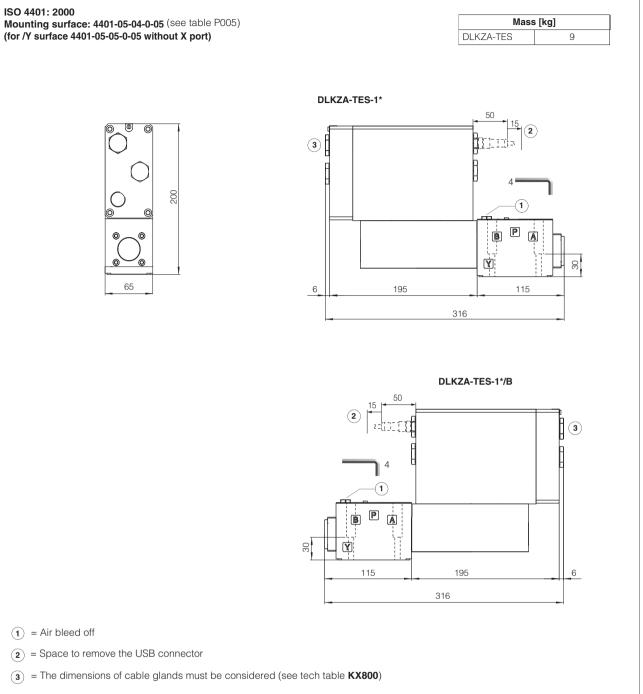
	DLHZA	DLKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø 7,5 mm (max) 1 OR 2025 Diameter of port Y: Ø = 3,2 mm (only for /Y option)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max) 1 OR 108 Diameter of port Y: Ø = 5 mm (only for /Y option)

24 INSTALLATION DIMENSIONS [mm]



DLKZA-TES

ISO 4401: 2000



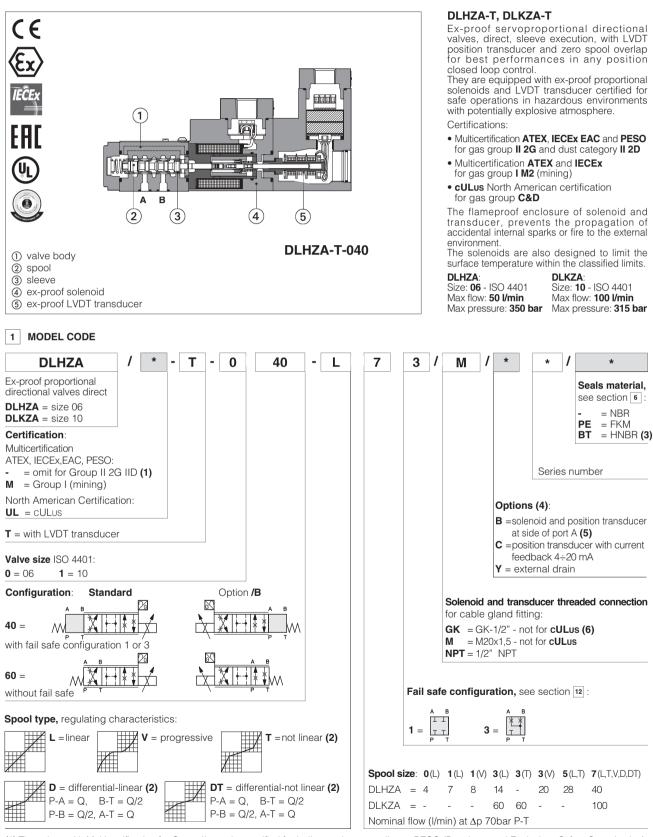
25 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments	GS500	Programming tools
X020	Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO	GS510	Fieldbus
FX500	Ex-proof digital proportionals with P/Q control	GX800	Ex-proof pressure transducer type E-ATRA-7
FX610	Ex-proof servoproportionals with on-board axis card	KX800	Cable glands for ex-proof valves
FX900	Operating and manintenance information for ex-proof proportional valves	P005	Mounting surfaces for electrohydraulic valves

atos°A

Ex-proof servoproportional directional valves sleeve execution

direct, with LVDT transducer and zero spool overlap - ATEX, IECEx, EAC, PESO or cULus



(1) The valves with Multicertification for Group II are also certified for Indian market according to PESO (Petroleum and Explosives Safety Organization)
(2) Only for configuration 40
(3) Not for multicertification M group I (mining)
(4) Possible combined options: /BC, /BY, /CY, /BCY
(5) In standard configuration the solenoid and position transducer are at side of port B
(6) Approved only for the Italian market

2 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-TEB-* /A	E-BM-TES-* /A	Z-BM-TEZ-* /A
Туре	digital	digital	digital
Format		DIN-rail panel	
Data sheet	GS230	GS240	GS330

3 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	150 years, see technical table P007					
Ambient temperature range	Standard = -20° C \div $+70^{\circ}$ C /PE option = -20° C \div $+70^{\circ}$ C /BT option = -40° C \div $+60^{\circ}$ C					
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO9227) > 200h					
Compliance	Explosion proof protection, see section 7 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

4 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		DLHZA						DLKZA				
Pressure limits [bar]			ports P, A, B = 350; T = 210 (250 with external drain /Y)								ports P, A, B = 315; T = 210 (250 with external drain /Y)	
Spool type			L1	V1	L3	V3	L5 T5	L7 T7 V7	D7 DT7	L3 T3		D7 DT7
Max flow [l/m	nin]											
	at $\Delta p = 30$ bar	2,5	4,5	8	9	13	18	26	26÷13	40	60	60÷33
∆p P-T	at Δp = 70 bar	4	7	12	14	20	28	40	40÷20	60	100	100÷50
	max permissible flow	5	9	16	18	26	32	50	50÷28	70	100	100÷50
∆p max P-T	[bar]	120	120	120	120	120	100	100	100	90	70	70
Leakage [cm ³	³ /min] at P = 100 bar (1)	<100	<200	<100	<300	<150	<500 <200	<900 <200 <200	<700 <200	<1000<400	<1500<400<400	<1200 <400
Response time (2) [ms]			≤ 13					≤ 20				
Hysteresis	[% of max regulation]		≤ 0,1					≤ 0,1				
Repeatibility	[% of max regulation]		± 0,1					± 0,1				
Thermal drift							zero point	displacement <	1% at ∆T = 4	10°C		

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 2

(1) Referred to spool in neutral position and 50°C oil temperature (2) 0-100% step signal

5 ELECTRICAL CHARACTERISTICS

Max. power	35W
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved
Duty factor	Continuous rating (ED=100%)
Voltage code	standard
Coil resistance R at 20°C	3,2 Ω
Max. solenoid current	2,5 A

6 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at KTF		
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR HL, HLP, HLPD, HVLP, HVLPD		DIN 51524		
Flame resistant without water		FKM HFDU, HFDR		100 10000		
Flame resistant with water	(1)	NBR, HNBR	NBR, HNBR HFC ISO 12922			

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

7 CERTIFICATION DATA

Valve type	DLHZA	, DLKZA	DLHZA /M , DLKZA /M	DLHZA /UL	DLHZA /UL , DLKZA /UL		
Certifications		ation Group II	Multicertification Group I ATEX IECEx	North American cULus			
Solenoid certified code	OZ	A-T	OZAM-T	OZA	-T/EC		
Type examination certificate (1)	ATEX: CESI 02 ATEX 014 IECEx: IECEx CES 10.0010x EAC: TC RU C-IT. 08.B.01784 PESO: P338131		ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324	- E366100		
Method of protection	ATEX, EAC EX II 2G EX d II EX II 2D EX tb IIIC IECEX EX d IIC T4/T3 EX tb IIIC T85° PESO EX II 2G EX d II	T135°C/T200°C Db Gb C/T200°C Db	ATEX Ex I M2 Ex db I Mb IECEx Ex db I Mb	UL 1203 Class I, Div.I, Groups C & D Class I, Zone I, Groups IIA 8			
Temperature class	T4	Т3	-	T4	T3		
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135 °C	≤ 200 °C		
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C		
Applicable standards	EN 60079-0 EN 60079-1 EN 60079-31		IEC 60079-0 IEC 60079-1 IEC 60079-31	UL 1203 and UL429, CSA 22.2 n°30 CSA 22.2 n°139			
Cable entrance: threaded connection		GK = G M = M2 NPT = 1		1/2"	NPT		

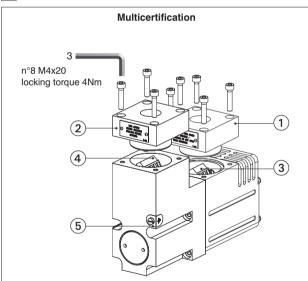
(1) The type examinator certificates can be downloaded from

(2) The solenoids Group II and cULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

8 EX PROOF SOLENOIDS AND LVDT TRANSDUCER WIRING



- solenoid cover with threaded connection for cable gland fitting
- (2) transducer cover with threaded connection for cable gland fitting
- (3) solenoid terminal board for cables wiring
- (4) transducer terminal board for cables wiring
- (5) screw terminal for additional equipotential grounding

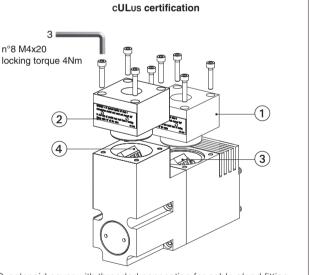
Solenoid wiring

- 1 = Coil PCB 3 poles terminal board 2 = GND
 - suitable for wires cross sections
 - 3 = Coil up to 2,5 mm² (max AWG14)

Position transducer wiring

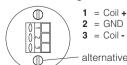
0-0	1	= Output signal
	2	= Supply -15 V
0	3	= Supply +15 V
0 -	Λ	

PCB 4 poles terminal board suitable for wires cross sections up to 2,5 mm² (max AWG14)



- ① solenoid cover with threaded connection for cable gland fitting
- (2) transducer cover with threaded connection for cable gland fitting (3) solenoid terminal board for cables wiring
- (4) transducer terminal board for cables wiring

Solenoid wiring

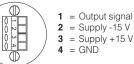


Pay attention to respect the polarity

PCB 3 poles terminal board suggested cable section up to 1,5 mm² (max AWG16), see section **9** note 1 3 = Coil -

alternative GND screw terminal connected to solenoid housing

Position transducer wiring



PCB 4 poles terminal board suggested cable section up to 1,5 mm² (max AWG16), see section **9** note 1

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper Conductors
- Bronze braided armor
- Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C)

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

9.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Multicertification

Max ambient temperature [°C]	Tempera	ture class	Max surface te	mperature [°C]	Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	135 °C	-	90 °C
60 °C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	T3	N.A.	200 °C	N.A.	120 °C

cULus certification

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature
55 °C	T4	135 °C	100 °C
70 °C	Т3	200 °C	100 °C

10 CABLE GLANDS - only Multicertification

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

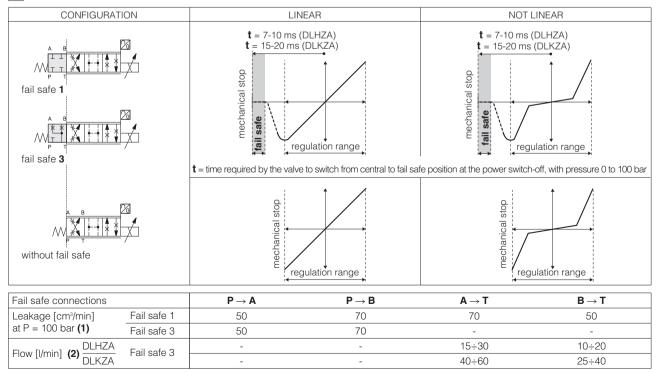
Note: a Loctite sealant type 545, should be used on the cable gland entry threads

11 OPTIONS

- **B** = Solenoid and position transducer at side of port A of the main stage
- C = Position transducer with current feedback 4÷20 mA, suggested in case of long distance between the electronic driver and the proportional valve
- Y = External drain, to be selected if the pressure at T port is higher than the max allowed limits

11.1 Possible combined options: /BC, /BY, /CY, /BCY

12 FAIL SAFE POSITION



(1) Referred to spool in fail safe position and 50°C oil temperature

(2) Referred to spool in fail safe position at $\Delta p = 35$ bar per edge

13 DIAGRAMS - based on mineral oil ISO VG 46 at 50 °C

13.1 Regulation diagrams

1 = Linear spools L

 $\mathbf{2}$ = Differential - linear spool D7

3 = Differential non linear spool DT7**4** = Non linear spool, T5 (only for DLHZA)

 ${\bf 5}$ = Non linear spool, T3 (only for DLKZA) and T7 ${\bf 6}$ = Progressive spool V

T3, T5 and T7 spool types are specific for fine low flow control in the range from 0 to 60% (T5) and 0 to 40% (T3 and T7) of max spool stroke.

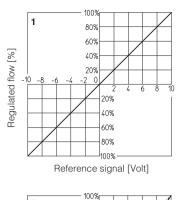
The non linear characteristics of the spool is compensated by the electronic driver, so the final valve regulation is resulting linear respect the reference signal (dotted line).

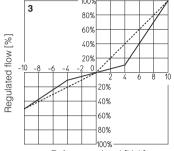
DT7 has the same characteristic of T7 but it is specific for applications with cylinders with area ratio 1:2

Note:

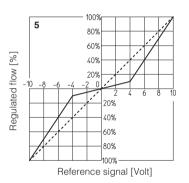
Hydraulic configuration	vs. reference signal:
Standard:	

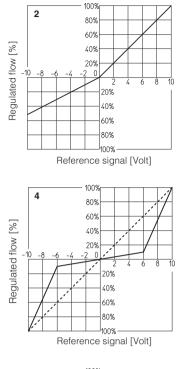
Reference signal	$ \begin{array}{c} 0 \div +10 \text{ V} \\ 12 \div 20 \text{ mA} \end{array} P \rightarrow \text{A} / \text{B} \rightarrow \text{T} $
Reference signal	$ \begin{array}{c} 0 \div -10 \ V \\ 12 \div 4 \ mA \end{array} \Big\} P \longrightarrow B \ / \ A \longrightarrow T $
option /B: Reference signal	$ \begin{array}{c} 0 \div +10 \text{ V} \\ 12 \div 20 \text{ mA} \end{array} \right\} P \rightarrow B / A \rightarrow T $
Reference signal	$ \begin{array}{c} 0 \div -10 \ V \\ 12 \div 4 \ mA \end{array} \Big\} P \rightarrow A \ / \ B \rightarrow T $

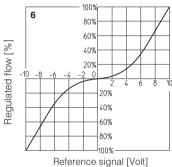




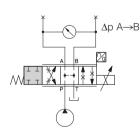


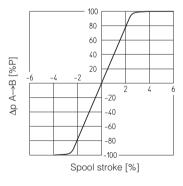






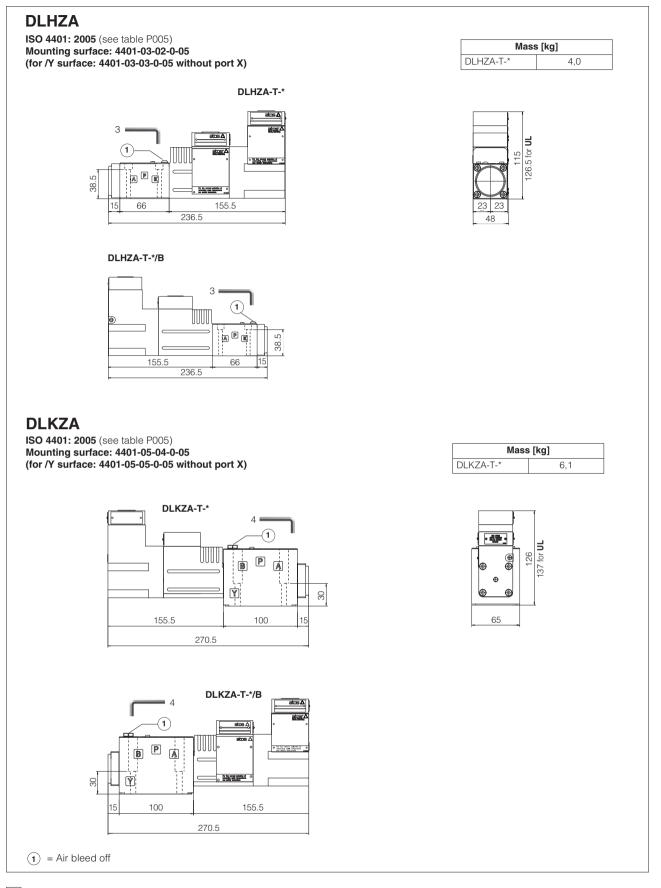
13.2 Pressure gain





14 FASTENING BOLTS AND SEALS

	DLHZA	DLKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø 7,5 mm (max) 1 OR 2025 Diameter of port Y: Ø = 3,2 mm (only for /Y option)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max) 1 OR 108 Diameter of port Y: Ø = 5 mm (only for /Y option)



16 RELATED DOCUMENTATION

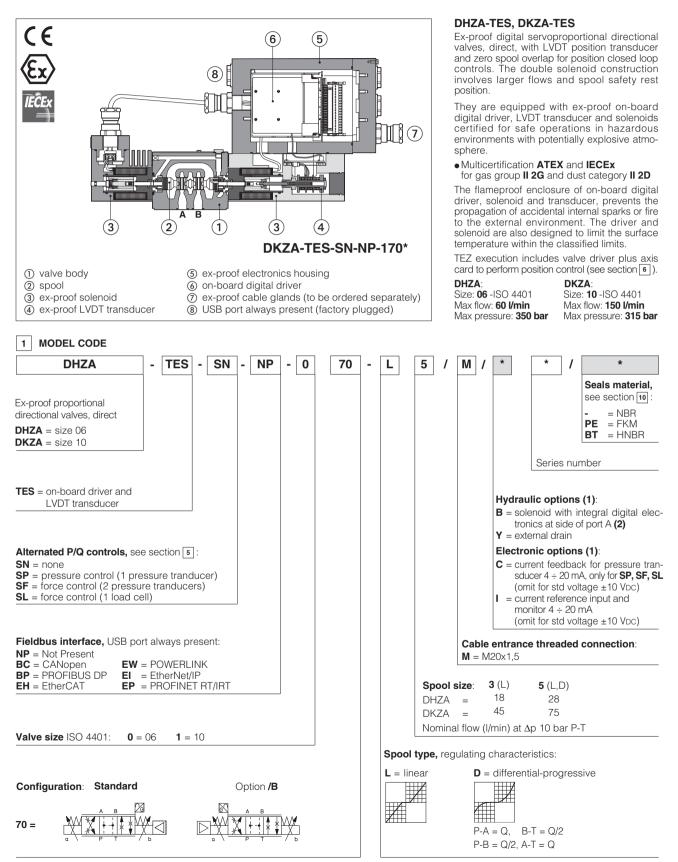
X010Basics for electrohydraulics in hazardous environmentsX020Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESOX030Summary of Atos ex-proof components certified to cULusFX900Operating and manintenance information for ex-proof proportional valvesKX800Cable glands for ex-proof valvesP005Mounting surfaces for electrohydraulic valves

Table FX135-2/E

atos°A

Ex-proof digital servoproportional directional valves

direct, with on-board driver, LVDT transducer and zero spool overlap - ATEX and IECEx



(1) For possible combined options, see section 16

(2) In standard configuration the solenoid with on-board digital driver and position transducer are at side port B

2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

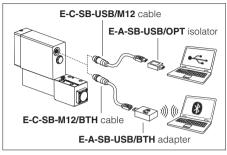


WARNING: the below operation must be performed in a safety area Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)		
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)		
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)		
E-SW-*/PQ	support:	valves with SP, SF,	SL alternated control (e.g. E-SW-BASIC/PQ)		
WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection						





WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 ALTERNATED P/Q CONTROLS - see tech. table FX500

S^{*} options add the closed loop control of pressure (**SP**) or force (**SF** and **SL**) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions. An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers for SF or 1 load cell for SL). The alternated pressure control (SP) is possible only for specific installation conditions.

6 AXIS CONTROLLER - see tech. table FX620

Digital servoproportional with integral electronics **TEZ** include valve's driver plus axis controller, performing position closed loop of any hydraulic actuator equipped with analog, encoder or SSI position transducer. Alternated pressure or force closed loop control can be set by software additionally to the position control.

Atos also supplies complete servoactuators integrating servocylinder, digital servoproportional valve and axis controller, fully assembled and tested. For more information consult Atos Technical Office.

7 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	150 years, see technical table P007				
Ambient temperature range	Standard = -20° C ÷ $+60^{\circ}$ C /PE option = -20° C ÷ $+60^{\circ}$ C /BT option = -40° C ÷ $+60^{\circ}$ C				
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h				
Compliance	Explosion proof protection, see section 11 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006				

8 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve mode	əl		DHZA			DKZA			
Pressure lin	nits [bar]	ports P , A , B = 350; T = 210 (250 with external drain /Y); Y = 10				ports P , A , B = 315; T = 210 (250 with external drain /Y); Y = 10			
Spool type		L3	L5	D5		L3	L5	D5	
Nominal flo	W								
[l/min]	at ∆p= 10 bar	18	28	28		45	75	75	
Δp P-T	at ∆p= 30 bar	30	50	50		80	130	130	
	x permissible flow	40	60	60		90	150	150	
∆p max P-1	۲ [bar]	70	50	50		40	40	40	
Response t	ime [ms] (1)		≤ 18			≤ 25			
Leakage	[cm ³]	<500 (at P :	<500 (at P = 100 bar); <1500 (at P = 350 bar) <800 (at P = 100 bar); <2500 (at P = 315 bar)						
Hysteresis		≤ 0,2 [% of max regulation]							
Repeatabil	ity	± 0,1 [% of max regulation]							
Thermal dri	ift			zero point displ	acement	< 1% at $\Delta T = 40^{\circ}$	C		

(1) 0-100% step signal

9 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal Rectified and filtered	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)						
Max power consumption	35 W							
Analog input signals	Voltage: range ±10 V Current: range ±20 n	/DC (24 VMAX tollerant) nA	Input impedance Input impedance					
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards				
Monitor outputs		oltage ±10 VDC @ ma urrent ±20 mA @ ma	ax 5 mA ax 500 Ω load resistance					
Enable input	Range: 0 ÷ 5 VDC (OFF	state), 9 ÷ 24 VDC (ON	state), 5 ÷ 9 VDC (not acc	epted); Input impedance: $Ri > 10 k\Omega$				
Fault output		VDC (ON state > [powe age not allowed (e.g. du		ate < 1 V) @ max 50 mA;				
Pressure transducer power supply	+24VDC @ max 100 r	mA (E-ATRA-7 see tech	table GX800)					
Alarms	Solenoid not connecte	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, valve spool transducer malfunctions						
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland						
Duty factor	Continuous rating (ED	=100%)						
Tropicalization	Tropical coating on el							
Additional characteristics		Short circuit protection of solenoid current supply; spool position control (SN) or pressure/force control (SP, SF, SL) by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply						
Electromagnetic compatibility (EMC)	According to Directive	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)						
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP,PROFINET IO RT / IRT EC 61158				
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX				

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

10 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	l temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷100 mm²/s - max allowed r	ange 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at KTF		
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM HFDU, HFDR		100 10000		
Flame resistant with water	(1)	NBR, HNBR	HFC	ISO 12922		

A The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

11 CERTIFICATION DATA

Valve type		DHZA, DKZA					
Certifications				Multicertifica	tion Group II		
				ATEX	IECEx		
Solenoid certified co	ode	OZA-TES					
Type examination c	ertificate (1)	ATEX: TUV IT 18 ATEX 068 X IECEx: IECEx TPS 19.0004X					
Method of protection		ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C Db			5°C Db		
	Single solenoid valve	Т6	-	T	5	T4	-
Temperature class	Double solenoid valve	-	T4	-		-	Т3
Surface temperature	9	≤ 85 °C	≤ 135 °C	≤ 100) °C	≤ 135 °C	≤ 200 °C
Ambient temperature (2)		-40 ÷ +40 °C		-40 ÷ +55 °C		-40 ÷ +70 °C	
Applicable Standards		EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079-31 EN 60079-1 IEC 60079-1					1
Cable entrance: three	eaded connection			$\mathbf{M} = \mathbf{M}$	20x1,5		

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code. WARNING:

A service work performed on the valve by the end users or not qualified personnel invalidates the certification.

12 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm ²	Grou
--	------

unding: section of external ground wire = 4 mm²

12.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

13 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

14 HYDRAULIC OPTIONS

- B = Solenoid, integral electronics and position transducer at side of port A of the main stage. For hydraulic configuration vs reference signal, see 17.1
- Y = Option /Y is mandatory if the pressure in port T exceeds 210 bar

15 ELECTRONIC OPTIONS

 I = It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

C = Only for SP, SF, SL

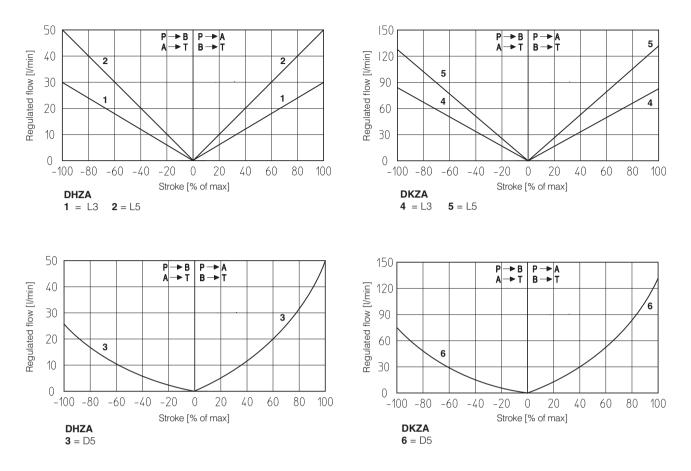
Option /C is available to connect pressure (force) transducers with 4 ÷ 20 mA current output signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

16 POSSIBLE COMBINED OPTIONS

For SN: /BI, /BY, /IY

For SP, SF, SL: /BI, /BY, /IY, /CI, /BCI, CIY, BCIY

17.1 Regulation diagrams (values measure at Δp 30 bar P-T)



Note:

Hydraulic configuration vs. reference signal for configurations 71 and 73 (standard and option /B)

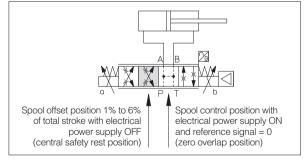
 $\begin{array}{l} \text{Reference signal} \begin{array}{c} 0 & \div & +10 \ \text{V} \\ 12 & \div & 20 \ \text{mA} \end{array} \right\} P \rightarrow A \ / \ B \rightarrow T \qquad \text{Reference signal} \begin{array}{c} 0 & \div & -10 \ \text{V} \\ 12 & \div & 4 \ \text{mA} \end{array} \right\} P \rightarrow B \ / \ A \rightarrow T$

17.2 Spool safety rest position

In absence of electric power supply (+24 VDC), the valve spool is moved by the springs force to the **safety rest position** characterized by a small offset of about 1% to 6% of the total stroke in P-B / A-T configuration.

This is specifically designed to avoid that in case of accidental interruption of the electrical power supply to the valve, the actuator moves towards an undefined direction (due to the tolerances of the zero overlap spool), with potential risk of damages or personnel injury.

Thanks to the **safety rest position** the actuator movement is suddenly stopped and it is recovered at very low speed towards the direction corresponding to the P-B/ A-T connection.



18 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

18.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

18.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the dia-

Ine separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

18.3 Flow reference input signal (Q_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDC.

18.4 Pressure or force reference input signal (F_INPUT+) - only SP, SF, SL

Functionality of F_INPUT+ signal (pin 12), is used as reference for the driver pressure/force closed loop (see tech. table FX500). Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range 0 $\div 24$ VDC.

18.5 Flow monitor output signal (Q_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA.

19.6 Pressure or force monitor output signal (F_MONITOR) - only for SP, SF, SL

The driver generates an analog output signal proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

18.7 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

18.8 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

18.9 Remote pressure/force transducer input signal - only for SP, SF, SL

Analog remote pressure transducers or load cell can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see table FX500).

19 TERMINAL BOARD OVERVIEW

EH, EW, EI, EP	BP (2) LINE_A - LINE_B - DGND - +5V - SHIELD -	BC (2) not used CAN_H CAN_GND CAN_SHLD CAN_SHLD CAN_L	(1) VF +24V (1) TR1 NC NC NC NC NC NC NC (1) F_INPUT+ O_INPUT+ INPUT- ENABLE VL+ VL+	<u>+++++++++++++++++++++++++++++++++++++</u>	LETTEL NORMANE	AGND (1) TR2 (3) EARTH NC NC NC NC NC NC NC AGND F_MONITOR (1) Q_MONITOR AGND FAULT VL0 VC	BC (2) CAN_H not used CAN_GND CAN_SHLD CAN_L	BP (2) - LINE_B - LINE_A - DGND - +5V - SHIELD	EH, EW, EI, EP RX+ RX- TX+ NC
			VL+ V+	_[] [4]		VL0 V0			

(1) connections available only SP, SF, SL

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

(3) connection available only SF

20 ELECTRONIC CONNECTIONS

20.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 VDC	Gnd - power supply
	2	V+	Power supply 24 VDc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
•	7	AGND	Analog ground	Gnd - analog signal
A	8	INPUT-	Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
	9	Q_MONITOR	Flow monitor output signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND Defaults are: ± 10 Vpc for standard and 4 $\div 20$ mA for /l option	Output - analog signal Software selectable
	10	Q_INPUT+	Flow reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	11	F_MONITOR	Pressure/Force monitor output signal: ± 10 Vbc / ± 20 mA maximum range, referred to AGND (1) Defaults are: ± 10 Vbc for standard and 4 $\div 20$ mA for /I option	Output - analog signal Software selectable
	12	F_INPUT+	Pressure/Force reference input signal: ±10 Vpc / ±20 mA maximum range (1) Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

Driver view

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(female)

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(1) Available only for SP, SF, SL

20.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	1	+5V_USB	Power supply
	2	ID	Identification
B	3	GND_USB	Signal zero data line
	4	D-	Data line -
	5	D+	Data line +

20.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
C1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

20.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

20.5 EH, EW, EI, EP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	CAN_L	Bus line (low)
	15	CAN_SHLD	Shield
C2	17	CAN_GND	Signal zero data line
	19	not used	Pass-through connection (1)
	21	CAN_H	Bus line (high)

(B)

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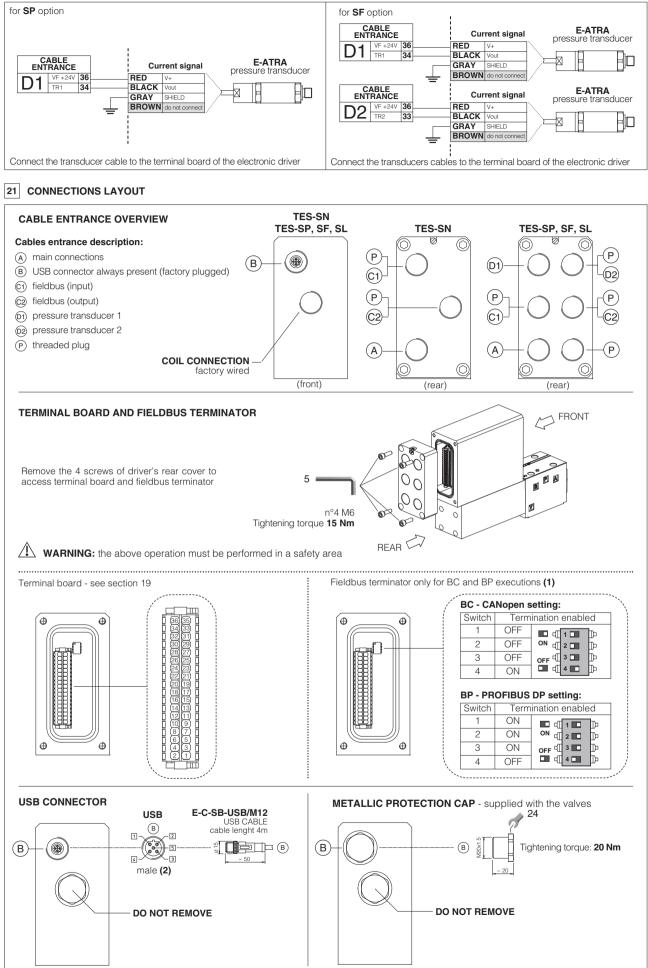
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	TX-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

20.6 Remote pressure transducer connector - only for SP, SF, SL

CABLE ENTRANCES	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	SP, SL - Single Voltage	transducer (1) Current	SF - Double transducers (1) Voltage Current				
	33	TR2	2nd signal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	/	/	Connect	Connect			
וט	34	TR1	1st ignal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect	Connect	Connect			
D2	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/	Connect	/			
	36	VF +24V	Power supply +24VDC	Output - power supply	Connect	Connect	Connect	Connect			

E-ATRA remote pressure transducer connection - see tech table GX800



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

21.1 Cable glands and threaded plug for TES-SN - see tech table KX800

Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	1	A	none	none		Cable entrance A is open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

21.2 Cable glands and threaded plug for TES-SP, SL - see tech table KX800

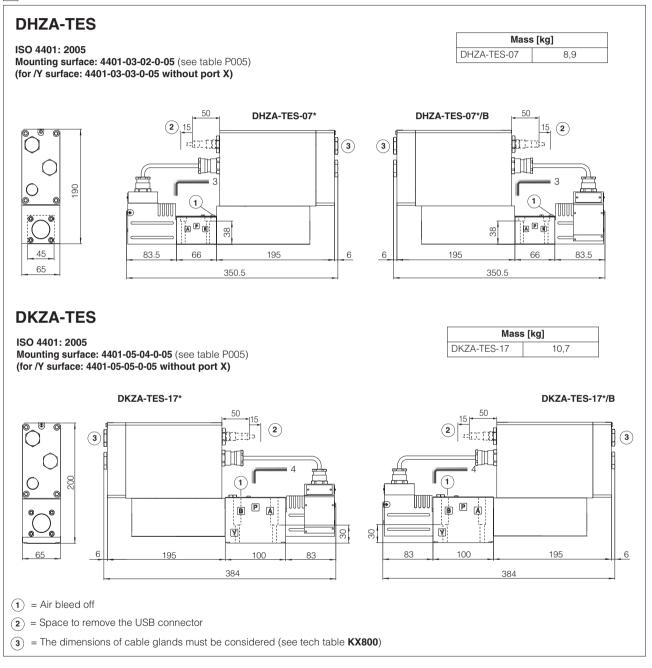
Communication		be ordere		,	Cable entrance	Notes
interfaces		gland entrance		ed plug entrance	overview	NOLES
NP	2	D1 A	none	none		Cable entrance A, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	3	D1 C1 A	1	C2		Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	4	D1 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged

21.3 Cable glands and threaded plug for TES-SF - see tech table KX800

Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	3	D1 D2 A	none	none		Cable entrance A, D1, D2 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	4	D1 - D2 C1 A	1	C2	000 000 000 000	Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	5	D1 - D2 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged

	DHZA	DKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
\bigcirc	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø7,5 mm (max)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max)
	1 OR 2025 Diameter of port Y: $\emptyset = 3,2$ mm (only for /Y option)	1 OR 108 Diameter of port Y: $\emptyset = 5$ mm (only for /Y option)

23 INSTALLATION DIMENSIONS [mm]



24 RELATED DOCUMENTATION

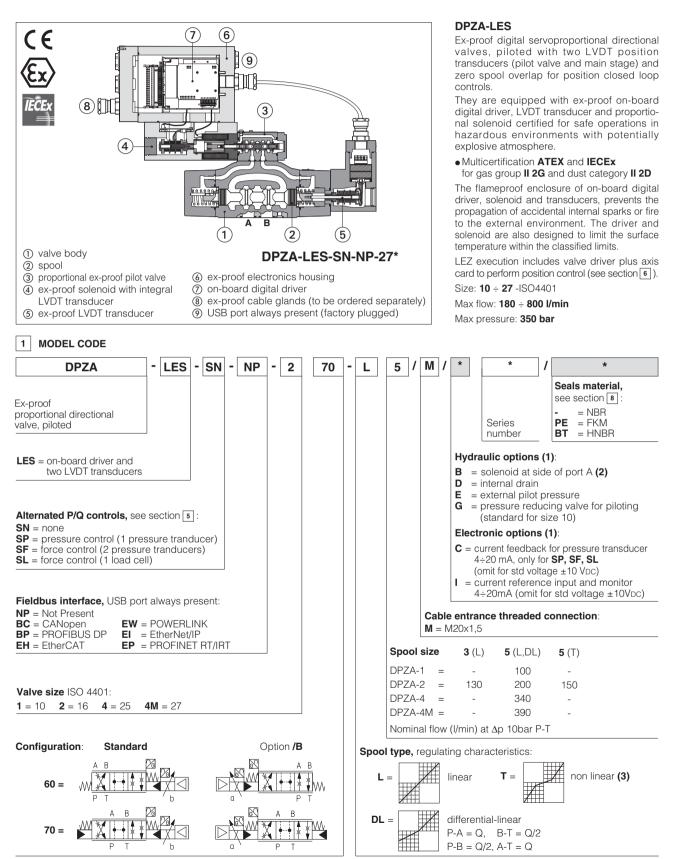
X010	Basics for electrohydraulics in hazardous environments	GS500	Programming tools
X020	Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO	GS510	Fieldbus
FX500	Ex-proof digital proportionals with P/Q control	GX800	Ex-proof pressure transducer type E-ATRA-7
FX620	Ex-proof servoproportionals with on-board axis c	KX800	Cable glands for ex-proof valves
FX900	Operating and manintenance information for ex-proof proportional valves	P005	Mounting surfaces for electrohydraulic valves

Table **FX235-2/E**

atos

Ex-proof digital servoproportional directional valves

piloted, with on-board driver, two LVDT transducers and zero spool overlap - ATEX and IECEx



(1) For possible combined options, see section 16

(2) In standard configuration the solenoid with on-board digital driver and position transducer are at side A of main stage (side B of pilot valve) (3) only for configuration 70

2 GENERAL NOTES

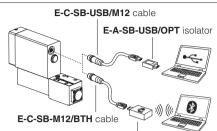
Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

3 VALVE SETTINGS AND PROGRAMMING TOOLS

WARNING: the below operation must be performed in a safety area Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)		
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)		
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)		
E-SW-*/PQ	support:	valves with SP, SF,	SL alternated control (e	e.g. E-SW-BASIC/PQ)		
WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection						



USB or Bluetooth connection

E-A-SB-USB/BTH adapter

V WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 ALTERNATED P/Q CONTROLS - see tech. table FX500

S^{*} options add the closed loop control of pressure (**SP**) or force (**SF** and **SL**) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions. An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers

An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers for SF or 1 load cell for SL). The alternated pressure control (SP) is possible only for specific installation conditions.

6 AXIS CONTROLLER - see tech. table FX630

Digital servoproportional with integral electronics LEZ include valve's driver plus axis controller, performing position closed loop of any hydraulic actuator equipped with analog, encoder or SSI position transducer. Alternated pressure or force closed loop control can be set by software additionally to the position control.

Atos also supplies complete servoactuators integrating servocylinder, digital servoproportional valve and axis controller, fully assembled and tested. For more information consult Atos Technical Office.

7 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	75 years, see technical table P007				
Ambient temperature range	Standard = -20° C ÷ $+60^{\circ}$ C /PE option = -20° C ÷ $+60^{\circ}$ C /BT option = -40° C ÷ $+60^{\circ}$ C				
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h				
Compliance	Explosion proof protection, see section 11 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006				

8 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		DPZA-*-1		DPZA-*-2		DPZA-*-4	DPZA-*-4M
Pressure limits	[bar]	ports P, A, B, X = 350; T = 250 (10 for option /D); Y = 10;					
Spool type		L5, DL5	L3	L5, DL5	T5	L5,	DL5
Nominal flow [I/min]							
	Δp = 10 bar	100	130	200	150	340	390
∆р Р-Т	$\Delta p = 30 \text{ bar}$	160	220	350	260	590	670
	Max permissible flow	180	320	440	360	680	800
Δp max P-T	[bar]	50	60	60	60	60	60
Piloting pressure	[bar]	min. = 25; max = 350 (option /G advisable for pilot pressure > 200 bar)					
Piloting volume	[cm ³]	1,4		3,7		9,0	11,3
Piloting flow (1)	[l/min]	1,7		3,7		6,8	8
Leakage	Pilot [cm³/min]	100/300		150/450		200/600	200/600
(2)	Main stage [l/min]	0,4/1,2		0,6/2,5		1,0/4,0	1,0/4,0
Response time (1)	[ms]	≤ 30		≤ 30		≤ 35	≤ 40
Hysteresis		≤ 0,1 [% of max regulation]					
Repeatability		± 0,1 [% of max regulation]					
Thermal drift			zero	point displace	ement < 1% a	$t \Delta T = 40^{\circ}C$	

(1) 0 $\div100$ % step signal and pilot pressure 100 bar

(2) at P = 100/350 bar

9 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)					
Max power consumption	35 W					
Analog input signals	Voltage: range ± 10 VDc (24 VMAX tollerant)Input impedance:Ri > 50 k Ω Current: range ± 20 mAInput impedance:Ri = 500 Ω					
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account				
Monitor outputs		bltage ±10 VDC @ ma urrent ±20 mA @ ma	ax 5 mA ax 500 Ω load resistance			
Enable input	Range: 0 ÷ 5 VDC (OFF	state), 9 ÷ 24 VDC (ON	state), 5 ÷ 9 VDC (not acc	epted); Input impedance: $Ri > 10 k\Omega$		
Fault output	Output range: 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)					
Pressure transducer power supply	+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)					
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, valve spool transducer malfunctions					
Protection degree to DIN EN60529	IP66/67 with relevant cable gland					
Duty factor	Continuous rating (ED=100%)					
Tropicalization	Tropical coating on electronics PCB					
Additional characteristics	Short circuit protection of solenoid current supply; spool position control (SN) or pressure/force control (SP, SF, SL) P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply					
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)					
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158		
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX		

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

10 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS	638 class 7	see also filter section at KTF		
contamination level	longer life	ISO4406 class 16/14/11 NAS	638 class 5	catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water (1)		NBR, HNBR	HFC	130 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

11 CERTIFICATION DATA

Valve type	DPZA				
Certifications	Multicertification Group II				
	ATEX IECEx				
Solenoid certified code		OZA	-LES		
Type examination certificate (1)	ATEX: TUV IT 18 ATEX 068 X IECEx: IECEx TPS 19.0004X				
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db IECEx Ex db IIC T6/T5/T4 Gb Ex tb IIIC T85°C/T100°C/T135°C Db				
Temperature class	T6	T5		T4	
Surface temperature	≤ 85 °C	≤ 100	°C	≤ 135 °C	
Ambient temperature (2)	-40 ÷ +40 °C -40 ÷ +55 °C		55 °C	-40 ÷ +70 °C	
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079-31 EN 60079-1 IEC 60079-1 IEC 60079-1				
Cable entrance: threaded connection	M = M20x1,5				

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

12 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

12.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

13 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

14 HYDRAULIC OPTIONS

B = Solenoid, integral electronics and position transducer at side of port B of the main stage.

D and **E** = Pilot and drain configuration can be modified as shown in section $\boxed{21}$.

- The valve's standard configuration provides internal pilot and external drain. For different pilot / drain configuration select:
 - Option /D Internal drain.
 - Option /E External pilot (through port X).

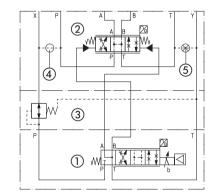
G = Pressure reducing valve installed between pilot valve and main body with fixed setting:

- DPZA-2 = 28 bar
- DPZA-1, -4 and -4M = 40 bar

It is advisable for valves with internal pilot in case of system pressure higher than 150 bar.

Pressure reducing valve is standard for DPZA-1, for other sizes add /G option.

FUNCTIONAL SCHEME - example of configuration 70



Pilot valve

- Main stage
- ③ Pressure reducing valve
- ④ Plug to be added for external pilot trough port X
- ⑤ Plug to be removed for internal drain through port T

15 ELECTRONIC OPTIONS

I = It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 VDC.

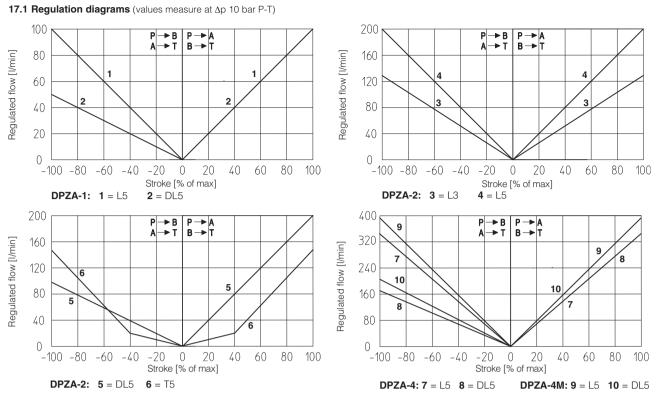
Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

C = Only for SP, SF, SL

Option /C is available to connect pressure (force) transducers with 4 ÷ 20 mA current output signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

16 POSSIBLE COMBINED OPTIONS

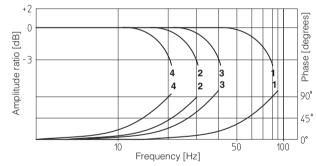
Hydraulic options: all combination possible Electronics options: /Cl (only for SP, SF, SL) **17 DIAGRAMS** (based on mineral oil ISO VG 46 at 50 °C)



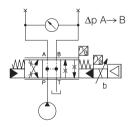
Note: Hydraulic configuration vs. reference signal for configurations 60 and 70 (standard and option /B) $\begin{array}{c} 0 \div +10 \ V \\ \text{Reference signal } 12 \div 20 \ \text{mA} \end{array} \Big\} \ P \rightarrow \text{A} \ / \ \text{B} \rightarrow \text{T} \qquad \text{Reference signal } \begin{array}{c} 0 \div -10 \ V \\ 4 \div 12 \ \text{mA} \end{array} \Big\} \ P \rightarrow \text{B} \ / \ \text{A} \rightarrow \text{T} \end{array}$

17.2 Bode diagrams

Stated at nominal hydraulic conditions.



17 2	Pressure	anin
17.0	riessuie	ualli



± 100% + 5% DPZA-2 DPZA-2 DPZA-4 DPZA-4 DPZA-4M ± 5% ± 100% DP7A-4M

DPZA-1

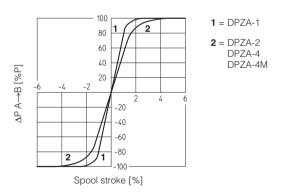
DPZA-1

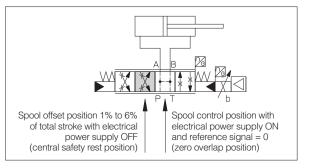
17.4 Safety rest position - configuration 70

In absence of electric power supply (+24 VDC), the valve main spool is moved by the springs force to the central safety rest position characterized by a small offset of about 1% to 6% of the total stroke in P-B / A-T configuration. This is specifically designed to avoid that in case of accidental interruption of the electrical power supply to the valve, the actuator moves towards an undefined direction (due to the tolerances of the zero overlap spool), with potential risk of damages or personnel injury.

Thanks to the central safety rest position the actuator movement is suddenly stopped and it is recovered at very low speed towards the direction corresponding to the P-B/ A-T connection.

The main spool moves to the closed loop control position (zero overlap) when the pilot pressure is activated, the valve is fed with power supply +24 VDC and reference input = 0V (or 12 mA for option /I) is applied to the driver.





18 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

18.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

18.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

18.3 Flow reference input signal (Q_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDc.

18.4 Pressure or force reference input signal (F_INPUT+) - only SP, SF, SL

Functionality of F_INPUT+ signal (pin 12), is used as reference for the driver pressure/force closed loop (see tech. table FX500). Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDc.

18.5 Flow monitor output signal (Q_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA.

18.6 Pressure or force monitor output signal (F_MONITOR) - only for SP, SF, SL

The driver generates an analog output signal proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

18.7 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

18.8 Fault output signal (FAULT)

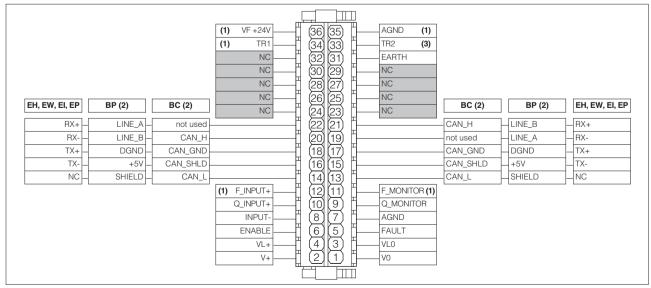
Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

18.9 Remote pressure/force transducer input signal - only for SP, SF, SL

Analog remote pressure transducers or load cell can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see table FX500).

19 TERMINAL BOARD OVERVIEW



(1) connections available only SP, SF, SL

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

(3) connection available only SF

20 ELECTRONIC CONNECTIONS

20.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 VDC	Input - power supply
	3	VL0	Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver, referred to VL0	Input - on/off signal
•	7	AGND	Analog ground	Gnd - analog signal
A	8	INPUT-	Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
	9	Q_MONITOR	Flow monitor output signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND Defaults are: ± 10 Vpc for standard and 4 $\div 20$ mA for /l option	Output - analog signal Software selectable
	10	Q_INPUT+	Flow reference input signal: ±10 Vbc / ±20 mA maximum range Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /l option	Input - analog signal Software selectable
	11	F_MONITOR	Pressure/Force monitor output signal: ± 10 Vbc / ± 20 mA maximum range, referred to AGND (1) Defaults are: ± 10 Vbc for standard and 4 $\div 20$ mA for /I option	Output - analog signal Software selectable
	12	F_INPUT+	Pressure/Force reference input signal: ±10 Vpc / ±20 mA maximum range (1) Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

Driver view

¹

G

(female)

CABLE ENTRANCE

ے ر

6

2

З

PIN

13

15

17

19

21

1

4

(1) Available only for SP, SF, SL

20.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	1	+5V_USB	Power supply
	2	ID	Identification
B	3	GND_USB	Signal zero data line
	4	D-	Data line -
	5	D+	Data line +

20.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
()1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

20.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

20.5 EH, EW, EI, EP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

(B)

SIGNAL

CAN L

CAN_SHLD

CAN_GND

not used

CAN_H

۲

 \bigcirc

Bus line (low)

Bus line (high)

Signal zero data line

Pass-through connection (1)

Shield

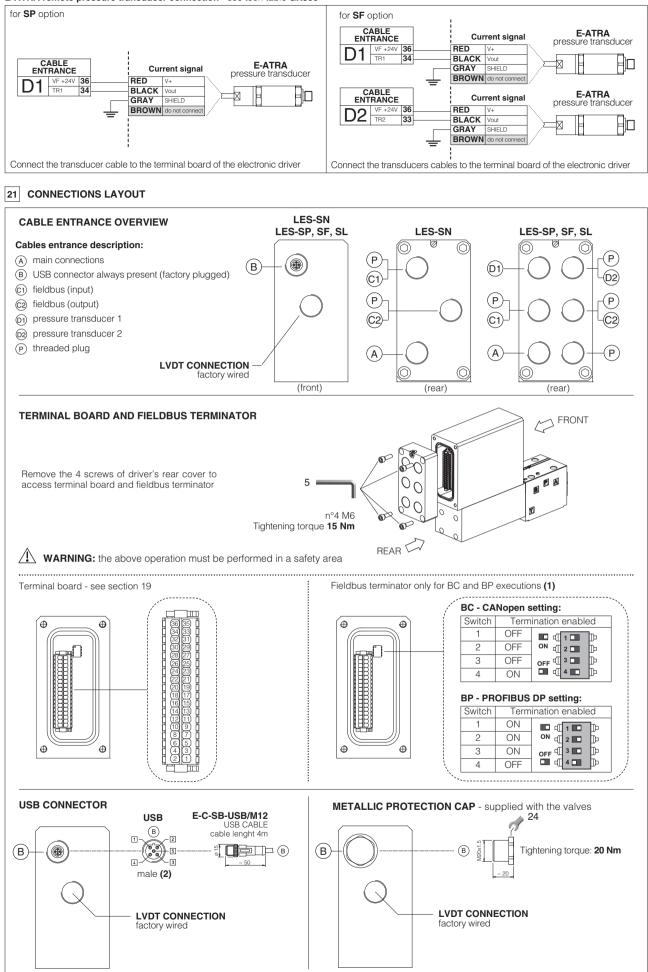
TECHNICAL SPECIFICATIONS

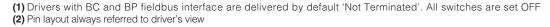
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	TX-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

20.6 Remote pressure transducer connector - only for SP, SF, SL

CABLE ENTRANCES	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	SP, SL - Single Voltage	transducer (1) Current	SF - Double transducers (1) Voltage Current		
	33	TR2	2nd signal transducer ±10 Vbc / ±20 mA maximum range	Input - analog signal Software selectable	/	/	Connect	Connect	
	34	TR1	1st ignal transducer ±10 Vbc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect	Connect	Connect	
D2	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/	Connect	/	
	36	VF +24V	Power supply +24Vbc	Output - power supply	Connect	Connect	Connect	Connect	

E-ATRA remote pressure transducer connection - see tech table GX800





21.1 Cable glands and threaded plug for LES-SN - see tech table KX800 $\,$

_						
Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance	Thread quantity	ed plug entrance	overview	Notes
NP	1	A	none	none		Cable entrance A is open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

21.2 Cable glands and threaded plug for LES-SP, SL - see tech table KX800

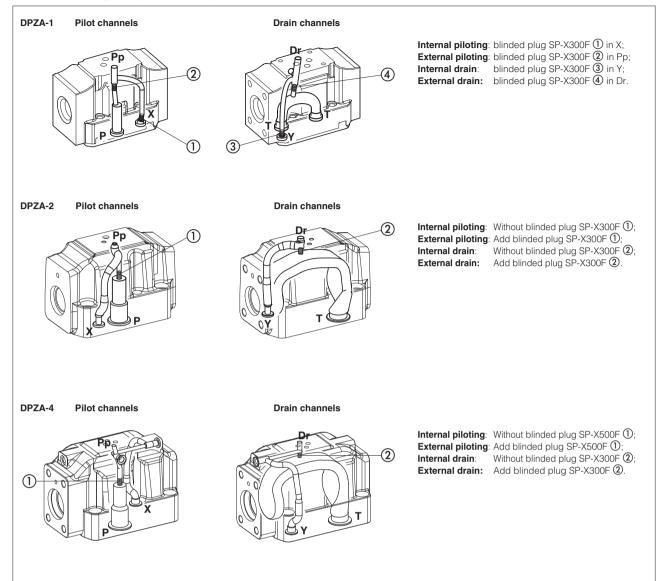
Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	2	D1 A	none	none		Cable entrance A, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	3	D1 C1 A	1	C2	00 00 00 00 00 00	Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	4	D1 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged

21.3 Cable glands and threaded plug for LES-SF - see tech table KX800

Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance	Thread quantity	ed plug entrance	overview	Notes
NP	3	D1 D2 A	none	none		Cable entrance A, D1, D2 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	4	D1 - D2 C1 A	1	C2	000 000 000 000	Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	5	D1 - D2 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged

22 PLUGS LOCATION FOR PILOT/DRAIN CHANNELS

Depending on the position of internal plugs, different pilot/drain configurations can be obtained as shown below. To modify the pilot/drain configuration, proper plugs must only be interchanged. The plugs have to be sealed using loctite 270. Standard valves configuration provides internal pilot and external drain

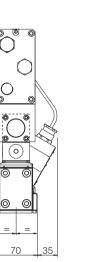


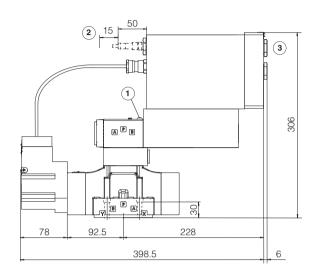
23 FASTENING BOLTS AND SEALS

Туре	Size	Fastening bolts	Seals		
	1 = 10	4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm	5 OR 2050; Diameter of ports A, B, P, T: Ø 11 mm (max) 2 OR 108 Diameter of ports X, Y: Ø = 5 mm (max)		
	2 = 16 ZA 4 = 25	4 socket head screws M10x50 class 12.9 Tightening torque = 70 Nm	4 OR 130; Diameter of ports A, B, P, T: Ø 20 mm (max)		
DPZA		2 socket head screws M6x45 class 12.9 Tightening torque = 15 Nm	2 OR 2043 Diameter of ports X, Y: Ø = 7 mm (max)		
DFZA		6 socket head screws M12x60 class 12.9	4 OR 4112; Diameter of ports A, B, P, T: Ø 24 mm (max)		
		Tightening torque = 125 Nm	2 OR 3056 Diameter of ports X, Y: $\emptyset = 7 \text{ mm} (\text{max})$		
	4M = 27	6 socket head screws M12x60 class 12.9	4 OR 3137; Diameter of ports A, B, P, T: Ø 32 mm (max)		
		Tightening torque = 125 Nm	2 OR 3056 Diameter of ports X, Y: $\emptyset = 7 \text{ mm} (\text{max})$		

DPZA-LES-*-1

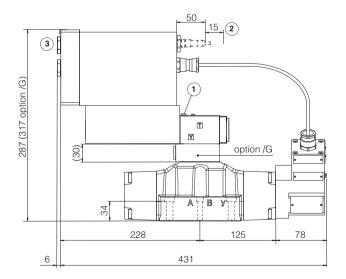
ISO 4401: 2005 Mounting surface: 4401-05-05-0-05 (see table P005)





DPZA-LES-*-2

ISO 4401: 2005 Mounting surface: 4401-07-07-0-05 (see table P005)



Mass [kg]					
DPZA-*-27*	17,9				
Option /G	+0,9				

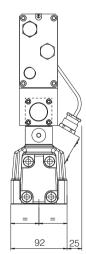
Mass [kg]

13,7

+0,9

DPZA-*-17*

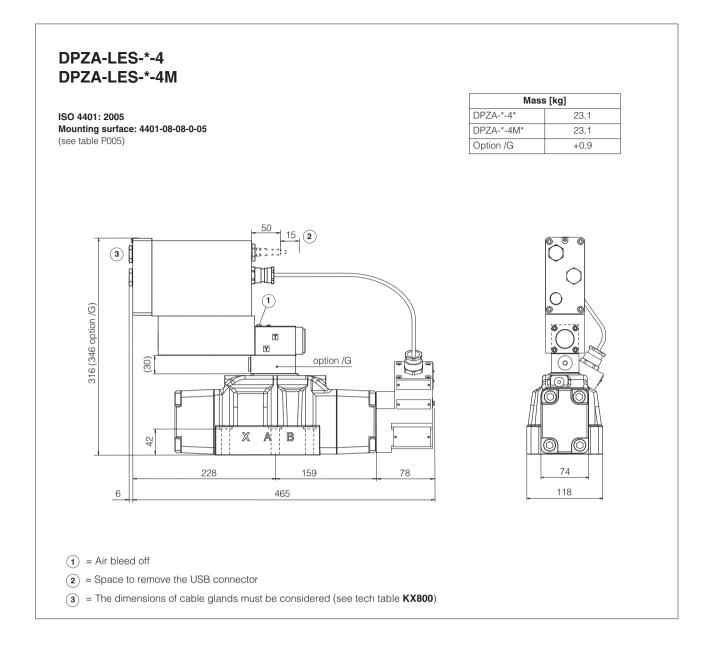
Option /G



(1) = Air bleed off

 $(\mathbf{2})$ = Space to remove the USB connector

(3) = The dimensions of cable glands must be considered (see tech table **KX800**)



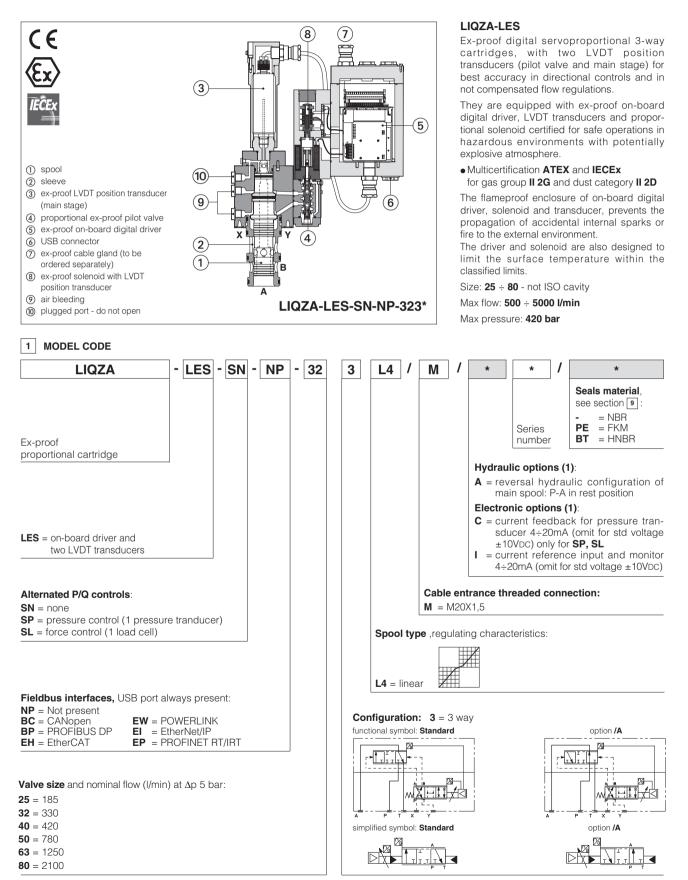
25 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments	GS500	Programming tools
X020	Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO	GS510	Fieldbus
FX500	Ex-proof digital proportionals with P/Q control	GX800	Ex-proof pressure transducer type E-ATRA-7
FX630	Ex-proof servoproportionals with on-board axis card	KX800	Cable glands for ex-proof valves
FX900	Operating and manintenance information for ex-proof proportional valves	P005	Mounting surfaces for electrohydraulic valves

atos

Ex-proof digital servoproportional 3-way cartridges

piloted, with on-board driver and two LVDT transducers - ATEX and IECEx



(1) For possible combined options, see section 15

2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

3 VALVE SETTINGS AND PROGRAMMING TOOLS

WARNING: the below operation must be performed in a safety area

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

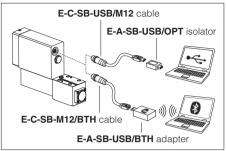
 The software is available in different versions according to the driver's options (see table GS500):

 E-SW-BASIC
 support: NP (USB)
 PS (Serial)
 IR (Infrared)

 E-SW-FIELDBUS
 support: BC (CANopen)
 BP (PROFIBUS DP)
 EH (EtherCAT)

E-SW-FIELDBUS support:		BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)	
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)	
E-SW-*/PQ	support:	valves with SP, SF,	SL alternated control (e	e.g. E-SW-BASIC/PQ)	

USB or Bluetooth connection



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: Bluetooth adapter is available only for European, USA and Canadian markets!

Bluetooth adapter is certified according RED (Europe), FCC (USA) and ISED (Canada) directives

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These execution allow to operate the valves through fieldbus or analog signals available on the main connector.

5 ALTERNATED P/Q CONTROLS - see tech. table FX500

S^{*} options add the closed loop control of pressure (**SP**) or force (**SL**) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions. An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP or 1 load cell for SL).

An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP or 1 load cell for SL). The alternated pressure control (SP) is possible only for specific installation conditions.

6 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	75 years, see technical table P007				
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$				
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Surface protection	Zinc coating with black passivation - salt spay test (EN ISO 9227) > 200 h				
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006				

7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

		25	32	40	50	63	80
Max regulated flow [I/min]							
∆p P-A or A-T	at $\Delta p = 5$ bar	185	330	420	780	1250	2100
•	at $\Delta p = 10$ bar	260	470	590	1100	1750	3000
Max permissible flow	W	500	850	1050	2000	3100	5000
Max pressure [bar]		Ports	P, A, T = 420	X = 350	$Y \le 10$	
Nominal flow of pilot	valve at $\Delta p = 70$ bar [l/min]	4	8	28	40	100	100
Leakage of pilot val	ve at P = 100 bar [l/min]	0,2	0,2	0,5	0,7	0,7	0,7
Piloting pressure	[bar]	min: 40% of system pressure max 350 recommended 140 ÷ 160					
Piloting volume	[cm ³]	2,16	7,2	8,9	17,7	33,8	42,7
Piloting flow (1)	[l/min]	6,5	20	25	43	68	76
Response time (2)	[ms]	≤ 25	≤ 27	≤ 27	≤ 30	≤ 35	≤ 40
Hysteresis	[% of the max regulation]	≤ 0,1					
Repeatability	[% of the max regulation]	± 0,1					
Thermal drift			zero p	oint displaceme	ent < 1% at ∆T =	= 40°C	

(1) 0÷100% step signal

(2) With pilot pressure = 140 bar

The loss of the pilot pressure causes the undefined position of the main spool.

The sudden interruption of the power supply during the valve operation causes the immediate main spool opening $A \rightarrow T$ or $P \rightarrow A$ (for option /A). This could cause pressure surges in the hydraulic system or high decelerations which may lead to machine damages.

8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)						
Max power consumption	35 W	35 W					
Analog input signals		/oltage: range ± 10 VDC (24 VMAX tollerant)Input impedance:Ri > 50 k\OmegaCurrent: range ± 20 mAInput impedance:Ri = 500 \Omega					
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards			
Monitor outputs		oltage ±10 VDC @ ma urrent ±20 mA @ ma	ax 5 mA ax 500 Ω load resistance				
Enable input	Range: 0 ÷ 5 VDC (OFF	state), 9 ÷ 24 VDC (ON	state), 5 ÷ 9 VDC (not acc	epted); Input impedance: $Ri > 10 k\Omega$			
Fault output	Output range: 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)						
Pressure/force transducer power supply (only for SP, SL)	+24VDC @ max 100 r	+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)					
Alarms	Solenoid not connecte valve spool transduce		preak with current refere	nce signal, over/under temperature,			
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland					
Duty factor	Continuous rating (ED	=100%)					
Tropicalization	Tropical coating on ele	ectronics PCB					
Additional characteristics	Short circuit protection of solenoid current supply; spool position control (SN) or pressure/force control (SP, SL) by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply						
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)						
Communication interface	USB Atos ASCII coding	SB CANopen PROFIBUS DP EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT					
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX			

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	l temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷100 mm²/s - max allowed ra	20 ÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without wa	ater	FKM HFDU, HFDR		- ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	1 100 12922		

A The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

10 CERTIFICATION DATA

Components type	Pilot v	LVDT main stage transducer				
Certifications		Multicertification ATEX IECEx				
Components Certified code		OZA-LES		ETHA-15		
	•	ATEX: TUV IT 18 ATEX 06	8 X	• ATEX: TUV IT 16 ATEX 053 X		
Type examination certificate (1)	•	• IECEX: IECEX TPS 16.0003X				
Method of protection		• ATEX Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C				
Temperature class	Т6	T5	T4	T6		
Surface temperature	≤ 85 °C	≤ 100 °C	≤ 135 °C	≤ 85 °C		
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +40 °C -40 ÷ +55 °C -40 ÷ +70 °C		-40 ÷ +70 °C		
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 EN 60079-1 IEC 60079-1			IEC 60079-31		
Cable entrance: threaded connection		M = M20×1,5				

(1) The type examinator certificates can be downloaded from

(2) The driver solenoid and LVDT transducers are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	Т6	85 °C	80 °C
55 °C	Τ5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table KX800

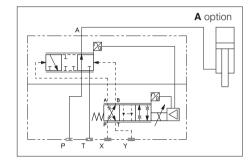
Note: a Loctite sealant type 545, should be used on the cable gland entry threads

13 HYDRAULIC OPTIONS

A = The standard valve version provides the hydraulic configuration A-T of main spool in absence of electric power supply to the valve.

The option /A provides the reverse configuration P-A of main spool in absence of electric power supply to the valve.

This execution is particularly requested in vertical presses for safety reasons, because in case of electric power breakdown the P-A configuration of the main spool prevents the uncontrolled and dangerous downstroke of the press ram.



14 ELECTRONICS OPTIONS

This option provides 4 ÷ 20 mA current reference and monitor signals, instead of the standard 0 ÷ 10 VDC.
 Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.
 It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

C = Only for SP, SL

This option is available to connect pressure (force) transducers with 4 ÷ 20 mA current output signal, instead of the standard ±10 VDc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ±20 mA.

15 POSSIBLE COMBINED OPTIONS

For SN: /Al For SP, SL: /AC, Al, /Cl, /ACl

16 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

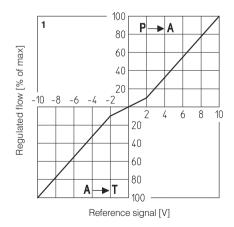
16.1 Regulation diagrams, see note

1 = LIQZA (all sizes)

Hydraulic configuration vs. reference signal:

 $\begin{array}{c} \text{standard option /A}\\ \text{Reference signal } 0 \div +10 \text{ V}\\ 12 \div 20 \text{ mA} \end{array} \} \text{P} \rightarrow \text{A} \qquad \text{A} \rightarrow \text{T} \end{array}$

Reference signal $0 \div 10 V$ $4\div 12 \text{ mA}$ $A \rightarrow T$ $P \rightarrow A$



17 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

17.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

17.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the

diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

17.3 Flow reference input signal (Q_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDC.

17.4 Pressure or force reference input signal (F_INPUT+) - only SP, SL

Functionality of F_INPUT+ signal (pin 12), is used as reference for the driver pressure/force closed loop (see tech. table FX500). Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range 0 $\div 24$ VDC.

18.5 Flow monitor output signal (Q_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA.

17.6 Pressure or force monitor output signal (F_MONITOR) - only for SP, SL

The driver generates an analog output signal proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

17.7 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

17.8 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

17.9 Remote pressure/force transducer input signal - only for SP, SL

Analog remote pressure transducers or load cell can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see table FX500).

18 TERMINAL BOARD OVERVIEW

EH, EW, EI, EP BP (2) BC (2) RX+ LINE_A not used RX- LINE_B CAN_H TX+ DGND CAN_GND TX- +5V CAN_SHLD NC SHIELD CAN_L	-	AGND (1) NC EARTH NC NC NC NC NC C MC AGND FAULT VL0	BC (2) - CAN_H - not used - CAN_GND - CAN_SHLD - CAN_L	BP (2)	EH, EW, EI, EP RX+ RX- TX+ TX- NC
RX+ LINE_A not used RX- LINE_B CAN_H TX+ DGND CAN_GND TX- +5V CAN_SHLD	NC NC NC NC NC Image: State of the s	EARTH NC NC NC NC NC F_MONITOR (1) Q_MONITOR AGND FAULT	- CAN_H - not used - CAN_GND - CAN_SHLD	LINE_B LINE_A DGND +5V	

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

19 ELECTRONIC CONNECTIONS

19.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	VO Power supply 0 Vbc	
	2	V+	Power supply 24 VDc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
•	7	AGND	Analog ground	Gnd - analog signal
A	8	INPUT-	Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
	9	Q_MONITOR	Flow monitor output signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND Defaults are: ± 10 Vpc for standard and 4 \div 20 mA for /l option	Output - analog signal Software selectable
	10	Q_INPUT+	Flow reference input signal: ±10 Vbc / ±20 mA maximum range Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	11	F_MONITOR	Pressure/Force monitor output signal: ± 10 Vbc / ± 20 mA maximum range, referred to AGND (1) Defaults are: ± 10 Vbc for standard and 4 $\div 20$ mA for /I option	Output - analog signal Software selectable
	12	2 F_INPUT+ Pressure/Force reference input signal: ±10 Vbc / ±20 mA maximum range (1) Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /I option		Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

Driver view

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(female)

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(1) Available only for SP, SL

19.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	1	+5V_USB	Power supply
	2	ID	Identification
B	3	GND_USB	Signal zero data line
	4	D-	Data line -
	5	D+	Data line +

19.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
()1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

19.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

19.5 EH, EW, EI, EP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	CAN_L	Bus line (low)
	15	CAN_SHLD	Shield
C2	17	CAN_GND	Signal zero data line
	19	not used	Pass-through connection (1)
	21	CAN_H	Bus line (high)

(B)

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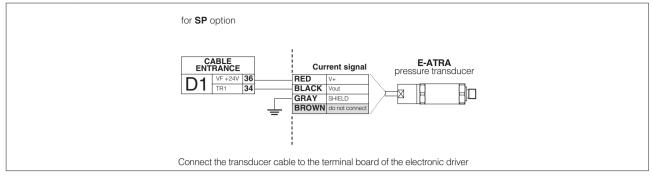
0

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

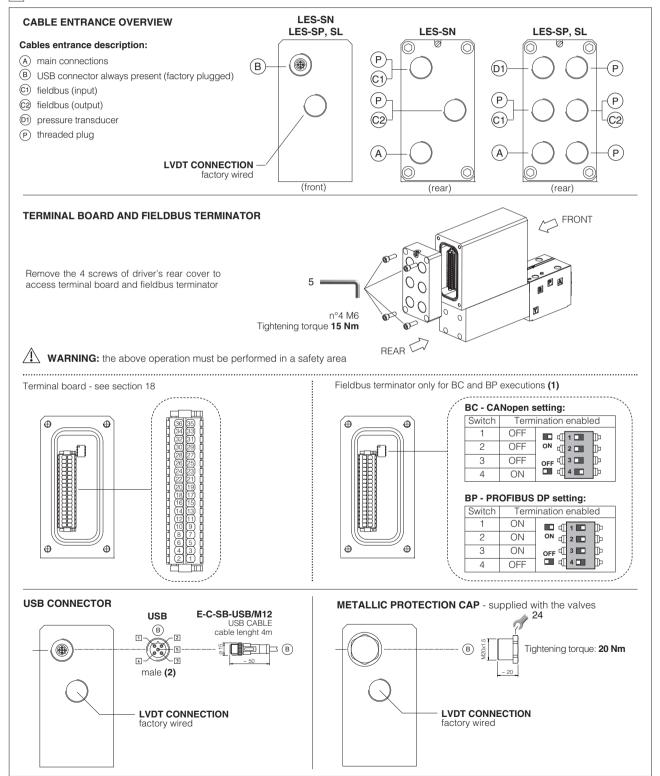
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

19.6 Remote pressure transducer connector - only for SP, SL

CABLE ENTRANCES	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	SP, SL - Single Voltage	transducer (1) Current	SF - Double tr Voltage	ansducers (1) Current		
	34	TR1	1st ignal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect	Connect	Connect		
D1	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/	Connect	/		
	36	VF +24V	Power supply +24Vbc	Output - power supply	Connect	Connect	Connect	Connect		



20 CONNECTIONS LAYOUT



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

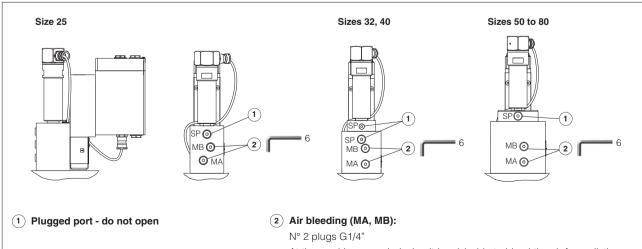
20.1 Cable glands and threaded plug for LES-SN - see tech table KX800

Communication			ed separat		Cable entrance	Notes
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	1	A	none	none		Cable entrance A is open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

20.2 Cable glands and threaded plug for LES-SP, SL $\,$ - see tech table KX800 $\,$

Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance	Thread quantity	ed plug entrance	overview	Notes
NP	2	D1 A	none	none		Cable entrance A, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	3	D1 C1 A	1	C2	00 00 00 00 00 00	Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	4	D1 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged

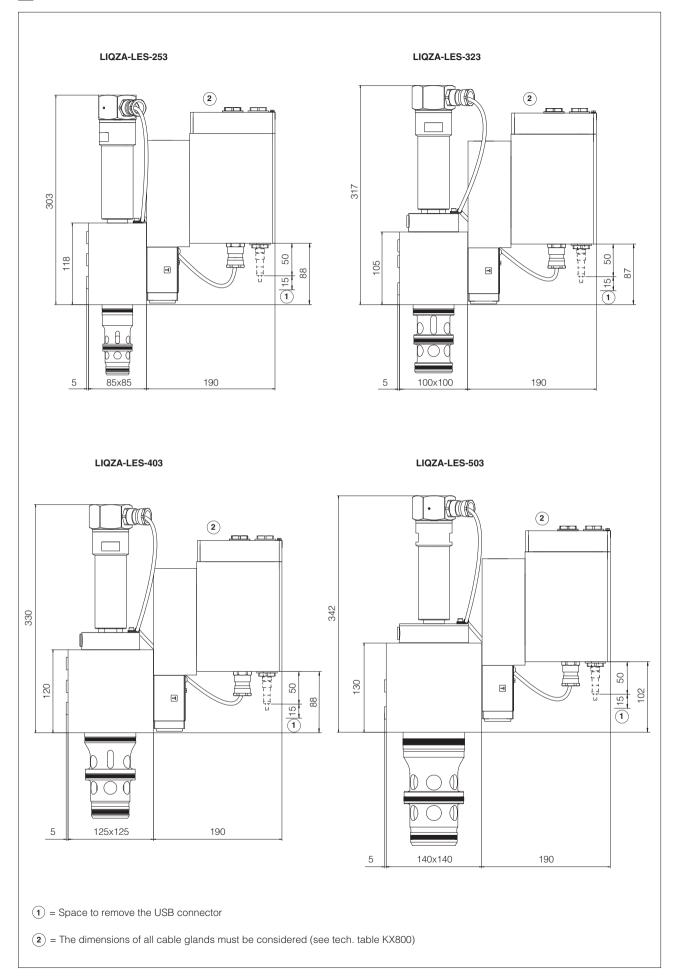
21 AIR BLEEDING

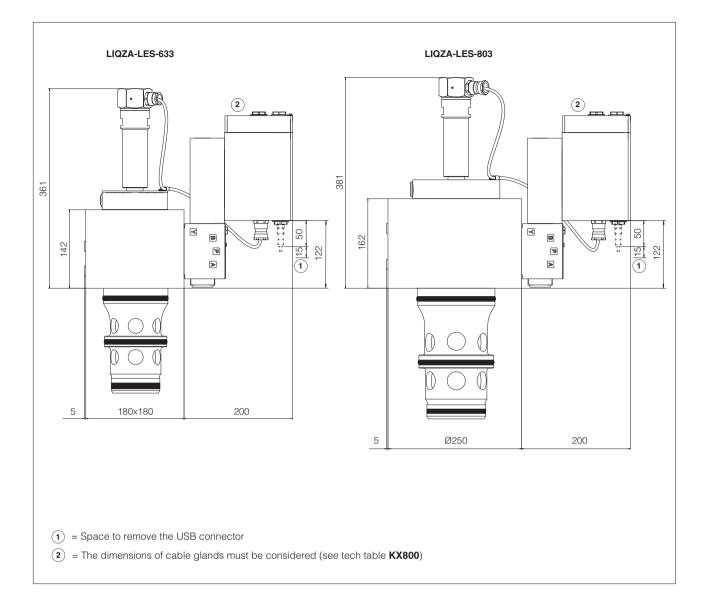


At the machine commissioning it is advisable to bleed the air from piloting chambers, by loosening the 2 plugs shown in the picture.

Operate the valve for few seconds at low pressure and then lock the plugs.

22 INSTALLATION DIMENSIONS [mm]





23 FASTENING BOLTS AND VALVE MASS

Туре	Size	Fastening bolts (1) supplied with the valve	Mass [kg]
	25	4 socket head screws M12x100 class 12.9 Tightening torque = 125 Nm	15,8
	32	4 socket head screws M16x60 class 12.9 Tightening torque = 300 Nm	18,2
LIQZA	40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	23,7
LIGZA	50	4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	31,6
	63	4 socket head screws M30x120 class 12.9 Tightening torque = 2100 Nm	51,6
	80	8 socket head screws M24x80 class 12.9 Tightening torque = 1000 Nm	79,2

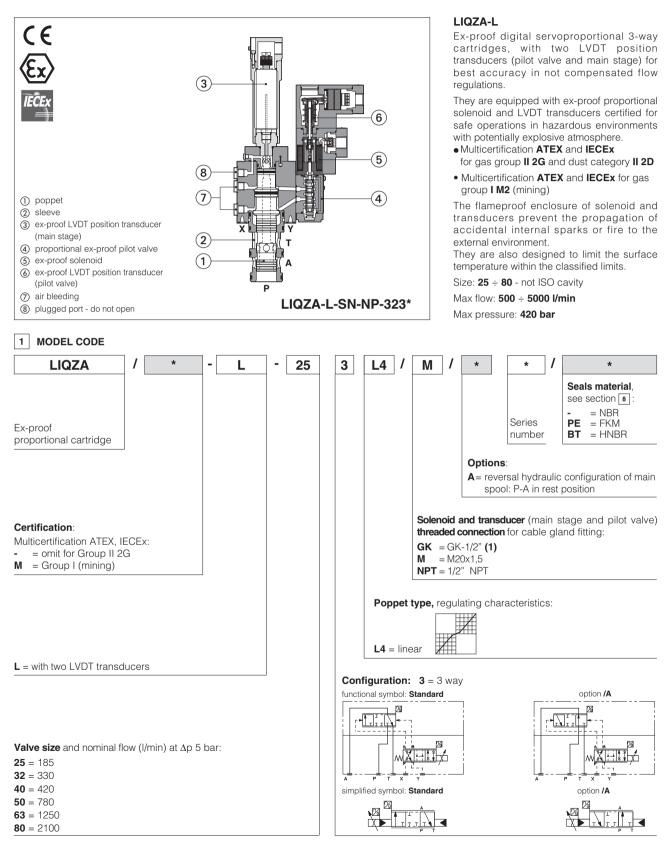
24 RELATED DOCUMENTATION

X010 X020 FX500 FX900	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO Ex-proof digital proportionals with P/Q control Operating and manintenance information for ex-proof proportional valves	GS500 GS510 GX800 KX800 P006	Programming tools Fieldbus Ex-proof pressure transducer type E-ATRA-7 Cable glands for ex-proof valves Mounting surfaces and cavities for cartridge valves
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atos

Ex-proof servoproportional 3-way cartridges

piloted, with two LVDT transducers - ATEX and IECEx



(1) Approved only for the italian market

2 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves. Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-LEB-* /A	E-BM-LES-* /A
Туре	digital	digital
Format	DIN-ra	il panel
Data sheet	GS230	GS240

3 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	75 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spay test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t" RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

4 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Size		25	32	40	50	63	80
Max regulated flow [l/min]						
at $\Delta p = 5$ bar	-	185	330	420	780	1250	2100
$\Delta p P-A \text{ or } A-T$ at $\Delta p = 10 \text{ bar}$		260	470	590	1100	1750	3000
Max permissible flow		500	850	1050	2000	3100	5000
Max pressure [bar]			Ports	P, A, T = 420	X = 350	$Y \le 10$	
Nominal flow of pilot value at $\Delta p = 70$ bar [I	/min]	4	8	28	40	100	100
Leakage of pilot valve at P = 100 bar [I/min]		0,2	0,2	0,5	0,7	0,7	0,7
Piloting pressure	[bar]	min:	40% of system	pressure ma	ax 350 recor	nmended 140 ÷	160
Piloting volume	[cm ³]	2,16	7,2	8,9	17,7	33,8	42,7
Piloting flow (1) [I	/min]	6,5	20	25	43	68	76
Response time (2)	[ms]	≤ 25	≤ 27	≤ 27	≤ 30	≤ 35	≤ 40
Hysteresis [% of the max regula	ation]	≤ 0,1					
Repeatability [% of the max regula	ation]	± 0,1					
Thermal drift		zero point displacement < 1% at $\Delta T = 40^{\circ}C$					

(1) 0÷100% step signal

(2) With pilot pressure = 140 bar

5 ELECTRICAL CHARACTERISTICS

Max. power	35W
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account
Protection degree	IP66/67 to DIN EN60529 with relevant cable glandraintight enclosure, UL approved
Duty factor	Continuous rating (ED=100%)
Voltage code	standard
Coil resistance R at 20°C	3,2 Ω
Max. solenoid current	2,5 A

6 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

		NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$				
Seals, recommended fluid temperature		FKM seals (/PE option) = -20° C ÷ $+80^{\circ}$ C				
		HNBR seals (/BT option) = -40° C ÷ $+60^{\circ}$ C, with HFC hydraulic fluids = -40° C ÷ $+50^{\circ}$ C				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	130 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

The loss of the pilot pressure causes the undefined position of the main poppet.

The sudden interruption of the power supply during the valve operation causes the immediate shut-off of the main poppet. This could cause pressure surges in the hydraulic system or high decelerations which may lead to machine damages.

7 CERTIFICATION DATA

Valve type	LIC)ZA	LIQZA /M	LIQZA, LIQZA /M	
Component type	l l	Pilot solenoid and	LVDT transducer	LVDT main stage transducer	
Certifications		ation Group II IECEx	Multicertification Group I ATEX IECEx	Multicertification Group I and II ATEX IECEx	
Solenoid certified code	OZ	A-T	OZAM-T	ETHA-15	
Type examination certificate (1)	ATEX: CESI 02 IECEx: IECEx C		ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	ATEX: TUV IT 16 ATEX 053X ICEX: IECEX TPS 16.0003X	
Method of protection	 ATEX Ex II 2G Ex d IIC T4/T3 Gb Ex II 2D Ex tb IIIC T135°C/T200°C Db IECEX Ex d IIC T4/T3 Gb Ex tb IIIC T85°C/T200°C Db 		ATEX Ex I M2 Ex db I Mb IECEx Ex db I Mb	ATEX Ex II 2G Ex db IIC T6 Gb Ex II 2D Ex tb IIIC T85°C Db Ex I M2 Ex db IMb IECEx Ex db IIC T6 Gb Ex tb IIIC T85°C Db Ex db IMb	
Temperature class	T4	Т3	-	T6	
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 85 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +70 °C (3)	
Applicable standards		EN 60079-0 EN 60079-1 EN 60079-3	P-1 IEC 60079-1		
Cable entrance: threaded connection	GK = GK-1/2" M = M20x1,5 NPT = 1/2" NPT				

(1) The type examinator certificates can be downloaded from

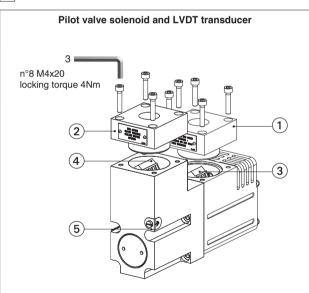
(2) The solenoids Group II are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

(3) For Group I (mining) the temperature range is -20°C \div +70°C

WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

8 EX PROOF SOLENOIDS AND LVDT TRANSDUCER WIRING



- ① solenoid cover with threaded connection for cable gland fitting
- (2) transducer cover with threaded connection for cable gland fitting
- solenoid terminal board for cables wiring
- (4) transducer terminal board for cables wiring
- (5) screw terminal for additional equipotential grounding

Solenoid wiring

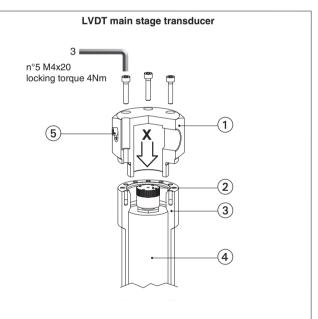
- 1
 = Coil
 PCB 3 poles terminal board

 2
 = GND
 suitable for wires cross sections
 - $\mathbf{3} = \text{Coil}$ up to 2,5 mm² (max AWG14)

Position transducer wiring

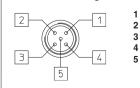
0-0	1	= Output signal
)~□	2	= Supply -15 V
) - 🗆	3	= Supply +15 V
) + []	4	= GND

PCB 4 poles terminal board suitable for wires cross sections up to 2,5 mm² (max AWG14)



- ① transducer cover with threaded connection for cable gland fitting
- (2) transducer terminal board for cables wiring
- ③ ex-proof protection for LVDT transducer
- (4) LVDT transducer
- (5) screw terminal for additional equipotential grounding

Transducer wiring - view from X



1 = Do not connect **2** = Supply +15 V **3** = GND **4** = Output signal **5** = Supply -15 V

9 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

9.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products. Multicertification

Max ambient temperature [°C]	Tempera	ture class	Max surface te	mperature [°C]	Min. cable temperature [°C]		
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II	
40 °C	-	T4	150 °C	135 °C	-	90 °C	
60 °C	-	-	150 °C	-	110 °C	-	
70 °C	N.A.	T3	N.A.	200 °C	N.A.	120 °C	

10 CABLE GLANDS

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table KX800

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

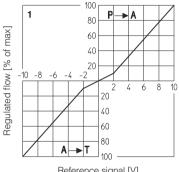
11 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

11.1 Regulation diagrams, see note

1 = LIQZA (all sizes)

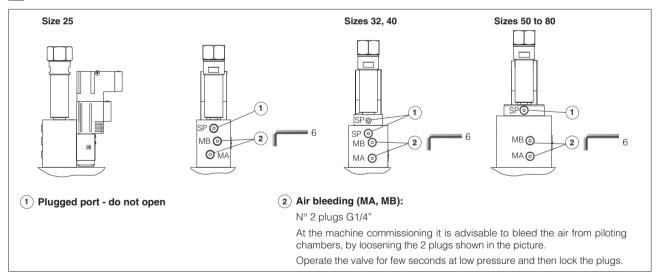
Hydraulic configuration vs. reference signal:

standard option /A Reference signal 0 ÷+10 V $P \rightarrow A$ $A \rightarrow T$ 12÷20 mA Reference signal 0 ÷-10 V 4÷12 mA } А $\rightarrow T$ $P \rightarrow A$



Reference signal [V]

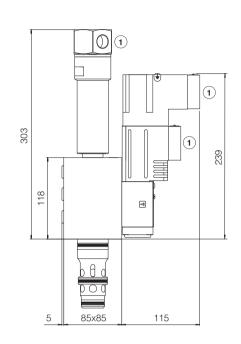
12 AIR BLEEDING

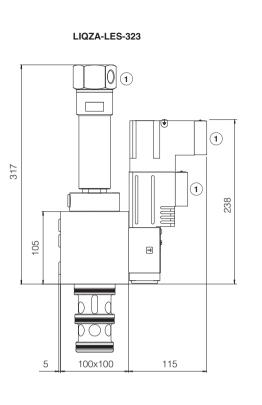


13 FASTENING BOLTS AND VALVE MASS

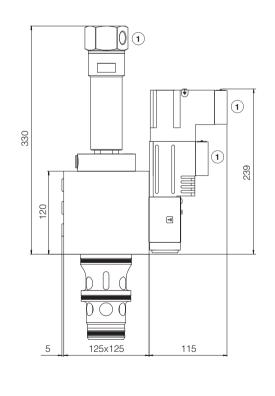
Туре	Size	Fastening bolts (1) supplied with the valve	Mass [kg]
	25	4 socket head screws M12x100 class 12.9 Tightening torque = 125 Nm	15,8
	32	4 socket head screws M16x60 class 12.9 Tightening torque = 300 Nm	18,2
LIQZA	40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	23,7
LIQZA	50 4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm		31,6
	63	4 socket head screws M30x120 class 12.9 Tightening torque = 2100 Nm	51,6
	80	8 socket head screws M24x80 class 12.9 Tightening torque = 1000 Nm	79,2

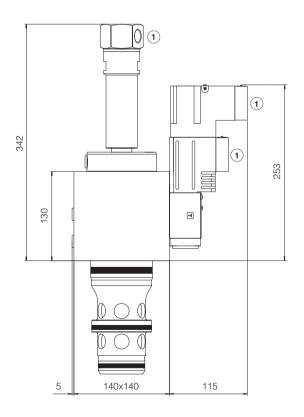
LIQZA-LES-253





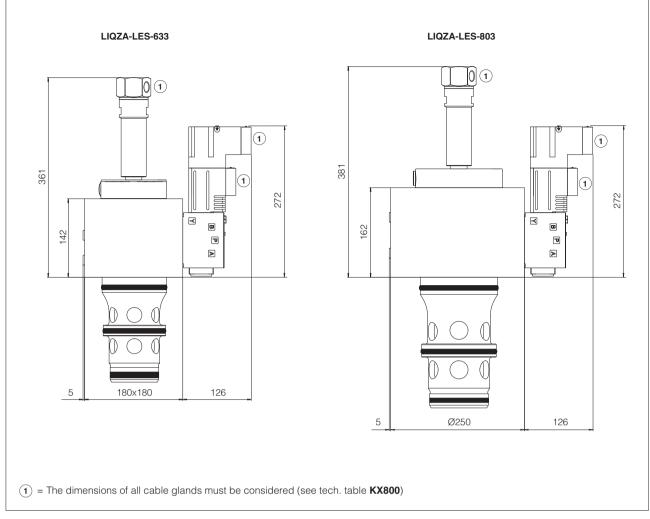
LIQZA-LES-403





LIQZA-LES-503

(1) = The dimensions of all cable glands must be considered (see tech. table **KX800**)



Note: for mounting surface and cavity dimensions, see table P006

15 RELATED DOCUMENTATION

X010 Basics for electrohydraulics in hazardous environments
 X020 Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO
 FX900 Operating and manintenance information for ex-proof proportional valves

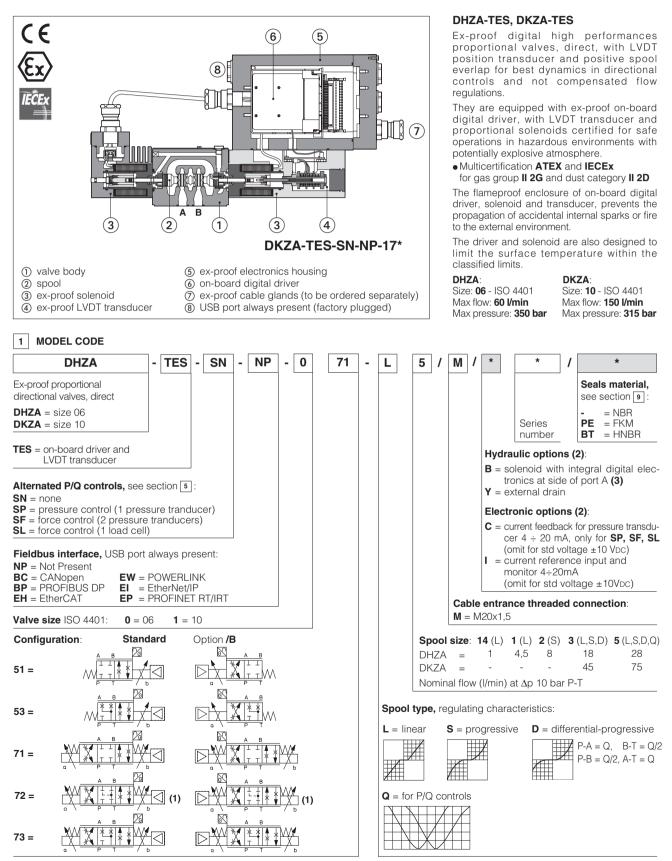
 KX800
 Cable glands for ex-proof valves

 P006
 Mounting surfaces and cavities for cartridge valves

atos

Ex-proof digital proportional directional valves high performance

direct, with on-board driver, LVDT transducer and positive spool overlap - ATEX and IECEx



(1) Only for DKZA-*-S5 the spool overlapping type 2 provides the same characteristic of type 1, but in central position the internal leakages from P to A and B are drained to tank, avoiding the drift of cylinders with differential areas
 (2) For possible combined options, see section 15
 (3) In standard configuration the solenoid with on-board digital driver and position transducer are at side port B

2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

3 VALVE SETTINGS AND PROGRAMMING TOOLS

WARNING: the below operation must be performed in a safety area

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

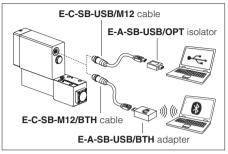
 The software is available in different versions according to the driver's options (see table GS500):

 E-SW-BASIC
 support:
 NP (USB)
 PS (Serial)
 IR (Infrared)

 E-SW-FIELDBUS
 support:
 BC (CANopen)
 BP (PROFIBUS DP)
 EH (EtherCAT)

 E-SW-*/PQ
 support:
 valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)





WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 ALTERNATED P/Q CONTROLS - see tech. table FX500

S^{*} options add the closed loop control of pressure (**SP**) or force (**SF** and **SL**) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions. An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers for SF or 1 load cell for SL). The alternated pressure control (SP) is possible only for specific installation conditions.

6 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	150 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section 11 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model					DHZA			DKZA	
Pressure limits	[bar]	ports P , A , B = 350; T = 210 (250 with external drain /Y) Y = 10						rts P , A , B = 3 with external dra	
Configuration				51,	53, 71, 73		51, 53,	71, 73	72
Spool Type		L14	L1	S2	L3, S3, D3	L5, S5, D5, Q5	L3, S3, D3	L5, S5, D5, Q5	S5
Nominal flow						•			
[l/min]	at ∆p= 10 bar	1	4,5	8	18	28	45	75	75
∆р Р-Т	at ∆p= 30 bar	1,7	8	14	30	50	80	130	130
	max permissible flow	2,6	12	21	40	60	90	150	150
∆p max P-T	[bar]	70	70	70	50	50	40	40	40
Leakage [cm ³ /r	min]	<	30 (at p =	= 100 ba	ar); <135 (at p = 3	50 bar)	<80 (at p = 10	00 bar); <600 (at p = 315 bar)
Response time	e (1) [ms]	≤ 20				≤ 25			
Hysteresis		≤ 0,2 [% of max regulation]							
Repeatibility		± 0,1 [% of max regulation]							
Thermal drift					zero point disp	lacement < 1% a	t $\Delta T = 40^{\circ}C$		

(1) (0-100% step signal)

8 ELECTRICAL CHARACTERISTICS

	N	2.1.1.		1				
Power supplies	1 ton milda	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)						
Max power consumption	35 W							
Analog input signals	Voltage: range ±10 V Current: range ±20 m	DC (24 VMAX tollerant)	Input impedance Input impedance					
Insulation class		curing surface tempera 32 must be taken into a		ils, the European standards				
Monitor outputs		urrent ±10 VDC @ ma	ax 5 mA ix 500 Ω load resistance					
Enable input	Range: 0 ÷ 5 VDC (OFF	state), 9 ÷ 24 VDC (ON	state), 5 ÷ 9 VDC (not acc	epted); Input impedance: $Ri > 10 k\Omega$				
Fault output		VDC (ON state > [powe ge not allowed (e.g. du		ate < 1 V) @ max 50 mA;				
Pressure/force transducer power supply (only for SP, SF, SL)	+24VDC @ max 100 m/	A (E-ATRA-7 see tech t	able GX800)					
Alarms	Solenoid not connecte valve spool transduce		preak with current refere	nce signal, over/under temperature,				
Protection degree to DIN EN60529	IP66/67 with relevant c	able gland						
Duty factor	Continuous rating (ED:	=100%)						
Tropicalization	Tropical coating on ele	ectronics PCB						
Additional characteristics	Short circuit protection of solenoid current supply; spool position control (SN) or pressure/force control (SP, SF, SL) by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply							
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)							
Communication interface		CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158				
Communication physical layer		optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX				

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type		DHZA, DKZA						
Certifications				Multicertifica	tion Group II			
				ATEX	IECEx			
Solenoid certified co	ode			OZA	AES			
Type examination certificate (1)		• ATEX: TUV I	T 18 ATEX 068 X	<	IECEX: IEC	Ex TPS 19.0004X		
Method of protection		ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C Db						
	Single solenoid valve	Т6	-	T	Т5		-	
Temperature class	Double solenoid valve	-	T4	-		-	Т3	
Surface temperature	Э	≤ 85 °C	≤ 135 °C	≤ 100	O°C	≤ 135 °C	≤ 200 °C	
Ambient temperature (2)		-40 ÷ +40 °C		-40 ÷ +55 °C		-40 ÷ +70 °C		
Applicable Standards		EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079-31 EN 60079-1 IEC 60079-1					1	
Cable entrance: thre	eaded connection	M = M20x1,5						

(1) The type examinator certificates can be downloaded from - catalog on line, technical information section

(2) The solenoids Group II are certified for minimum ambient temperature -40°C

WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification.

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]	
40 °C	T6	85 °C	80 °C	
55 °C	T5	100 °C	90 °C	
70 °C	T4	135 °C	110 °C	

12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

13 HYDRAULIC OPTIONS

- B = Solenoid, integral electronics and position transducer at side of port A of the main stage. For hydraulic configuration vs reference signal, see 17.1
- Y = Option /Y is mandatory if the pressure in port T exceeds 210 bar

14 ELECTRONIC OPTIONS

 I = It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

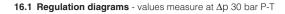
C = Only for **SP**, **SF**, **SL**

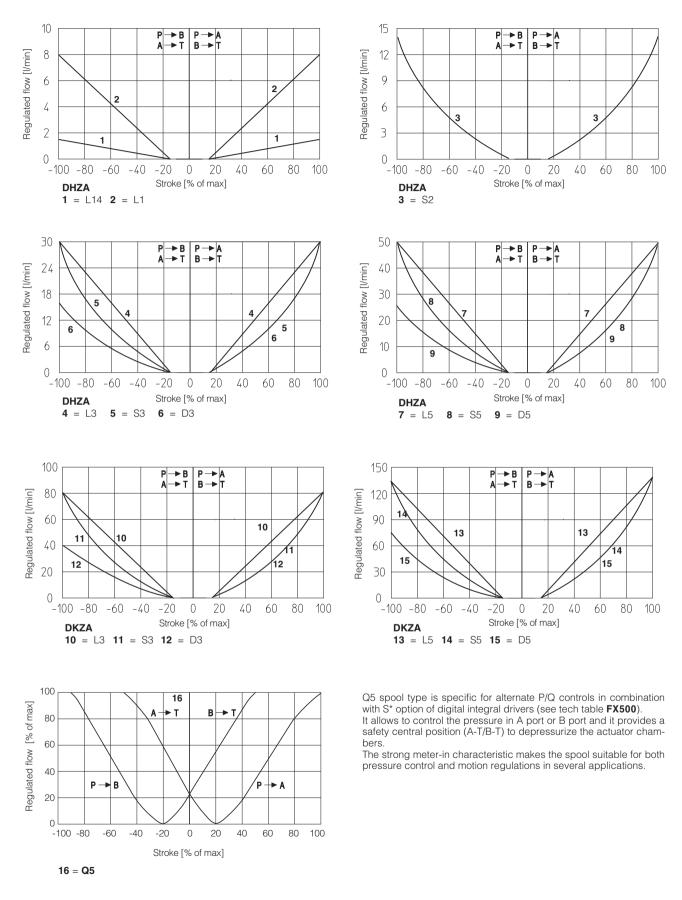
Option /C is available to connect pressure (force) transducers with 4 ÷ 20 mA current output signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

15 POSSIBLE COMBINED OPTIONS

For SN: /BI, /BY, /IY

For SP, SF, SL: /BI, /BY, /IY, /CI, /BCI, CIY, BCIY





Note:

Hydraulic configuration vs. reference signal for configurations 71 and 73 (standard and option /B) Reference signal $\begin{array}{c} 0 & \div & +10 \text{ V} \\ 12 & \div & 20 \text{ mA} \end{array}$ $P \rightarrow A / B \rightarrow T$ Reference signal $\begin{array}{c} 0 & \div & -10 \text{ V} \\ 12 & \div & 4 \text{ mA} \end{array}$ $P \rightarrow B / A \rightarrow T$

17 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and componentshydraulics, EN-982).

17.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 µF/40 V capacitance to single phase rectifiers or a 4700 µF/40 V capacitance to three phase rectifiers.

/]\ A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

17.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μF/40 V capacitance to single phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

∕!∖ A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

17.3 Flow reference input signal (Q_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range 0 ÷ 24VDC.

17.4 Pressure or force reference input signal (F_INPUT+) - only SP, SF, SL

Functionality of F_INPUT+ signal (pin 12), is used as reference for the driver pressure/force closed loop (see tech. table FX500). Reference input signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDC.

17.5 Flow monitor output signal (Q MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

17.6 Pressure or force monitor output signal (F_MONITOR) - only for SP, SF, SL

The driver generates an analog output signal proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

17.7 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition does not comply with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

17.8 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

17.9 Remote pressure/force transducer input signal - only for SP, SF, SL

Analog remote pressure transducers or load cell can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are ±10 VDc for standard and 4 ÷ 20 mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ± 20 mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see table FX500).

18 TERMINAL BOARD OVERVIEW

						·			
			(1) VF +24V		533797753779 533797753779	AGND (1)			
			(1) TR1			TR2 (3)			
			NC						
			NC NC			NC			
· · · · · · · · · · · · · · · · · · ·			NC			NC			
EH, EW, EI, EP	BP (2)	BC (2)	NC		123	NC NC	BC (2)	BP (2)	EH, EW, EI, EP
RX+	LINE_A -	not used		(22			CAN_H	LINE_B	RX+
RX-	LINE_B -	CAN_H			19		not used	LINE_A	RX-
TX+	DGND -	CAN_GND				-	CAN_GND	DGND	TX+
TX-	+5V	CAN_SHLD					CAN_SHLD	-+5V	TX
NC_	SHIELD _	CAN_L		-[] (14			_CAN_L	SHIELD	NC
			(1) F_INPUT+	(12	2(11)	F_MONITOR (1)			
			Q_INPUT+	(10	R	Q_MONITOR			
			INPUT-	-	\mathcal{L}	AGND			
			ENABLE	-		FAULT			
			VL+ 	$-\frac{1}{1}\left(\frac{4}{2}\right)$	A}	VL0			
			V+	╶╢╚					
]			

Connections available only SP, SF, SL
 For BC and BP executions the fieldbus connections have an internal pass-through connection

(3) Connection available only SF

19 ELECTRONIC CONNECTIONS

19.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	
	1	V0	Power supply 0 VDC	Gnd - power supply	
	2	V+	Power supply 24 VDc	Input - power supply	
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply	
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply	
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal	
	6	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver, referred to VL0	Input - on/off signal	
•	7	AGND	Analog ground	Gnd - analog signal	
	8	INPUT-	Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal	
	9 Q_MONITOF		MONITOR Flow monitor output signal: ±10 Vbc / ±20 mA maximum range, referred to AGND Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /l option		
	10	Q_INPUT+	Flow reference input signal: ±10 Vbc / ±20 mA maximum range Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /l option	Input - analog signal Software selectable	
	11 F_N		Pressure/Force monitor output signal: ± 10 Vbc / ± 20 mA maximum range, referred to AGND (1) Defaults are: ± 10 Vbc for standard and 4 $\div 20$ mA for /I option	Output - analog signal Software selectable	
	12	F_INPUT+	Pressure/Force reference input signal: ±10 Vbc / ±20 mA maximum range (1) Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /l option	Input - analog signal Software selectable	
	31	EARTH	Internally connected to driver housing		

Driver view

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(female)

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(1) Available only for SP, SF, SL

19.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS		
	1	+5V_USB	Power supply		
	2	ID	Identification		
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -		
	5	D+	Data line +		

19.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	14	CAN_L	Bus line (low)	
	16	CAN_SHLD	Shield	
C1	18	CAN_GND	Signal zero data line	
	20	CAN_H	Bus line (high)	
	22	not used	Pass-through connection (1)	

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

19.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS		
	14	SHIELD			
	16	+5V	Power supply		
C1	18	DGND	Data line and termination signal zero		
	20	LINE_B	Bus line (low)		
	22	LINE_A	Bus line (high)		

19.5 EH, EW, EI, EP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS		
	14	NC	do not connect		
	16	тх-	Transmitter		
C1	18	TX+	Transmitter		
	20	RX-	Receiver		
(input)	22	RX+	Receiver		

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	13	CAN_L	Bus line (low)	
	15	CAN_SHLD	Shield	
C2	17	CAN_GND	Signal zero data line	
	19	not used	Pass-through connection (1)	
	21	CAN_H	Bus line (high)	

(B)

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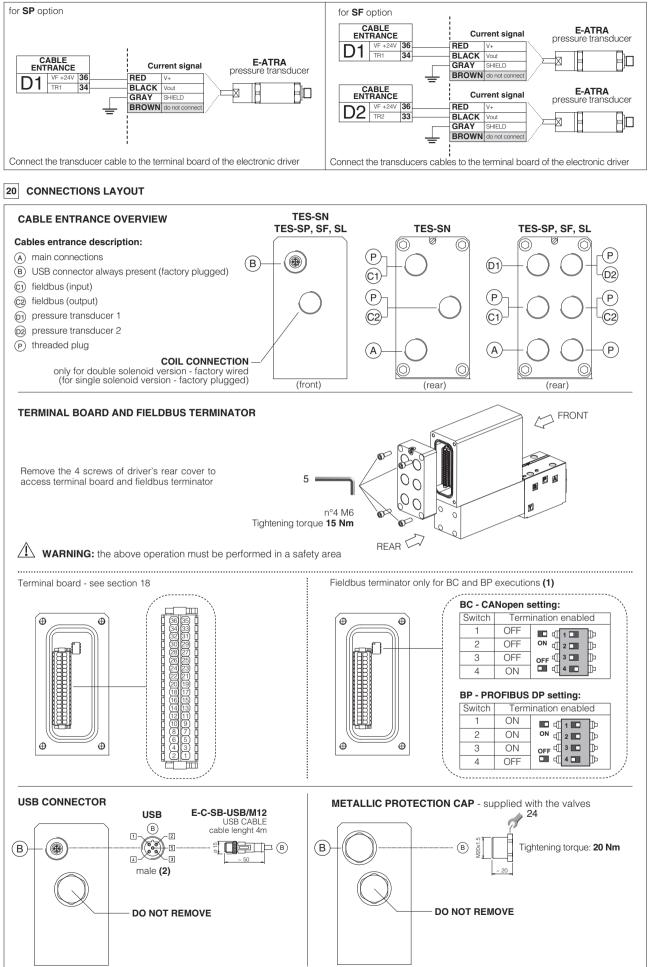
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS			
	13	SHIELD				
	15	+5V	Power supply			
C2	17	DGND	Data line and termination signal zero			
	19	LINE_A	Bus line (high)			
	21	LINE_B	Bus line (low)			

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS		
	13	NC	do not connect		
	15	тх-	Transmitter		
C2	17	TX+	Transmitter		
	19	RX-	Receiver		
(output) 21 RX+ Receiver			Receiver		

19.6 Remote pressure transducer connector - only for SP, SF, SL

CABLE ENTRANCES	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	SP, SL - Single Voltage	P, SL - Single transducer (1) Voltage Current		SF - Double transducers (1) Voltage Current		
	33	TR2	2nd signal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	/	/	Connect	Connect		
וט	34	TR1	1st ignal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect	Connect	Connect		
ר2	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/	Connect	/		
	36	VF +24V	Power supply +24VDC	Output - power supply	Connect	Connect	Connect	Connect		

E-ATRA remote pressure transducer connection - see tech table GX800



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

20.1 Cable glands and threaded plug for TES-SN - see tech table KX800

Communication	То	be ordere	ed separat	ely	Cable entrance		
interfaces		gland entrance	Thread quantity	ed plug entrance	overview	Notes	
NP	1	A	none	none		Cable entrance A is open for costumers Cable entrance P are factory plugged	
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

20.2 Cable glands and threaded plug for TES-SP, SL - see tech table KX800

Communication	Communication To be ordered separately Cable entrance		ed separat	ely	Cable entrance		
interfaces		gland entrance		ed plug entrance	overview	Notes	
NP	2	D1 A	none	none		Cable entrance A, D1 are open for costumers Cable entrance P are factory plugged	
BC, BP, EH, EW, EI, EP "via stub" connection	3	D1 C1 A	1	C2	00 00 00 00 00 00 00 00	Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged	
BC, BP, EH, EW, EI, EP "daisy chain" connection	4	D1 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged	

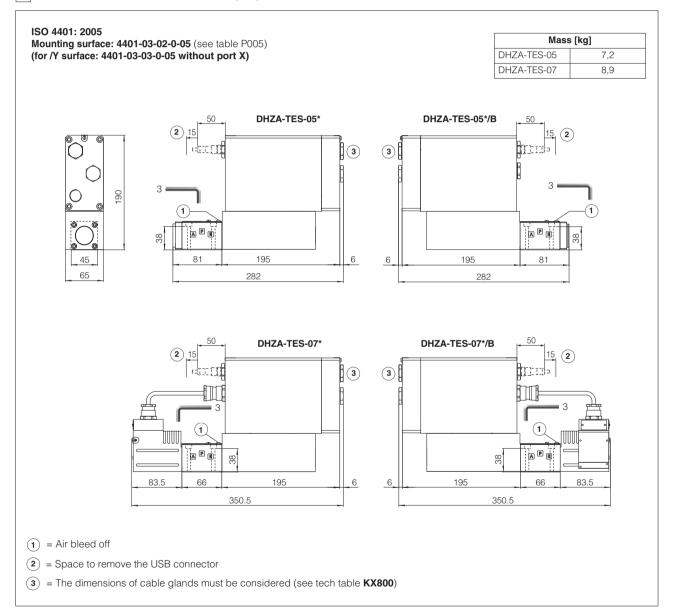
20.3 Cable glands and threaded plug for TES-SF - see tech table KX800 $\,$

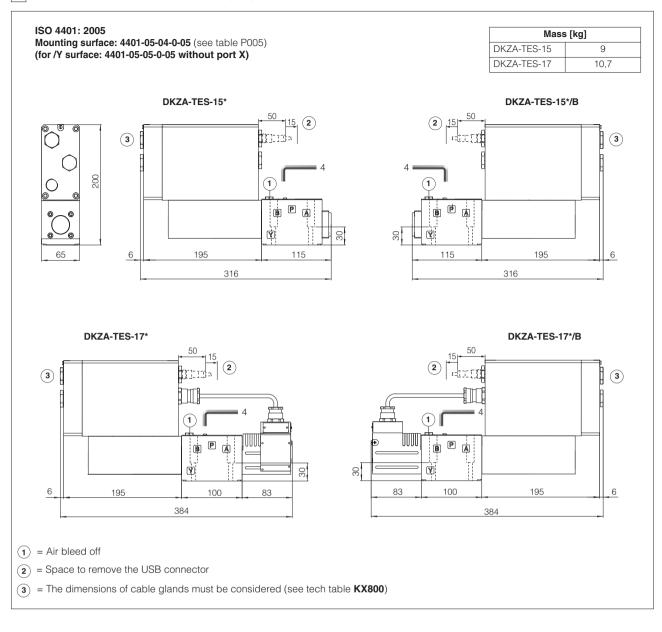
Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	3	D1 D2 A	none	none		Cable entrance A, D1, D2 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	4	D1 - D2 C1 A	1	C2	000 000 000 000	Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	5	D1 - D2 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged

21 FASTENING BOLTS AND SEALS

	DHZA	DKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø 7,5 mm (max) 1 OR 2025 Diameter of port Y: Ø = 3,2 mm (only for /Y option)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max) 1 OR 108 Diameter of port Y: Ø = 5 mm (only for /Y option)

22 INSTALLATION DIMENSIONS FOR DHZA [mm]





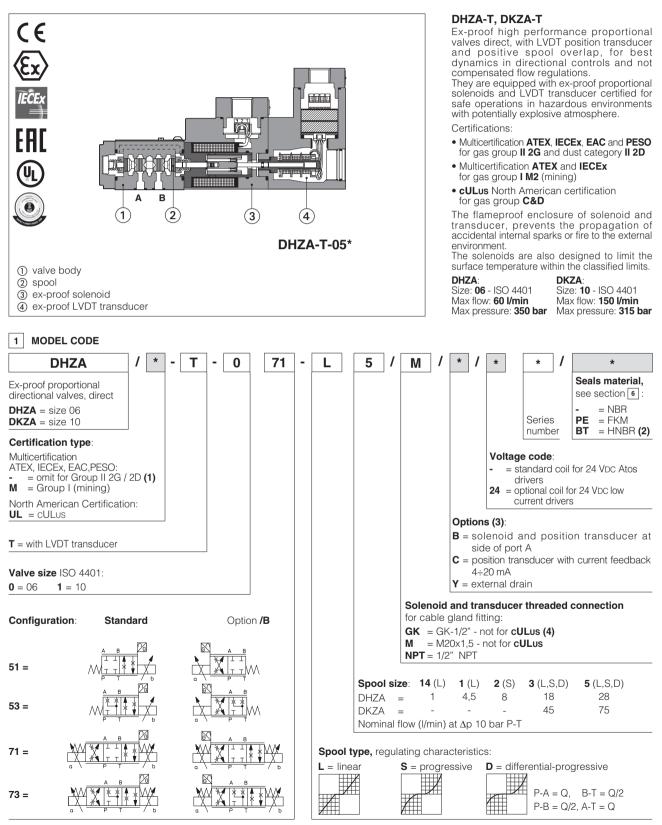
24 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments	GS500	Programming tools
X020	Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO	GS510	Fieldbus
FX900	Operating and manintenance norms for ex-proof proportional valves	GX800	Ex-proof pressure transducer type E-ATRA-7
FX500	Ex-proof for digital proportionals with P/Q control	KX800	Cable glands for ex-proof valves
		P005	Mounting surfaces for electrohydraulic valves

atos

Ex-proof proportional directional valves high performance

direct, with LVDT transducer and positive spool overlap - ATEX, IECEx, EAC, PESO or cULus



(1) The valves with Multicertification for Group II are also certified for Indian market according to **PESO** (Petroleum and Explosives Safety Organization). The PESO certificate can be downloaded from

(2) Not for multicertification M group I (mining) (3) Possible combined options: /BC, /BY, /CY, /BCY (4) Approved only for the Italian market

2 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-TEB-* /A	E-BM-TES-* /A
Туре	digital digital	
Format	DIN-ra	il panel
Data sheet	GS230	GS240

3 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	150 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200h					
Compliance	Explosion proof protection, see section 7 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

4 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model					DHZA		DKZA	
Pressure limits [bar]		ports P, A, B = 350; T = 210 (250 with external drain /Y) Y = 10						, B = 315; ernal drain /Y) Y = 10
Configuration		51, 53, 71, 73					51, 53, 71, 73	
Spool type		L14	L1	S2	L3, S3, D3	L5, S5, D5	L3, S3, D3	L5, S5, D5
Max flow [l/min]								
	$\Delta p = 10 \text{ bar}$	1	4,5	8	18	28	45	75
∆р Р-Т	$\Delta p = 30 \text{ bar}$	1,7	8	14	30	50	80	130
	max permissible flow	2,6	1	21	40	60	90	150
	∆p max P-T [bar]	70	70	70	50	50	40	40
Leakage	[cm³/min]	n] <30 (at p =			100 bar); <135 (at p = 350 bar)		<80 (at p = 100 bar);	<600 (at p = 315 bar)
Response time (1)	[ms]	≤ 20					≤	25
Hysteresis	[% of max regulation]	≤ 0,2				≤ 0,2	•	
Repeatibility	[% of max regulation]		± 0,1					
Thermal drift			zero point displacement < 1% at $\Delta T = 40^{\circ}C$					

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 2

(1) 0-100% step signal

5 ELECTRICAL CHARACTERISTICS

Max. power	35W		
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account		
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved		
Duty factor	Continuous rating (ED=100%)		
Voltage code	standard		
Coil resistance R at 20°C	3,2 Ω		
Max. solenoid current	2,5 A		

6 SEALS AND HYDRAULIC FLUID - for other fluids not included in below table, consult Atos Technical Office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without wa	iter	FKM HFDU, HFDR		ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

7 CERTIFICATION DATA

Valve type	DHZA DKZA		DHZA /M DKZA /M		A/UL A/UL	
Certifications	Multicertification Group II ATEX IECEX EAC PESO		Multicertification Group I ATEX IECEx		North American cULus	
Solenoid cerified code	OZ	А-Т	OZAM-T	OZA	-T/EC	
Type examination certificate (1)	ATEX: CESI 02 IECEx: IECEX C EAC: TC RU C- PESO: P33813	ES 10.0010x IT. 08.B.01784	ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324	- E366100	
Method of protection	ATEX, EAC Ex II 2G Ex d Ex II 2D Ex tb III0 IECEx Ex d IIC T6/T4 Ex tb IIIC T850 PESO Ex II 2G Ex d	°C/T200°C Db	ATEX Ex I M2 Ex db I Mb IECEx Ex db I Mb	• UL 1203 Class I, Div.I, (Class I, Zone I	Groups C & D , Groups IIA & IIB	
Temperature class	T4	Т3	-	T4	Т3	
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135°C	≤ 200 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C	
Applicable standards	EN 60079-0 IEC 60079-0 EN 60079-1 IEC 60079-1 EN 60079-31 IEC 60079-31		CSA 22	and UL429, 2.2 n°30 2 n°139-13		
Cable entrance: threaded connection	GK = GK-1/2" M = M20x1,5 NPT = 1/2" NPT			1/2"	NPT	

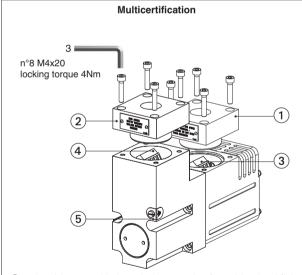
(1) The type examinator certificates can be downloaded from

(2) The solenoids Group II and cULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

8 EX PROOF SOLENOIDS WIRING



- ① solenoid cover with threaded connection for cable gland fitting
- 0 transducer cover with threaded connection for cable gland fitting
- ③ solenoid terminal board for cables wiring
- (4) transducer terminal board for cables wiring
- (5) screw terminal for additional equipotential grounding

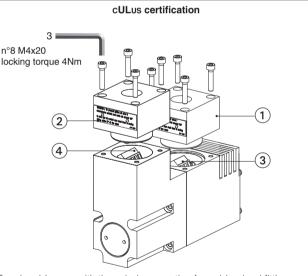
Solenoid wiring

1= CoilPCB 3 poles terminal board2= GNDsuitable for wires cross sections3= Coilup to 2,5 mm² (max AWG14)

Position transducer wiring

0-0	1 = Output signal
0~0	2 = Supply -15 V
0 -	3 = Supply +15 V
0⊧-□	4 = GND

PCB 4 poles terminal board suitable for wires cross sections up to 2,5 mm² (max AWG14)



- ① solenoid cover with threaded connection for cable gland fitting
- (2) transducer cover with threaded connection for cable gland fitting(3) solenoid terminal board for cables wiring
- (a) transducer terminal board for cables wiring

Solenoid wiring

A Pay attention to respect the polarity

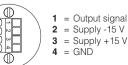


 \square

 PCB 3 poles terminal board suggested cable section up to 1,5 mm²
 (max AWG16), see section • note 1

alternative GND screw terminal connected to solenoid housing

Position transducer wiring



PCB 4 poles terminal board suggested cable section up to 1,5 mm² (max AWG16), see section 9 note 1

9 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper Conductors
- Bronze braided armor
- Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C) **Note 1:** For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

9.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Multicertification

Max ambient temperature [°C]	Temperat	ture class	Max surface temperature [°C]		Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	135 °C	-	90 °C
60 °C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	Т3	N.A.	200 °C	N.A.	120 °C

cULus certification

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature
55 °C	Τ4	135 °C	100 °C
70 °C	T3	200 °C	100 °C

10 CABLE GLANDS - only Multicertification

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

11 OPTIONS

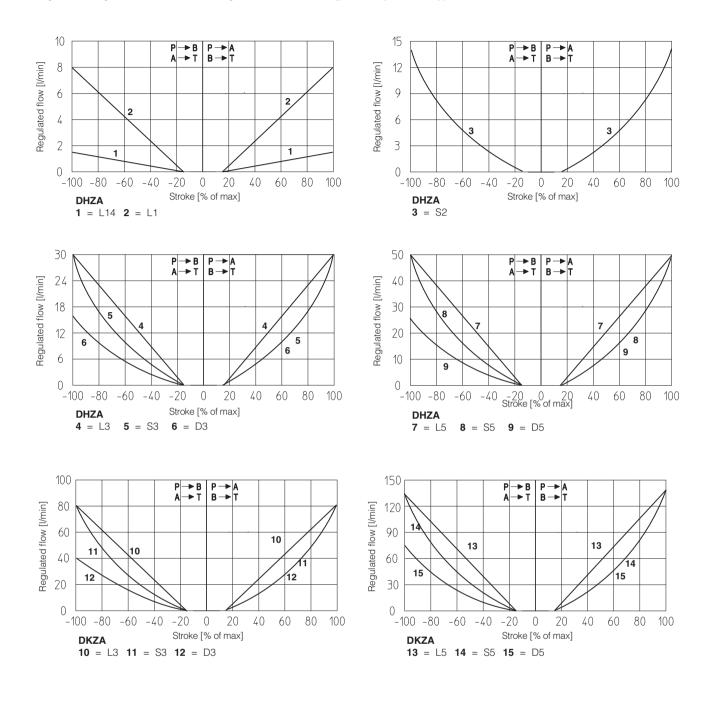
B = Solenoid and position transducer at side of port A of the main stage. For hydraulic configuration vs reference signal, see section 12

C = Position trasducer with current feedback 4÷20 mA, suggested in case of long distance between the electric driver and the proportional valve

Y = External drain, to be selected if the pressure at T port is higher than the max allowed limits

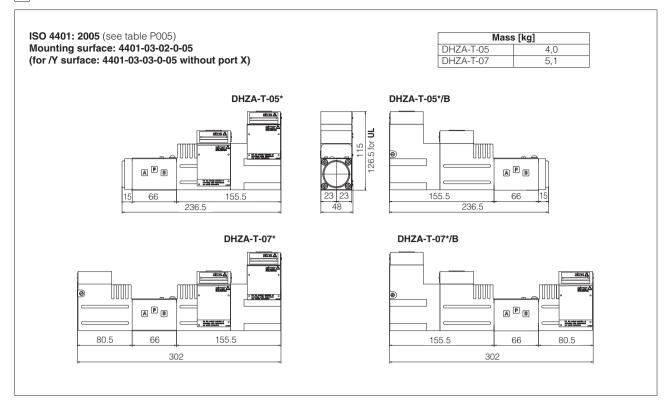
11.1 Possible combined options: /BC, /BY, /CY, /BCY

Regulation diagrams of valves with configrations 51, 53, 71, 73 (positive spool overlap) - values measure at Δp 30 bar P-T

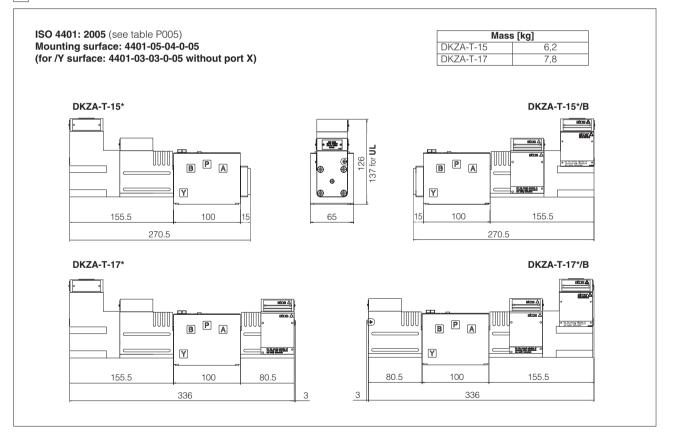


13 FASTENING BOLTS AND SEALS

	DHZA	DKZA
Ø	Fastening bolts:	Fastening bolts:
H H	4 socket head screws M5x50 class 12.9	4 socket head screws M6x40 class 12.9
	Tightening torque = 8 Nm	Tightening torque = 15 Nm
	Seals:	Seals:
\cap	4 OR 108;	5 OR 2050;
	Diameter of ports P, A, B, T: Ø 7,5 mm (max) 1 OR 2025	Diameter of ports P, A, B, T: Ø11,5 mm (max) 1 OR 108
	Diameter of port Y: $\emptyset = 3,2 \text{ mm}$ (only for /Y option)	Diameter of port Y: $\emptyset = 5 \text{ mm}$ (only for /Y option)



15 INSTALLATION DIMENSIONS FOR DKZA [mm]



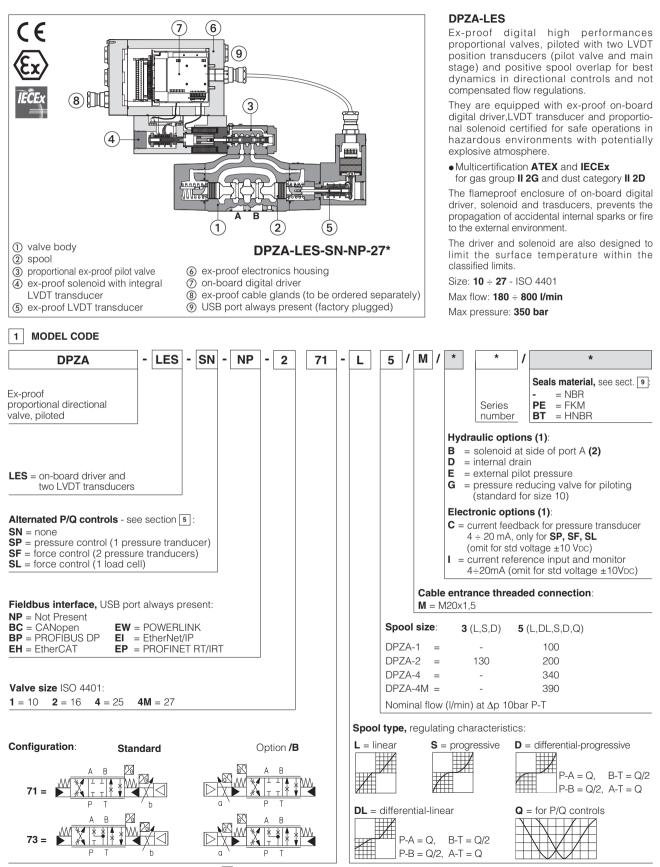
16 RELATED DOCUMENTATION

X010 Basics for electrohydraulics in hazardous environments
 X020 Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO
 X030 Summary of Atos ex-proof components certified to cULus
 FX900 Operating and manintenance information for ex-proof proportional valves
 KX800 Cable glands for ex-proof valves
 P005 Mounting surfaces for electrohydraulic valves

atos®

Ex-proof digital proportional directional valves high performance

piloted, with on-board driver, two LVDT transducers and positive spool overlap - ATEX and IECEx



(1) For possible combined options, see section $\fbox{15}$

(2) In standard configuration the solenoid with on-board digital driver and position transducer are at side A of main stage (side B of pilot valve)

2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

3 VALVE SETTINGS AND PROGRAMMING TOOLS

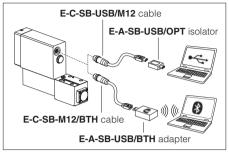
WARNING: the below operation must be performed in a safety area

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table **GS500**): **E-SW-BASIC** support: NP (USB) PS (Serial) IR (Infrared)

	ouppoin		1 0 (001101)	
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)
E-SW-*/PQ	support:	valves with SP, SF, S	SL alternated control (e	e.g. E-SW-BASIC/PQ)

USB or Bluetooth connection



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 ALTERNATED P/Q CONTROLS - see tech. table FX500

 S^* options add the closed loop control of pressure (SP) or force (SF and SL) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions. An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers for SF or 1 load cell for SL). The alternated pressure control (SP) is possible only for specific installation conditions.

6 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	75 years, see technical table P007				
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$				
Storage temperature range	Standard = -20° C ÷ $+70^{\circ}$ C /PE option = -20° C ÷ $+70^{\circ}$ C /BT option = -40° C ÷ $+70^{\circ}$ C				
Surface protection	Zinc coating with black passivation - salt spay test (EN ISO 9227) > 200 h				
Compliance	Explosion proof protection, see section 11 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006				

7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		DPZA-*-1	DPZ	'A-*-2	DPZA-*-4	DPZA-*-4M
Pressure limits	[bar]	ports P , A , B , X = 350; T = 250 (10 for option /D); Y = 10;);	
Spool type		L5, DL5, S5, D5, Q5	L3, S3, D3 L5, DL5, S5, D5, Q5			;
Nominal flow [l/min]		·				
	$\Delta p = 10 \text{ bar}$	100	130	200	340	390
Δp P-T	$\Delta p = 30 \text{ bar}$	160	220	350	590	670
	Max permissible flow	180	320	440	680	800
∆p max P-T	[bar]	50	60	60	60	60
Piloting pressure	[bar]	min. = 25	min. = 25; max = 350 (option /G advisable for pilot pressure > 150 bar)			
Piloting volume	[cm ³]	1,4	3	3,7	9,0	11,3
Piloting flow (1)	[l/min]	1,7	3	3,7	6,8	8
Leakage	Pilot [cm³/min]	100/300	100)/300	200/500	200/600
(2)	Main stage [l/min]	0,15/0,5	0,2	2/0,6	0,3/1,0	0,3/1,0
Response time (1)	[ms]	≤ 55	≤	65	≤ 85	≤ 90
Hysteresis		≤ 0,1 [% of max regulation]				
Repeatability		± 0,1 [% of max regulation]				
Thermal drift		zero point displacement < 1% at $\Delta T = 40^{\circ}C$				

(1) 0 ÷100 % step signal and pilot pressure 100 bar

(2) at P = 100/350 bar

8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)					
Max power consumption	35 W					
Analog input signals	Voltage: range ±10 V Current: range ±20 m	/DC (24 VMAX tollerant) nA	Input impedance Input impedance			
Insulation class		curing surface tempera 82 must be taken into a		ils, the European standards		
Monitor outputs		oltage ±10 VDC @ ma urrent ±20 mA @ ma	ax 5 mA ax 500 Ω load resistance			
Enable input	Range: 0 ÷ 5 VDC (OFF	state), 9 ÷ 24 VDC (ON	state), 5 ÷ 9 VDC (not acc	epted); Input impedance: $Ri > 10 k\Omega$		
Fault output	Output range: 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)					
Pressure/force transducer power supply (only for SP, SF, SL)	+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)					
Alarms	Solenoid not connected valve spool transducer	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, valve spool transducer malfunctions				
Protection degree to DIN EN60529	IP66/67 with relevant c	able gland				
Duty factor	Continuous rating (ED:	=100%)				
Tropicalization	Tropical coating on ele	ectronics PCB				
Additional characteristics	Short circuit protection of solenoid current supply; spool position control (SN) or pressure/force control (SP, SF, SL) by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply					
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)					
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158		
Communication physical layer	0	optical insulated	optical insulated RS485	Fast Ethernet, insulated 100 Base TX		

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = -20°C ÷ +60°C, with HFC hydraulic fluids = -20°C ÷ +50°C FKM seals (/PE option) = -20°C ÷ +80°C HNBR seals (/BT option) = -40°C ÷ +60°C, with HFC hydraulic fluids = -40°C ÷ +50°C			
Recommended viscosity		20 ÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1638 class 7 s		see also filter section at KTF	
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922	
Flame resistant with water	(1)	NBR, HNBR	HFC	150 12922	

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type	DPZA					
Certifications		Multicertification Group II ATEX IECEx				
Solenoid certified code		OZA-LES				
Type examination certificate (1)	• ATEX: TUV IT 18 ATEX 068 X	• ATEX: TUV IT 18 ATEX 068 X • IECEx: IECEx TPS 19.0004X				
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db HECEx Ex db IIC T6/T5/T4 Gb Ex tb IIIC T85°C/T100°C/T135°C Db					
Temperature class	Т6	T5	T4			
Surface temperature	≤ 85 °C	≤ 100 °C	≤ 135 °C			
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +55 °C	-40 ÷ +70 °C			
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079-31 EN 60079-1 IEC 60079-1					
Cable entrance: threaded connection		M = M20×1,5				

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm² **Grounding:** section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	Т6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

13 HYDRAULIC OPTIONS

- **B** = Solenoid, integral electronics and position transducer at side of port B of the main stage.
- D and E = Pilot and drain configuration can be modified as shown in section [21]. The valve's standard configuration provides internal pilot and external drain. For different pilot / drain configuration select:
 - Option /D Internal drain
 - Option /E External pilot (through port X).

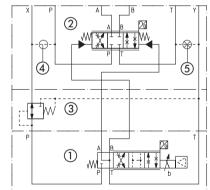
G = Pressure reducing valve installed between pilot valve and main body with fixed setting:

- DPZA-2 = 28 bar
- DPZA-1, -4 and -4M = 40 bar

It is advisable for valves with internal pilot in case of system pressure higher than 150 bar.

Pressure reducing valve is standard for DPZA-1, for other sizes add /G option.

FUNCTIONAL SCHEME - example of configuration 71



Pilot valve

Main stage

③ Pressure reducing valve

④ Plug to be added for external pilot trough port X

(5) Plug to be removed for internal drain through port T

14 ELECTRONIC OPTIONS

I = It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 VDC.
 Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.
 It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected

by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

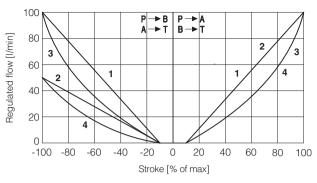
C = Only for SP, SF, SL

Option /C is available to connect pressure (force) transducers with 4 ÷ 20 mA current output signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

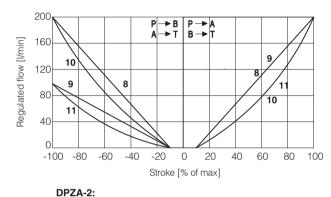
15 POSSIBLE COMBINED OPTIONS

Hydraulic options: all combination possible Electronics options: /Cl (only for SP, SF, SL)

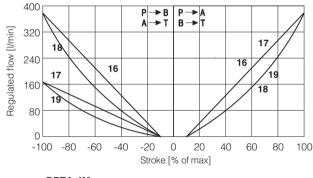




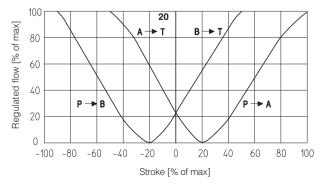




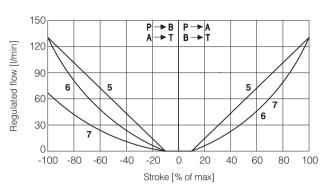




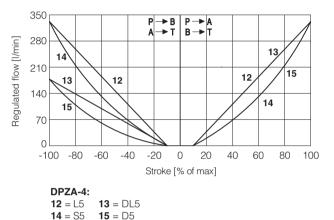
DPZA-4M: 16 = L5 17 = DL5 18 = S5 19 = D5



20 = Q5







Note: Hydraulic configuration vs. reference signal (standard and option /B)

 $\begin{array}{l} \text{Reference signal } \begin{array}{l} 0 \ \div \ +10 \ \text{V} \\ 12 \ \div \ 20 \ \text{mA} \end{array} \right\} \ P \rightarrow \text{A} \ / \ \text{B} \rightarrow \text{T} \\ \\ \text{Reference signal } \begin{array}{l} 0 \ \div \ -10 \ \text{V} \\ 12 \ \div \ 4 \ \text{mA} \end{array} \right\} \ P \rightarrow \text{B} \ / \ \text{A} \rightarrow \text{T} \end{array}$

20 = linear spool Q5

Q5 spool type is specific for alternate P/Q controls in combination with /S* option, (see tech. table FX500).

It allows to control the pressure in A port or B port and it provides a safety central position (A-T/B-T) to depressurize the actuator chambers.

The strong meter-in characteristic makes the spool suitable for both pressure control and motion regulations in several applications.

17 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

17.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

17.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

🔨 A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

17.3 Flow reference input signal (Q_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDc.

17.4 Pressure or force reference input signal (F_INPUT+) - only SP, SF, SL

Functionality of F_INPUT+ signal (pin 12), is used as reference for the driver pressure/force closed loop (see tech. table FX500). Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range 0 $\div 24$ VDc.

17.5 Flow monitor output signal (Q_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA.

17.6 Pressure or force monitor output signal (F_MONITOR) - only for SP, SF, SL

The driver generates an analog output signal proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

17.7 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

17.8 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection

17.9 Remote pressure/force transducer input signal - only for SP, SF, SL

Analog remote pressure transducers or load cell can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see table FX500).

18 TERMINAL BOARD OVERVIEW

V+ (2)(1) (2) V0

(1) connections available only SP, SF, SL

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

(3) connection available only SF

19 ELECTRONIC CONNECTIONS

19.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 VDc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
•	7	AGND	Analog ground	Gnd - analog signal
	А <u>8</u> імрит- 9 Q_мон іт		Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
			Flow monitor output signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND Defaults are: ± 10 Vpc for standard and 4 $\div 20$ mA for /l option	Output - analog signal Software selectable
	10	Q_INPUT+	Flow reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /l option	Input - analog signal Software selectable
	11	F_MONITOR	Pressure/Force monitor output signal: ± 10 Vbc / ± 20 mA maximum range, referred to AGND (1) Defaults are: ± 10 Vbc for standard and 4 $\div 20$ mA for /I option	Output - analog signal Software selectable
	12	F_INPUT+	Pressure/Force reference input signal: ±10 Vbc / ±20 mA maximum range (1) Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

Driver view

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(female)

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CABLE ENTRANCE

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PIN

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(1) Available only for SP, SF, SL

19.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	1	+5V_USB	Power supply
В	2	ID	Identification
	3	GND_USB	Signal zero data line
	4	D-	Data line -
	5	D+	Data line +

19.3 BC fieldbus execution connections

	CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
Γ		14	CAN_L	Bus line (low)
		16	CAN_SHLD	Shield
	()1	18	CAN_GND	Signal zero data line
		20	CAN_H	Bus line (high)
		22	not used	Pass-through connection (1)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

19.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
· · ·	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

19.5 EH, EW, EI, EP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE B	Bus line (low)

(B)

N

SIGNAL

CAN L

CAN_SHLD

CAN_GND

not used

CAN_H

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0

Bus line (low)

Bus line (high)

Signal zero data line

Pass-through connection (1)

Shield

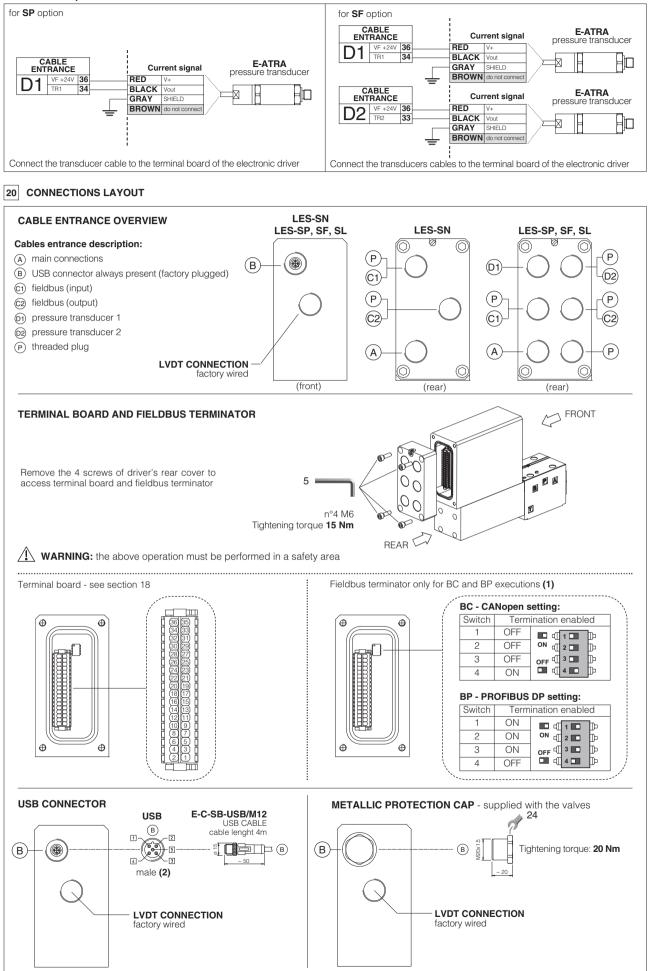
TECHNICAL SPECIFICATIONS

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

19.6 Remote pressure transducer connector - only for SP, SF, SL

CABLE ENTRANCES	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	SP, SL - Single Voltage	transducer (1) Current	SF - Double tr Voltage	ansducers (1) Current	
	33	TR2	2nd signal transducer ±10 Vbc / ±20 mA maximum range	Input - analog signal Software selectable	/	/	Connect	Connect	
וט	34	TR1	1st ignal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect	Connect	Connect	
D2	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/	Connect	/	
	36	VF +24V	Power supply +24Vbc	Output - power supply	Connect	Connect	Connect	Connect	

E-ATRA remote pressure transducer connection - see tech table GX800



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

20.1 Cable glands and threaded plug for LES-SN - see tech table KX800 $\,$

Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	1	A	none	none		Cable entrance A is open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

20.2 Cable glands and threaded plug for LES-SP, SL - see tech table KX800

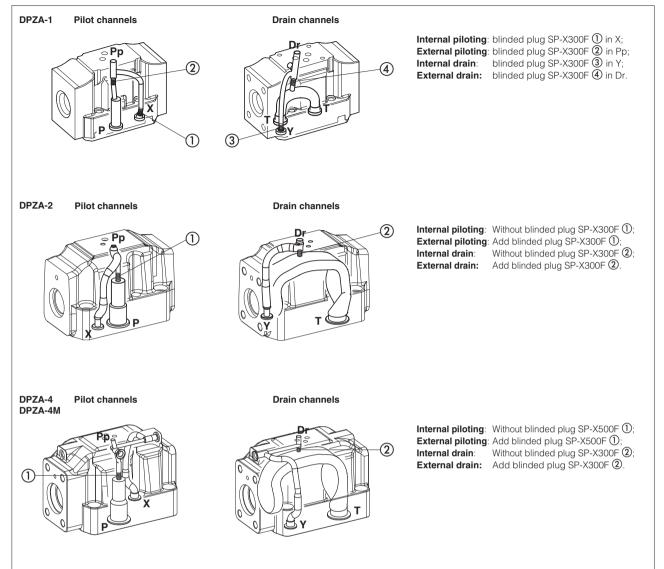
Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	2	D1 A	none	none		Cable entrance A, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	3	D1 C1 A	1	C2	00 00 00 00 00 00 00	Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	4	D1 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P are factory plugged

20.3 Cable glands and threaded plug for LES-SF - see tech table KX800

Communication	То	be ordere	ed separat	ely	Cable entrenes	
Communication interfaces		gland entrance	Thread quantity	ed plug entrance	Cable entrance overview	Notes
NP	3	D1 D2 A	none	none		Cable entrance A, D1, D2 are open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	4	D1 - D2 C1 A	1	C2	000 000 000 000	Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged
BC, BP, EH, EW, EI, EP "daisy chain" connection	5	D1 - D2 C1 - C2 A	none	none		Cable entrance A, C1, C2, D1, D2 are open for costumers Cable entrance P is factory plugged

21 PLUGS LOCATION FOR PILOT/DRAIN CHANNELS

Depending on the position of internal plugs, different pilot/drain configurations can be obtained as shown below. To modify the pilot/drain configuration, proper plugs must only be interchanged. The plugs have to be sealed using loctite 270. Standard valves configuration provides internal pilot and external drain



22 FASTENING BOLTS AND SEALS

Туре	Size	Fastening bolts	Seals
	1 = 10	4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm	5 OR 2050; Diameter of ports A, B, P, T: Ø 11 mm (max) 2 OR 108 Diameter of ports X, Y: Ø = 5 mm (max)
	$\mathbf{DPZA} \qquad 2 = 16 \qquad \begin{array}{c} \text{Tigh} \\ 2 \text{ so} \\ \text{Tigh} \\ \text{Tigh} \end{array}$	4 socket head screws M10x50 class 12.9 Tightening torque = 70 Nm 2 socket head screws M6x45 class 12.9 Tightening torque = 15 Nm	4 OR 130; Diameter of ports A, B, P, T: Ø 20 mm (max) 2 OR 2043 Diameter of ports X, Y: Ø = 7 mm (max)
DPZA		6 socket head screws M12x60 class 12.9 Tightening torque = 125 Nm	4 OR 4112; Diameter of ports A, B, P, T: Ø 24 mm (max) 2 OR 3056 Diameter of ports X, Y: Ø = 7 mm (max)
	4M = 276 socket head screws M12x60 class 12.9 Tightening torque = 125 Nm		4 OR 3137; Diameter of ports A, B, P, T: Ø 32 mm (max) 2 OR 3056 Diameter of ports X, Y: Ø = 7 mm (max)

DPZA-LES-*-1

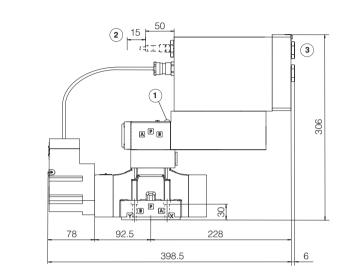
ISO 4401: 2005 Mounting surface: 4401-05-05-0-05 (see table P005)

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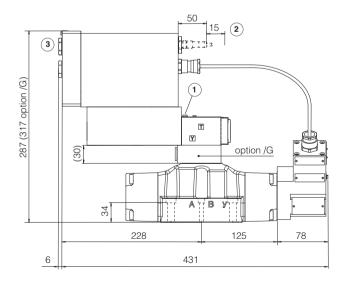
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DPZA-LES-*-2

ISO 4401: 2005 Mounting surface: 4401-07-07-0-05 (see table P005)



Mass [kg]						
DPZA-*-27*	17,9					
Option /G	+0,9					

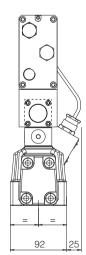
Mass [kg]

9,5

+0,9

DPZA-*-17*

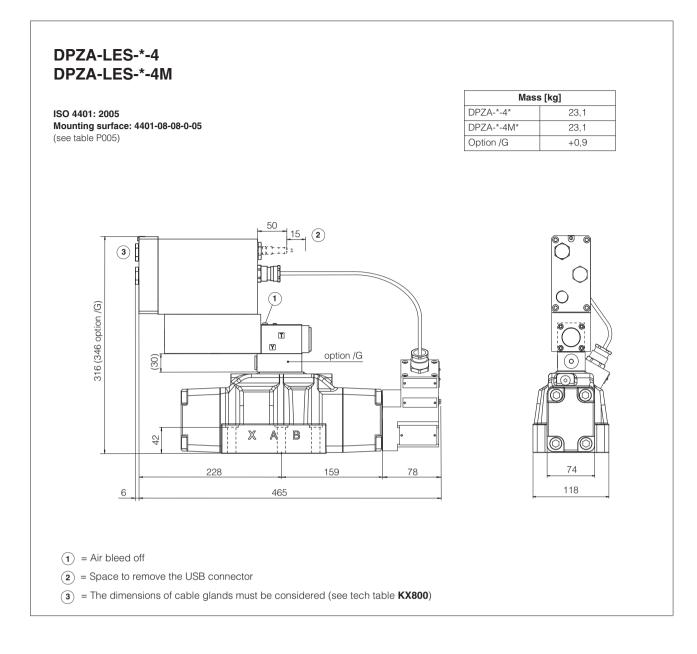
Option /G



(1) = Air bleed off

 $(\mathbf{2})$ = Space to remove the USB connector

(3) = The dimensions of cable glands must be considered (see tech table **KX800**)



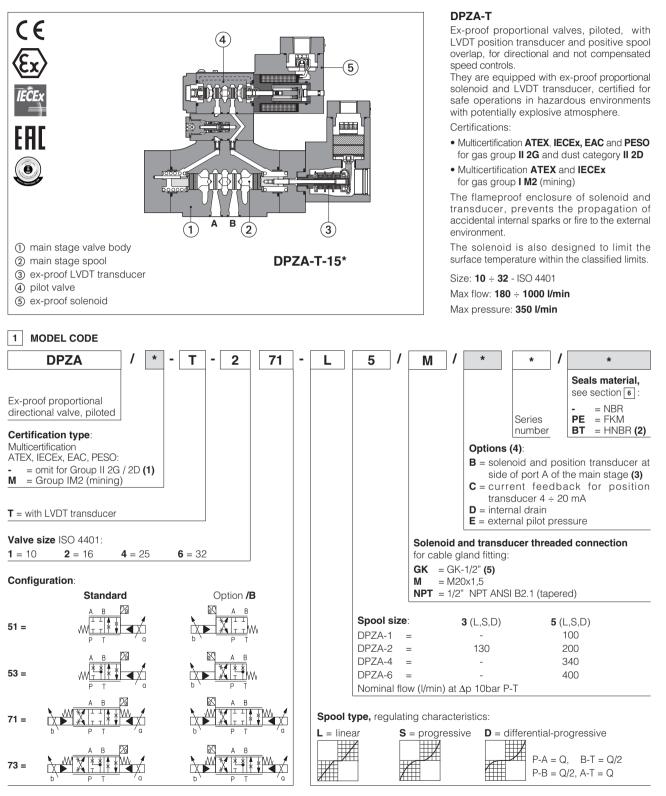
24 RELATED DOCUMENTATION

X010 X020 FX500 FX900	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO Ex-proof digital proportionals with P/Q control Operating and manintenance information for ex-proof proportional valves	GS500 GS510 GX800 KX800 P005	Programming tools Fieldbus Ex-proof pressure transducer type E-ATRA-7 Cable glands for ex-proof valves Mounting surfaces for electrohydraulic valves	
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atos°A

Ex-proof proportional directional valves

piloted, with LVDT transducer and positive spool overlap - ATEX, IECEx, EAC, PESO



(1) The valves with Multicertification for Group II are also certified for Indian market according to **PESO** (Petroleum and Explosives Safety Organization). The PESO certificate can be downloaded from

(2) Not for multicertification M group I (mining)
 (3) In standard configuration the solenoid and transducer are at side B of the main stage
 (4) Possible combined options: /BC, /BD, /BE, /CD, /CE, /DE
 (5) Approved only for the Italian market

For valve with internal drain (option /D) the pressure at T port makes difficult the manual override operation that can be possible only if the pressure at T port is lower than 50 bar

2 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-TEB-* /A E-BM-TES-* /A			
Туре	digital digital			
Format	DIN-rai	l panel		
Data sheet	GS230	GS240		

3 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	75 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection Zinc coating with black passivation - Salt spray test (EN ISO 9227) > 200h						
Compliance	Explosion proof protection, see section 7 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

4 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		DPZA-*-1	DPZ	A-*-2	DPZA-*-4	DPZA-*-6		
Pressure limits	[bar]	ports P , A , B , X = 350; T = 250 (10 for option /D); Y = 10;						
Spool type	standard	L5, S5, D5	L3, S3, D3	L5, S5, D5	L5, S5, D5	L5, S5, D5		
Nominal flow [I/min]								
	$\Delta p = 10 \text{ bar}$	100	130	200	340	400		
∆p P-T	$\Delta p = 30 \text{ bar}$	160	220	350	590	700		
	max permissible flow	180	320	440	680	1000		
∆p max P-T	[bar]	50	60	60	60	70		
Piloting pressure	[bar]	min. = 25; max = 350 (option /G advisable for pilot pressure > 200 bar)						
Piloting volume	[cm ³]	1,4	3	,7	9,0	21,6		
Piloting flow (1)	[l/min]	1,7	3	,7	6,8	14,4		
Leakage (2)	Pilot [cm³/min]	100/300	100/300		200/500	900/2800		
	Main stage [I/min]	0,15/0,5	0,2	/0,6	0,3/1,0	1,0/3,0		
Response time (1)	[ms]	≤ 70	≤	85	≤ 100	≤ 130		
Hysteresis			≤ 1	[% of max regulati	ion]			
Repeatability			± 0,	5 [% of max regula	tion]			
Thermal drift			zero point d	isplacement < 1%	at ∆T = 40°C			
Thermal drift			zero point d	isplacement < 1%	at $\Delta T = 40^{\circ}C$			

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 2

(1) 0 \div 100 % step signal and pilot pressure 100 bar (2) at $\Delta p = 100/350$ bar

5 ELECTRICAL CHARACTERISTICS

Max. power	35W
	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards
Insulation class	ISO 13732-1 and EN982 must be taken into account
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529
Duty factor	Continuous rating (ED=100%)
Voltage code	standard
Coil resistance R at 20°C	3,2 Ω
Max. solenoid current	2,5 A

6 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$					
Recommended viscosity		20 ÷ 100 mm²/s - max allowed r	20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid normal operation		ISO4406 class 18/16/13 NAS1638 class 7		see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog				
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard			
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524			
Flame resistant without water		FKM HFDU, HFDR		ISO 12922			
Flame resistant with water	(1)	NBR, HNBR HFC ISO 12922					

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) performance limitations in case of flame resistant fluids with water:

- max operating pressure = 210 bar - max fluid temperature = 50°C

7 CERTIFICATION DATA

Valve type	DPZA	DPZA /M				
Certifications		Multicertification Group II ATEX IECEX EAC PESO				
Solenoid certified code	OZA-A + ETH/	OZA-A + ETHA-4				
Type examination certificate (1)	ATEX: CESI 02 ATEX 014 IECEx: IECEx CES 10.0010x EAC: TC RU C-IT. 08.B.01784 PESO: P338131	ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x				
Method of protection	ATEX, EAC Ex II 2G Ex d IIC T4/T3 Gb Ex II 2D Ex tb IIIC T135°C/T200°C Db IECEx Ex d IIC T4/T3 Gb Ex tb IIIC T135°C/T200°C Db •PESO Ex II 2G Ex d IIC T6/T4 Gb	Ex II 2G Ex d IIC T4/T3 Gb Ex II 2D Ex tb IIIC T135°C/T200°C Db • IECEx Ex d IIC T4/T3 Gb Ex tb IIIC T135°C/T200°C Db •PESO				
Temperature class	T4	Т3	-			
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C			
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C			
Mechanical construction Flameproof enclosure Ex d		EN 60079-0, EN 6	0079-1			
Cable entrance: threaded connection	GK = GK-1/2" M = M20x1,5 NPT = 1/2" NPT					

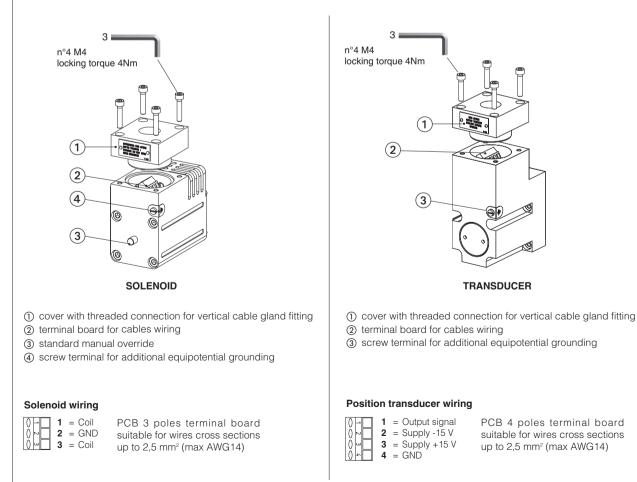
(1) The type examinator certificates can be downloaded from

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(2) In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

8 EX PROOF SOLENOIDS AND TRANSDUCERS WIRING



PCB 4 poles terminal board suitable for wires cross sections up to 2,5 mm² (max AWG14)

FX220

9 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

9.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products. **SOLENOID - Multicertification**

Max ambient temperature [°C]	Temperature class		Max surface temperature [°C]		Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	135 °C	90 °C	90 °C
45 °C	-	T4	-	135 °C	-	95 °C
55 °C	-	T3	-	200 °C	-	110 °C
60 °C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	T3	N.A.	200 °C	N.A.	120 °C

TRANSDUCER - Multicertification

Max ambient temperature [°C]	Temperature class		Max surface temperature [°C]		Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	N.A.	T6	150 °C	85 °C	-	-
70 °C	N.A.	T6	150 °C	85 °C	90 °C	90 °C

10 CABLE GLANDS

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

11 OPTIONS

- **B** = DPZA-*-*5 = solenoid and integral electronics at side of port B of the main stage. DPZA-*-*7 = integral electronics at side of port B of the main stage.
- **C** = Position transducer with current feedback 4÷20 mA, suggested in case of long distance between the electronic driver and the proportional valve
- D and E = Pilot and drain configuration can be modified as shown in section 13. The valve's standard configuration provides internal pilot and external drain. For different pilot / drain configuration select:

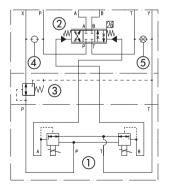
Option /D Internal drain.

Option /E External pilot (through port X).

11.1 Possible combined options: /BC, /BD, /BE, /CD, /CE, /DE

FUNCTIONAL SCHEME

example of configuration 7* 3 positions, spring centered

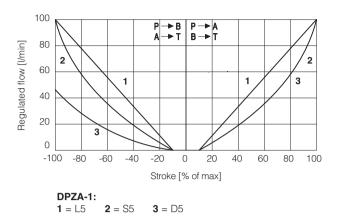


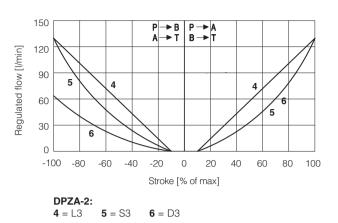
Pilot valve
 Main stage

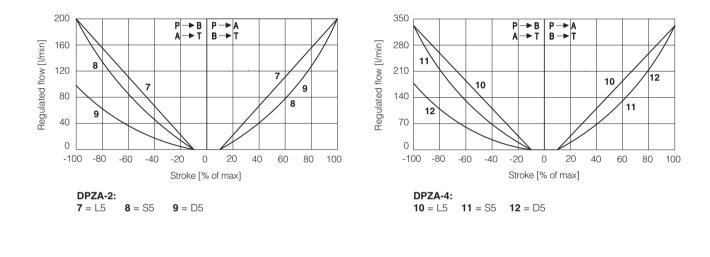
③ Pressure reducing valve

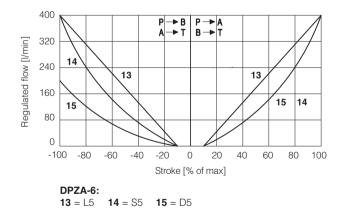
- ④ Plug to be added for external pilot trough port X
- (5) Plug to be removed for internal drain through port T

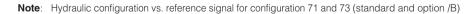
Regulation diagrams (values measure at Δp 10 bar P-T)







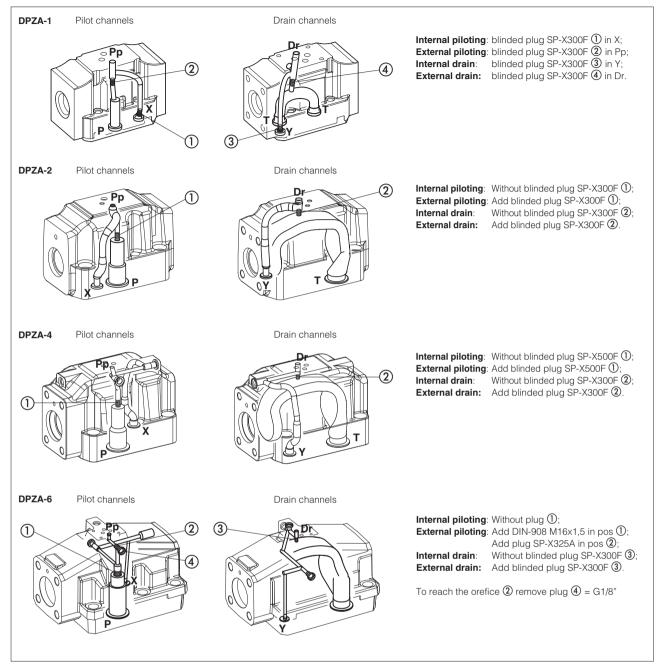




 $\begin{array}{ccc} \text{Reference signal} & 0 & \div & +10 \text{ V} \\ 12 & \div & 20 \text{ mA} \end{array} \Big\} \text{ P} \rightarrow \text{A} \text{ / B} \rightarrow \text{T} \\ \end{array} \\ \begin{array}{cccc} \text{Reference signal} & 0 & \div & -10 \text{ V} \\ 12 & \div & 4 \text{ mA} \end{array} \Big\} \text{ P} \rightarrow \text{B} \text{ / A} \rightarrow \text{T} \\ \end{array}$

13 PLUGS LOCATION FOR PILOT/DRAIN CHANNELS

Depending on the position of internal plugs, different pilot/drain configurations can be obtained as shown below. To modify the pilot/drain configuration, proper plugs must only be interchanged. The plugs have to be sealed using loctite 270. Standard valves configuration provides internal pilot and external drain

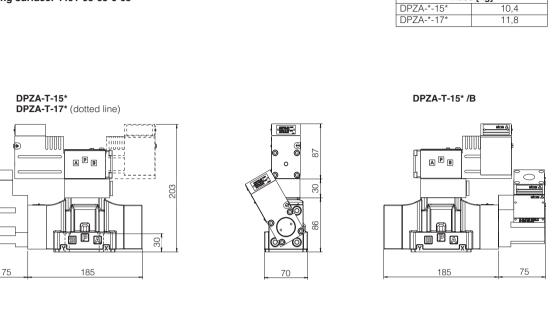


14 FASTENING BOLTS AND SEALS

	DPZA-1	DPZA-2	DPZA-4	DPZA-6
	Fastening bolts:	Fastening bolts:	Fastening bolts:	Fastening bolts:
	4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm	4 socket head screws M10x50 class 12.9 Tightening torque = 70 Nm 2 socket head screws M6x45 class 12.9 Tightening torque = 15 Nm	6 socket head screws M12x60 class 12.9 Tightening torque = 125 Nm	6 socket head screws M20x90 class 12.9 Tightening torque = 600 Nm
	Seals:	Seals:	Seals:	Seals:
\cap	5 OR 2050 Diameter of ports A, B, P, T: Ø 11 mm (max)	4 OR 130 Diameter of ports A, B, P, T: Ø 20 mm (max)	4 OR 4112 Diameter of ports A, B, P, T: Ø 24 mm (max)	4 OR 144 Diameter of ports A, B, P, T: Ø 34 mm (max)
	2 OR 108 Diameter of ports X, Y: Ø 5 mm (max)	2 OR 2043 Diameter of ports X, Y: Ø 7 mm (max)	2 OR 3056 Diameter of ports X, Y: Ø 7 mm (max)	2 OR 3056 Diameter of ports X, Y: Ø 7 mm (max)

DPZA-1

ISO 4401: 2005 (see table P005) Mounting surface: 4401-05-05-0-05

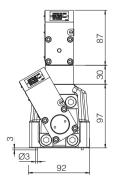


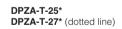
DPZA-2

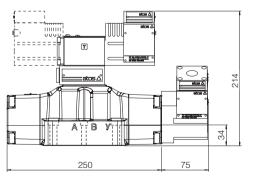
ISO 4401: 2005 Mounting surface: 4401-07-07-0-05 (see table P005)

Mass [kg]							
DPZA-*-25*	13,3						
DPZA-*-27*	14,7						

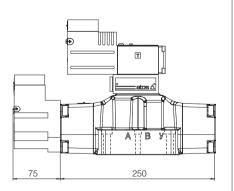
Mass [kg]







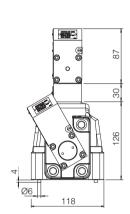
DPZA-T-25* /B

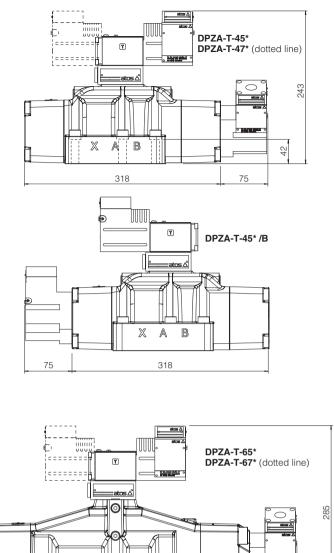


DPZA-4

ISO 4401: 2005 (see table P005) Mounting surface: 4401-08-08-0-05

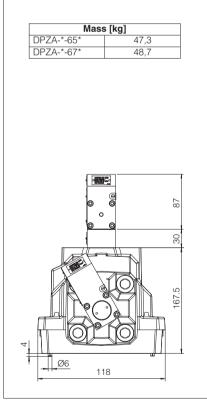
Mass	Mass [kg]								
DPZA-*-45*	20,8								
DPZA-*-47*	22,2								

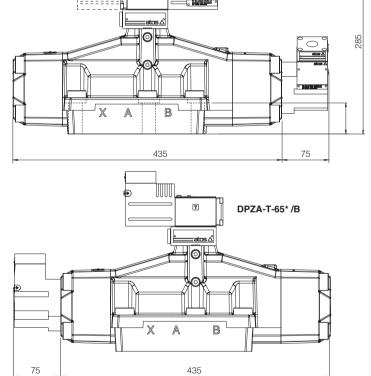




DPZA-6

ISO 4401: 2005 (see table P005) Mounting surface: 4401-10-09-0-05





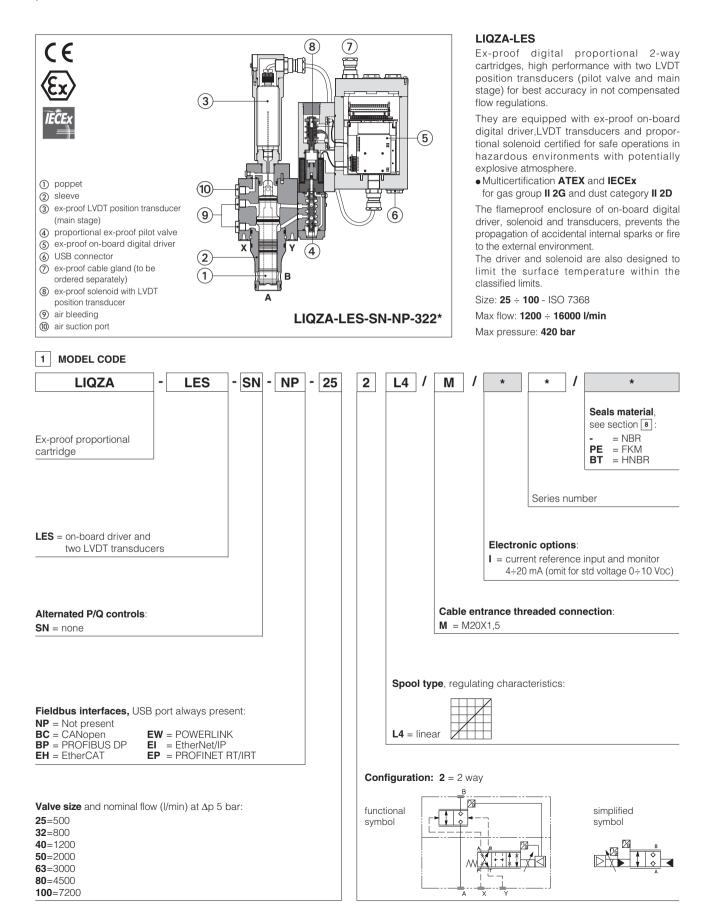
16 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments
X020	Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO
X030	Summary of Atos ex-proof components certified to cULus
FX900	Operating and manintenance information for ex-proof proportional valves
KX800	Cable glands for ex-proof valves
P005	Mounting surfaces for electrohydraulic valves

atos®

Ex-proof digital proportional 2-way cartridges high performance

piloted, with on-board driver and two LVDT transducers - ATEX and IECEx



2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

The loss of the pilot pressure causes the undefined position of the main poppet.

The sudden interruption of the power supply during the valve operation causes the immediate shut-off of the main poppet. This could cause pressure surges in the hydraulic system or high decelerations which may lead to machine damages.

3 VALVE SETTINGS AND PROGRAMMING TOOLS

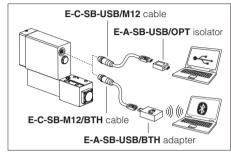
WARNING: the below operation must be performed in a safety area

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)
E-SW-*/PQ	support:	valves with SP, SF, S	SL alternated control (e	e.g. E-SW-BASIC/PQ)

USB or Bluetooth connection



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: Bluetooth adapter is available only for European, USA and Canadian markets! Bluetooth adapter is certified according RED (Europe), FCC (USA) and ISED (Canada) directives

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	75 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spay test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section 9 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

6 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Size		25	32	40	50	63	80	100
Max regulated flow	[l/min]							
	at $\Delta p = 5$ bar	500	800	1200	2000	3000	4500	7200
∆р А-В	at $\Delta p = 10$ bar	700	1100	1700	2800	4250	6350	10200
Max permissible flo	W	1200	1800	2500	4000	6000	10000	16000
Max pressure	[bar]			Ports A, B = 4	20 X = 35	50 Y≤1	0	
Nominal flow of pilot	8	20	40	40	100	100	100	
Leakage of pilot val	lve at P = 100 bar [l/min]	0,2	0,3	0,7	0,7	1	1	1
Piloting pressure	[bar]	r	nin: 40% of s	/stem pressur	e max 350	recomme	nded 140 ÷ 16	60
Piloting volume	[cm³]	2,2	7,0	9,4	17,7	32,5	39,5	49,5
Piloting flow (1)	[l/min]	5,3	14	19	35,5	56	60	60
Response time 0 ÷	100% step signal (2) [ms]	≤ 30	≤ 32	≤ 35	≤ 35	≤ 40	≤ 45	≤ 55
Hysteresis	[% of the max regulation]				≤ 0,1		·	
Repeatability	[% of the max regulation]				± 0,1			
Thermal drift		2	zero point disp	placement < 1	% at ∆T = 40	°C		

(1) 0÷100% step signal

(2) With pilot pressure = 140 bar

7 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)						
Max power consumption	35 W						
Analog input signals	Voltage: range ± 10 VDc (24 VMAX tollerant)Input impedance: Ri > 50 k Ω Current: range ± 20 mAInput impedance: Ri = 500 Ω						
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards			
Monitor outputs		urrent ±10 VDC @ ma	ax 5 mA ax 500 Ω load resistance				
Enable input	Range: 0 ÷ 5 VDC (OFF	state), 9 ÷ 24 VDC (ON	state), 5 ÷ 9 VDC (not acc	epted); Input impedance: Ri > 10 k Ω			
Fault output	Output range: 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)						
Alarms		Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, valve spool transducer malfunctions					
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland					
Duty factor	Continuous rating (ED	=100%)					
Tropicalization	Tropical coating on ele	ectronics PCB					
Additional characteristics	Short circuit protection of solenoid current supply; spool position control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply						
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)						
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158			
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX			

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

8 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid normal opera		ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without wa	iter	FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	130 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

9 CERTIFICATION DATA

Components type	Pilot va	Pilot valve solenoid and LVDT transducer				
Certifications		Multicertific	ation ATEX IECEx			
Components Certified code		OZA-LES		ETHA-15		
		ATEX: TUV IT 18 ATEX 06	68 X	• ATEX: TUV IT 16 ATEX 053 X		
Type examination certificate (1)	-	IECEX: IECEX TPS 19.000	4X	IECEx: IECEx TPS 16.0003X		
Method of protection	ATEX Ex II 2G Ex db IIC T6/ Ex II 2D Ex tb IIIC T85°C	ATEX Ex II 2G Ex db IIC T6 Gb Ex II 2D Ex tb IIIC T85°C Db Ex I M2 Ex db IMb IECEx Ex db IIC T6 Gb Ex tb IIIC T85°C Db Ex db IMb				
Temperature class	Т6	T5	T4	Т6		
Surface temperature	≤ 85 °C	≤ 100 °C	≤ 135 °C	≤ 85 °C		
Ambient temperature (2)	-40 ÷ +40 °C -40 ÷ +55 °C -40 ÷ +70 °C			-40 ÷ +70 °C		
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 EN 60079-1 IEC 60079-1			IEC 60079-31		
Cable entrance: threaded connection		M = M20x1,5		factory wired		

(1) The type examinator certificates can be downloaded from

(2) The driver solenoid and LVDT transducers are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

I WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

10 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

10.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]	
40 °C	Т6	85 °C	80 °C	
55 °C T5		100 °C	90 °C	
70 °C	T4	135 °C	110 °C	

11 CABLE GLANDS

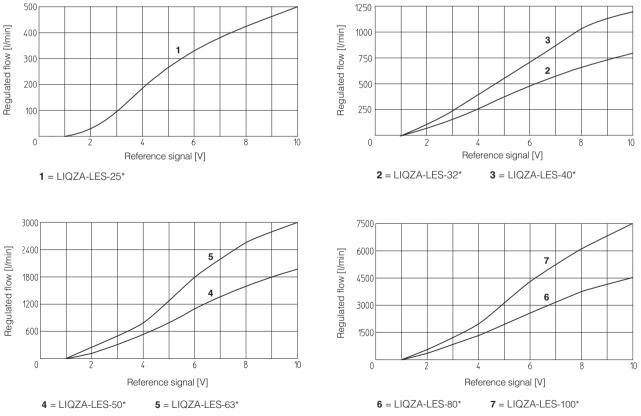
Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table KX800 Note: a Loctite sealant type 545, should be used on the cable gland entry threads

12 ELECTRONIC OPTIONS

I = It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

13 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

13.1 Regulation diagrams (values measured at Δp 5 bar)



14 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

14.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

/ A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

14.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

14.3 Flow reference input signal (Q_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDc.

14.4 Flow monitor output signal (Q_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDC for standard and $4 \div 20$ mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

14.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

14.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

NC NC (36) (35) NC NC (34) (33) NC (32) EARTH (31) NC (30) 29) NC (28) NC 27 NC 26 NC NC (25) EH, EW, EI, EP EH, EW, EI, EP BP (1) BC (1) BC (1) BP (1) (24) NC NC (23) RX+ LINE_A (22) (21) CAN_H LINE B RX+ not used RX-LINE B CAN H (20) (19) not used LINE A RX. (18) 17 DGND CAN_GND CAN_GND DGND TX+ TX+ TX-+5\ CAN SHLD (16 (15) CAN SHLD ±51/ TY_ (14) 13 NC SHIELD CAN L CAN L SHIELD NC NC NC (12)(11)(10) (9) Q INPUT+ Q MONITOR 75 8 AGND INPUT (6)FAULT ENABLE (4 (3) VL0 VL+ 1) V+ ່າ VO

15 TERMINAL BOARD OVERVIEW

(1) For BC and BP executions the fieldbus connections have an internal pass-through connection

16 ELECTRONIC CONNECTIONS

16.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 Vbc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vpc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 VDc) or disable (0 VDc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
	9	Q_MONITOR	Flow monitor output signal: $0 \div 10 \text{ Vpc} / \pm 20 \text{ mA maximum range, referred to AGND}$ Defaults are: $\pm 10 \text{ Vpc}$ for standard and $4 \div 20 \text{ mA for /I option}$	Output - analog signal Software selectable
	10	Q_INPUT+	Flow reference input signal: $0 \div 10$ Vpc / ± 20 mA maximum range Defaults are: ± 10 Vpc for standard and $4 \div 20$ mA for /I option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

16.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply		
	2	ID	Identification	I (To a s	
$ \mathbf{B} $	3	GND_USB	Signal zero data line		
	4	D-	Data line -		
	5	D+	Data line +	(female)	

16.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
C.1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

16.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

16.5 EH, EW, EI, EP fieldbus execution connections

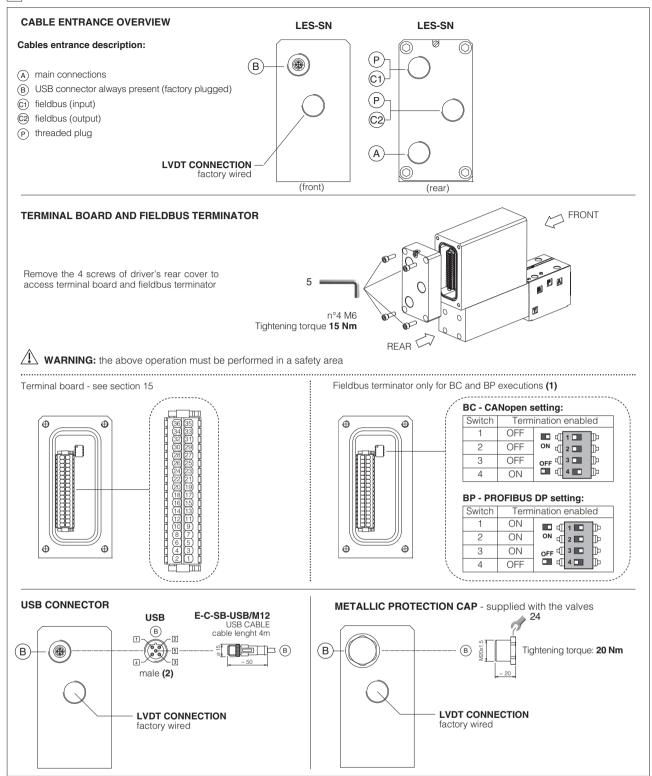
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	CAN_L	Bus line (low)
	15	CAN_SHLD	Shield
C2	17	CAN_GND	Signal zero data line
\sim –	19	not used	Pass-through connection (1)
	21	CAN_H	Bus line (high)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

17 POWER SUPPLY AND SIGNALS SPECIFICATIONS

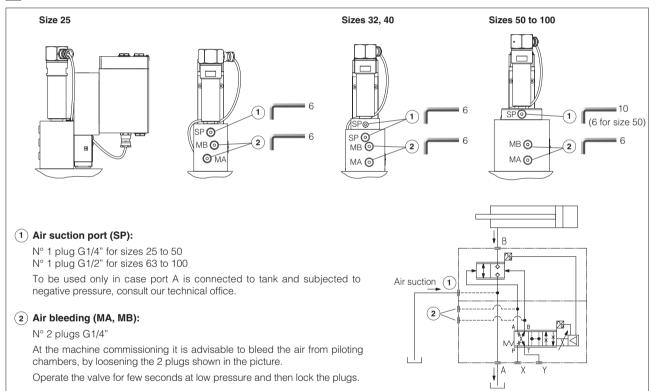


(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

17.1 Cable glands and threaded plug - see tech table KX800

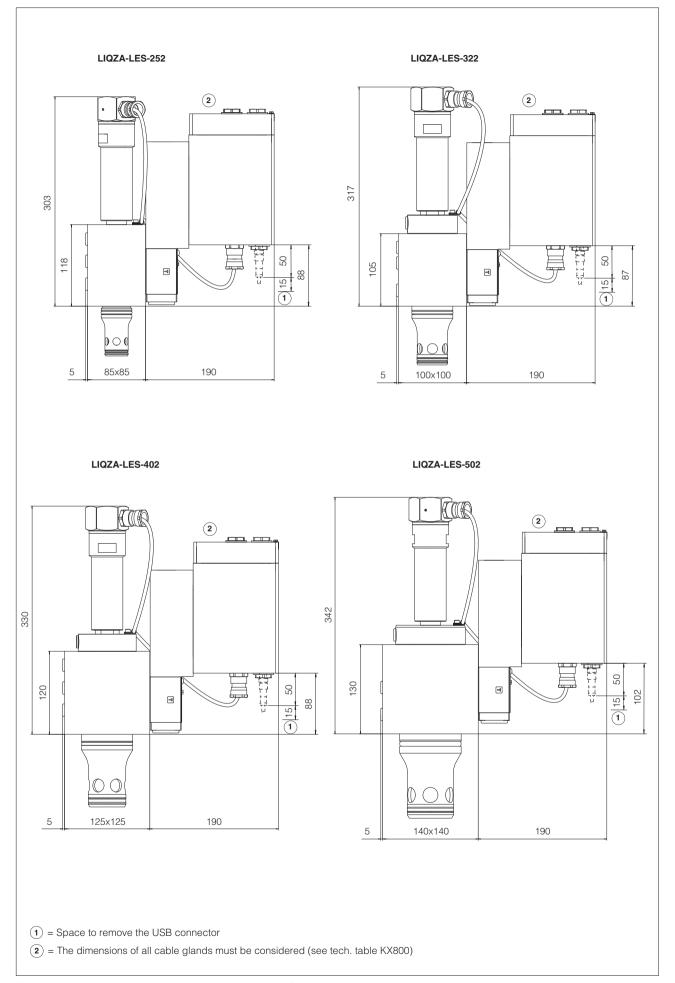
Communication	То	be ordere	ed separat	ely	Cable entrance	Notes	
interfaces		gland entrance		ed plug entrance	overview		
NP	1	A	none	none		Cable entrance A is open for costumers Cable entrance P are factory plugged	
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

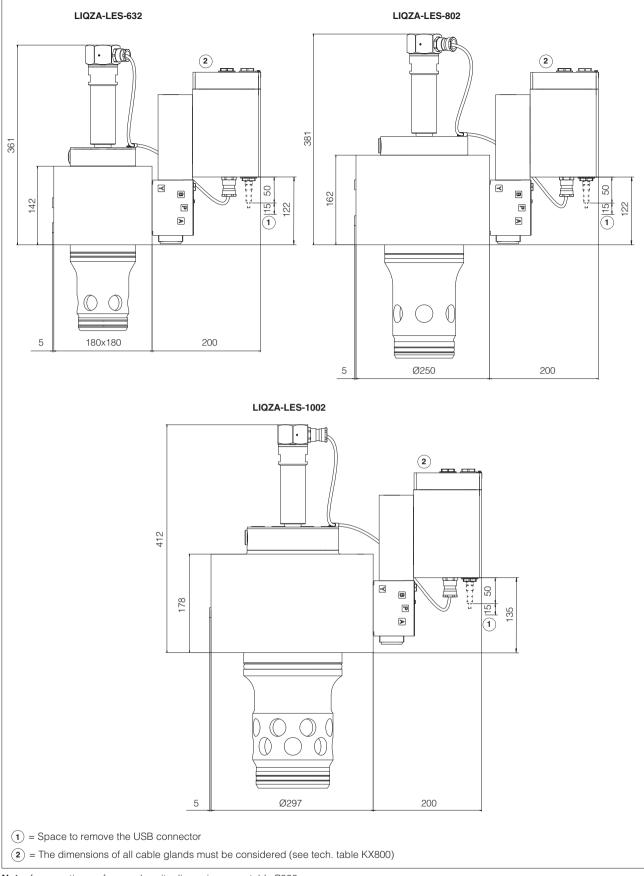
18 AIR BLEEDING



Туре	Size	Fastening bolts (supplied with the valve)	Mass [kg]
	25	4 socket head screws M12x100 class 12.9 Tightening torque = 125 Nm	15,2
	32	4 socket head screws M16x60 class 12.9 Tightening torque = 300 Nm	18
	40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	23,7
LIQZA	50	4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	31
	63	4 socket head screws M30x120 class 12.9 Tightening torque = 2100 Nm	51
80 8 socket head screws M24x80 class 12.9 Tightening torque = 1000 Nm			78,6
	8 socket head screws M30x120 class 12.9 Tightening torque = 2100 Nm		130

20 INSTALLATION DIMENSIONS [mm]





Note: for mounting surface and cavity dimensions, see table P006

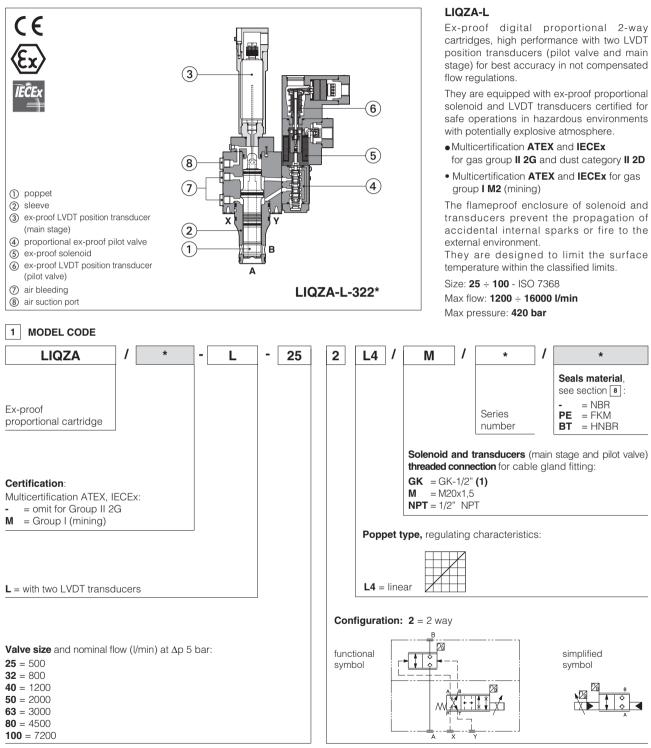
21 RELATED DOCUMENTATION

X010 X020 FX900 GS500	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO Operating and manintenance information for ex-proof proportional valves Programming tools	GS510 KX800 P006	Fieldbus Cable glands for ex-proof valves Mounting surfaces and cavities for cartridge valves
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atos

Ex-proof proportional 2-way cartridges high performance

piloted, with two LVDT transducers - ATEX and IECEx



(1) Approved only for the italian market

2 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-LEB-* /A	E-BM-LES-* /A	
Туре	digital	digital	
Format	DIN-rail panel		
Data sheet	GS230	GS240	

3 GENERAL CHARACTERISTICS

Assembly position	Any position		
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100		
MTTFd valves according to EN ISO 13849	75 years, see technical table P007		
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$		
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$		
Surface protection	Zinc coating with black passivation - salt spay test (EN ISO 9227) > 200 h		
Compliance	Explosion proof protection, see section 9 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"		
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006		

80

4500

6350

10000

10

100

7200

10200 16000

4 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C								
Size		25	32	40	50	63		
Max regulated flow	[l/min]							
	at $\Delta p = 5$ bar	500	800	1200	2000	3000		
Δp A-B	at $\Delta p = 10$ bar	700	1100	1700	2800	4250		
Max permissible flow		1200	1800	2500	4000	6000		
Max pressure	[bar]			Ports A, B = 4	20 X = 3	350 Y≤		

Nominal flow of pilot valve at $\Delta p = 70$ bar [l/min]		8	20	40	40	100	100	100	
Leakage of pilot v	valve at P = 100 bar	[l/min]	0,2	0,3	0,7	0,7	1	1	1
Piloting pressure		[bar]	n	nin: 40% of sy	/stem pressur	e max 350) recomme	nded 140 ÷ 10	60
Piloting volume		[cm ³]	2,2	7,0	9,4	17,7	32,5	39,5	49,5
Piloting flow (1)		[l/min]	5,3	14	19	35,5	56	60	60
Response time 0 ÷ 100% step signal (2) [ms]		≤ 30	≤ 32	≤ 35	≤ 35	≤ 40	≤ 45	≤ 55	
Hysteresis [% of the max regulation]		≤ 0,1							
Repeatability [% of the max regulation]			± 0,1						
Thermal drift		zero point displacement < 1% at $\Delta T = 40^{\circ}C$							

(1) 0÷100% step signal

(2) With pilot pressure = 140 bar

5 ELECTRICAL CHARACTERISTICS

Max. power	35W	
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account	
Protection degree with relevant cable gland	IP66/67 to DIN EN60529	
Duty factor	Continuous rating (ED=100%)	
Voltage code	standard	
Coil resistance R at 20°C	3,2 Ω	
Max. solenoid current	2,5 A	

6 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature		NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$				
		HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid normal operation		ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water (1)		NBR, HNBR	HFC	130 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

The loss of the pilot pressure causes the undefined position of the main poppet.

The sudden interruption of the power supply during the valve operation causes the immediate shut-off of the main poppet. This could cause pressure surges in the hydraulic system or high decelerations which may lead to machine damages.

7 CERTIFICATION DATA

Valve type	LIC	QZA	LIQZA /M	LIQZA, LIQZA /M	
Component type	F	Pilot solenoid and	I LVDT transducer	LVDT main stage transducer	
Certifications		ation Group II IECEx	Multicertification Group I ATEX IECEx	Multicertification Group I and II ATEX IECEx	
Solenoid certified code	OZ	A-T	OZAM-T	ETHA-15	
Type examination certificate (1)	ATEX: CESI 02 IECEx: IECEx C		ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	ATEX: TUV IT 16 ATEX 053X ICEX: IECEX TPS 16.0003X	
Method of protection	 ATEX Ex II 2G Ex d IIC T4/T3 Gb Ex II 2D Ex tb IIIC T135°C/T200°C Db IECEX Ex d IIC T4/T3 Gb Ex tb IIIC T85°C/T200°C Db 		ATEX Ex I M2 Ex db I Mb IECEx Ex db I Mb	ATEX Ex II 2G Ex db IIC T6 Gb Ex II 2D Ex tb IIIC T85°C Db Ex I M2 Ex db IMb IECEx Ex db IIC T6 Gb Ex tb IIIC T85°C Db Ex db IMb	
Temperature class	T4	Т3	-	T6	
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 85 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +70 °C (3)	
Applicable standards		EN 60079-0 EN 60079-1 EN 60079-3		IEC 60079-0 IEC 60079-1 IEC 60079-31	
Cable entrance: threaded connection		GK = GK-1/2" M = M20x1,5 NPT = 1/2" NPT			

(1) The type examinator certificates can be downloaded from

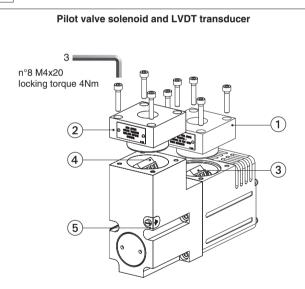
(2) The solenoids Group II are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

(3) For Group I (mining) the temperature range is -20°C \div +70°C

🗥 WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

8 EX PROOF SOLENOIDS AND LVDT TRANSDUCER WIRING



- () solenoid cover with threaded connection for cable gland fitting
- (2) transducer cover with threaded connection for cable gland fitting
- (3) solenoid terminal board for cables wiring
- (4) transducer terminal board for cables wiring
- (5) screw terminal for additional equipotential grounding

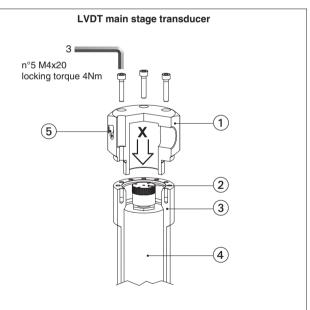
Solenoid wiring

- PCB 3 poles terminal board 1 = Coil = GND 2 suitable for wires cross sections
 - 3 = Coil up to 2,5 mm² (max AWG14)

Position transducer wiring

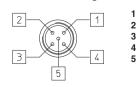
) - 🗆	1	= Output signal
)~□	2	= Supply -15 V
) []	3	= Supply +15 V
) +- []	4	= GND

PCB 4 poles terminal board suitable for wires cross sections up to 2,5 mm² (max AWG14)



- (1) transducer cover with threaded connection for cable gland fitting
- transducer terminal board for cables wiring
- ③ ex-proof protection for LVDT transducer
- (4) LVDT transducer
- (5) screw terminal for additional equipotential grounding

Transducer wiring - view from X



1 = Do not connect = Supply +15 V 3 = GND = Output signal = Supply -15 V

9 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm² **Main LVDT transducer:** section of cable connection wires = 1 mm²

9.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature	Temperature class		Max surface te	mperature [°C]	Min. cable temperature [°C]		
[°C]	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II	LVDT main stage
40 °C	-	T4	150 °C	135 °C	-	90 °C	-
60 °C	-	-	150 °C	-	110 °C	-	-
70 °C	N.A.	T3	N.A.	200 °C	N.A.	120 °C	90°C

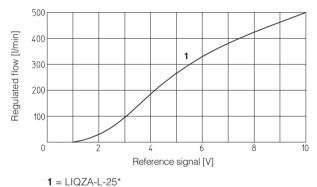
10 CABLE GLANDS

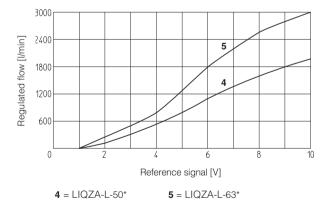
Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

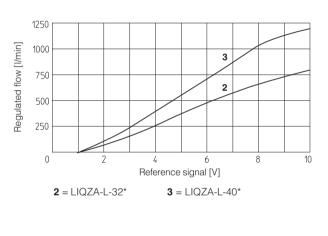
Note: a Loctite sealant type 545, should be used on the cable gland entry threads

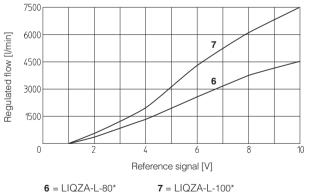
11 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

11.1 Regulation diagrams (values measured at Δp 5 bar)

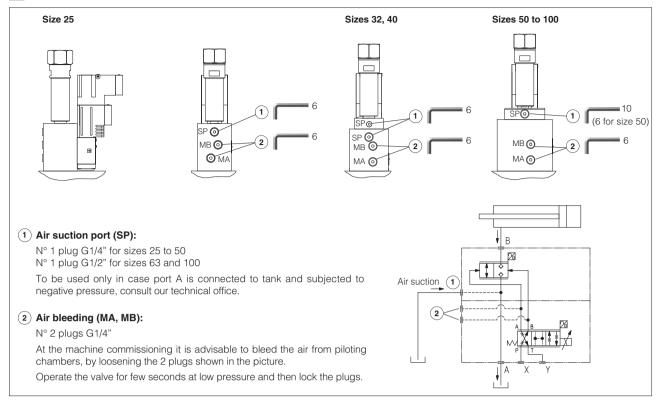








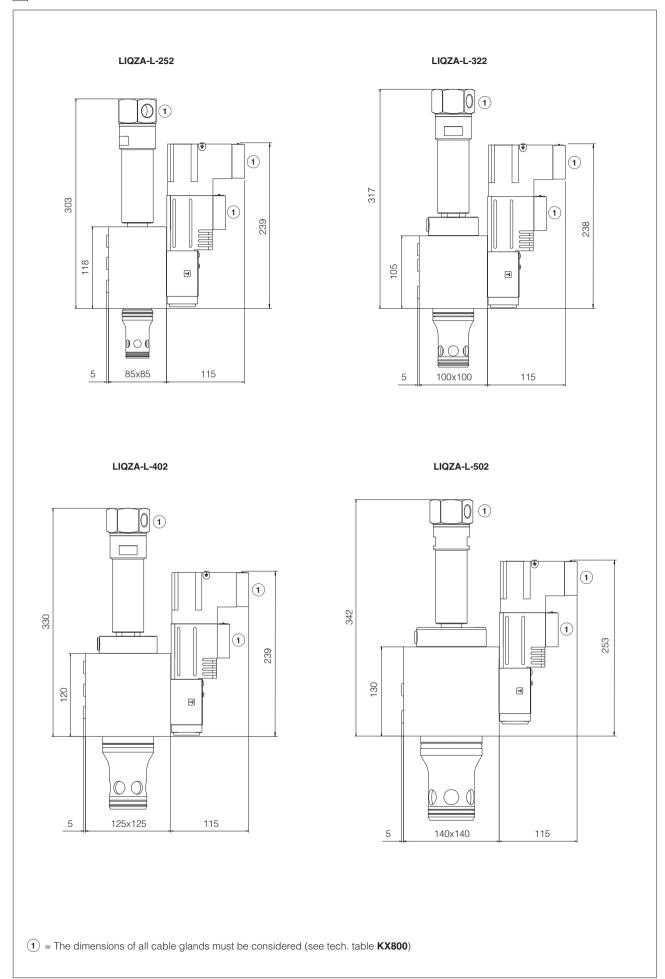
12 AIR BLEEDING

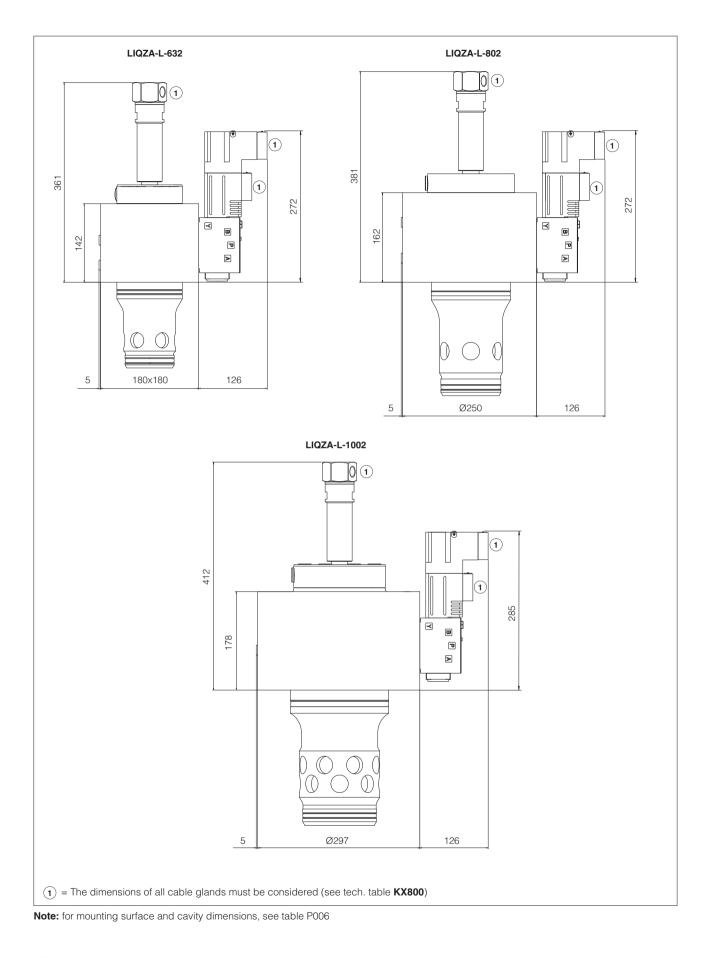


13 FASTENING BOLTS AND VALVE MASS

Туре	Size	Fastening bolts (supplied with the valve)	Mass [kg]		
	25	4 socket head screws M12x100 class 12.9 Tightening torque = 125 Nm	12		
-	32	4 socket head screws M16x60 class 12.9 Tightening torque = 300 Nm	14,8		
-	40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	20,5		
LIQZA	50	4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	22,8		
-	63	4 socket head screws M30x120 class 12.9 Tightening torque = 2100 Nm	48,1		
	80	8 socket head screws M24x80 class 12.9 Tightening torque = 1000 Nm	75,7		
	100	8 socket head screws M30x120 class 12.9 Tightening torque = 2100 Nm	127,1		

14 INSTALLATION DIMENSIONS [mm]





15 RELATED DOCUMENTATION

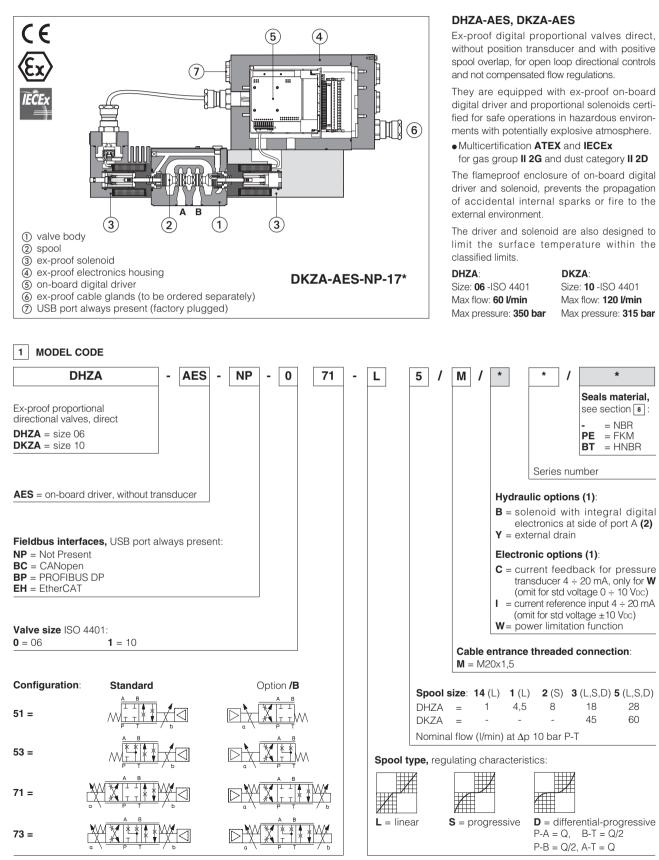
X010	Basics for electrohydraulics in hazardous environments	KX800	Cab
X020	Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO	P006	Mou
FX900	Operating and manintenance information for ex-proof proportional valves		

Cable glands for ex-proof valves Nounting surfaces and cavities for cartridge valves

atos®

Ex-proof digital proportional directional valves

direct, with on-board driver, without transducer and with positive spool overlap ATEX and IECEx



(1) For possible combined options, see section 14

(2) In standard configuration the solenoid with on-board digital driver and position transducer are at side port B

2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table FX900 and in the user manuals included in the E-SW-* programming software.

E-A-SB-USB/OPT isolator

C

E-A-SB-USB/BTH adapter



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 GENERAL CHARACTERISTICS

Assembly position	Horizontal position only					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	75 years; 150 years only for RZMA-010, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section 8 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

6 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve mo	del				DHZA			DKZA			
Pressure	limits [bar]	ports P	, A , B = 3	350; T =	210 (250 with	external drain	/Y); Y = 10	ports P , A , B = 315; T = 210 (250 with external drain /Y); Y = 10			
Configura	ation			51, 53	, 71, 73		70	51, 53	, 71, 73	70	
Spool typ	be	L14	L1	S2	L3,S3,D3	L5,S5,D5	L5	L3,S3,D3	L5,S5,D5	L3,L5,D5	
Nominal	flow [l/min]										
	Δp = 10 bar	1	4,5	8	18	2	8	45	6	60	
∆p P-T	Δp = 30 bar	1,7	8	14	30	5	0	80	100		
Max perr	nissible flow	2,6	12	21	40	6	0	90	1:	20	
Δp max l	P-T [bar]	70	70	70	50	5	0	40	4	0	
Response	e time [ms] (1)				≤ 35			≤ 45			
Leakage	[cm³/min]	n^{3} /min] <30 (at P = 100 bar); <135 (at P = 350 bar) <80 (at P = 100 bar); <600 (at P = 315 bar)					P = 315 bar)				
Hysteres	is	≤5 [% of max regulation]									
Repeatal	oility					=	±1 [% of m	ax regulation]			

(1) 0 ÷ 100% step signal

7 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)						
Max power consumption	35 W						
Analog input signals							
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account						
Monitor outputs	Voltage: maximum range ± 5 Vpc @ max 5 mA						
Enable input	Range: 0 ÷ 9 VDc (OFF state), 15 ÷ 24 VDc (ON state), 9 ÷ 15 VDc (not accepted); Input impedance: Ri > $87k\Omega$						
Fault output	Output range : $0 \div 24$ VDC (ON state \cong VL+ [logic power supply] ; OFF state \cong 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)						
Pressure transducer power supply (only /W option)	+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)						
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, current control monitoring, power supplies level, pressure transducer failure (/W option)						
Protection degree to DIN EN60529	IP66/67 with relevant cable gland						
Duty factor	Continuous rating (ED=100%)						
Tropicalization	Tropical coating on electronics PCB						
Additional characteristics	Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply						
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)						
Communication interface	USB CANopen PROFIBUS DP EtherCAT Atos ASCII coding EN50325-4 + DS408 EN50170-2/IEC61158 EC 61158						
Communication physical layer	not insulatedoptical insulatedoptical insulatedFast Ethernet, insulatedUSB 2.0 + USB OTGCAN ISO11898RS485100 Base TX						

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

8 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed r	20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without wa	iter	FKM HFDU, HFDR		- ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

9 CERTIFICATION DATA

Valve type		DHZA, DKZA						
Certifications				Multicertifica	ation Group II			
				ATEX	IECEx			
Solenoid certified co	ode			OZA	-AES			
Type examination ce	ertificate (1)	• ATEX: TUV I	T 18 ATEX 068	Х	IECEX: IEC	Ex TPS 19.0004X		
Method of protection		ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C Db						
	Single solenoid valve	Т6	-	Т	T5 -		-	
Temperature class	Double solenoid valve	-	T4				Т3	
Surface temperature	9	≤ 85 °C	≤ 135 °C	≤ 10	≤ 100 °C		≤ 200 °C	
Ambient temperature (2)		-40 ÷ +40 °C		-40 ÷ +	-40 ÷ +55 °C		-40 ÷ +70 °C	
Applicable Standards		EN 60079-0 E EN 60079-1		EN 60079-31 IEC 60079-0 IEC 6007 IEC 60079-1		C 60079-31		
Cable entrance: thre	eaded connection			$\mathbf{M} = \mathbb{N}$	20x1,5			

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code. WARNING:

 $\sim 10^{-12}$ service work performed on the valve by the end users or not qualified personnel invalidates the certification.

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

10.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]	
40 °C	T6	85 °C	80 °C	
55 °C	T5	100 °C	90 °C	
70 °C	T4	135 °C	110 °C	

11 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX600 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

12 HYDRAULIC OPTIONS

- B = Solenoid, integral electronics and position transducer at side of port A of the main stage. For hydraulic configuration vs reference signal, see 15.1
- Y = Option /Y is mandatory if the pressure in port T exceeds 210 bar

13 ELECTRONIC OPTIONS

- I = It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 Vbc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vbc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.
- C = Only in combination with option /W It is available to connect pressure transducer with 4 ÷ 20 mA current output signal, instead of the standard 0 ÷ 10Vbc .Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vbc or ±20 mA.

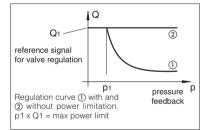
W = Only for valves coupled with pressure compensator type HC-011 or KC-011 (see tech table D150). It provides the hydraulic power limitation function. The driver receives the flow reference signal by the analog input INPUT+ and a pressure transducer, installed in the hydraulic system, has to be connected to the driver's analog input TR. When the actual requested hydraulic power **pxQ** (TR x INPUT+) reaches the max power limit (p1xQ1), internally set by software, the driver automatically reduces the flow regulation of the valve. The higher is the pressure feedback the lower is the valve's regulated flow:

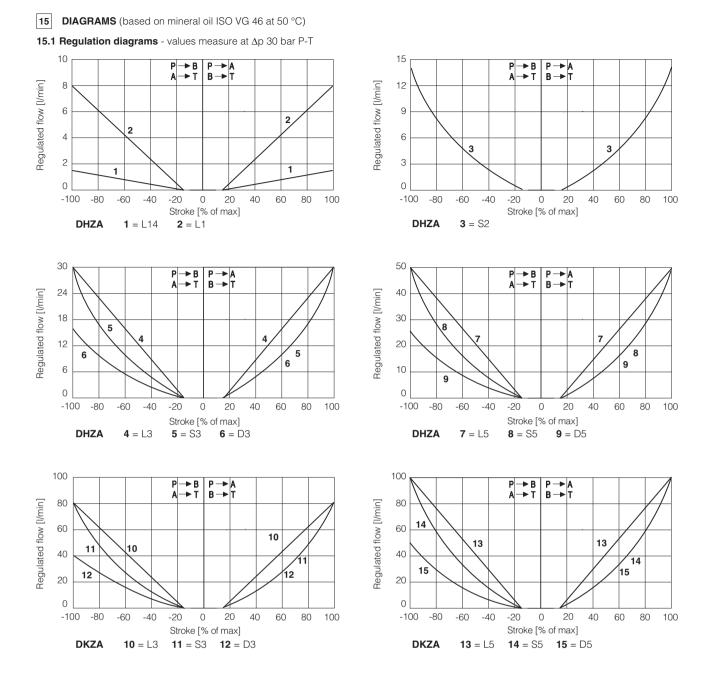
> Flow regulation = Min (PowerLimit [sw setting] Transducer Pressure [TR] ; Flow Reference [INPUT+])

14 POSSIBLE COMBINED OPTIONS

/BI, /BW, /BY, /IW, /IY, /WY, /BIW, /BIY, /BWY, /IWY, /CWB, /CWY, /BIWY, /CWBY







16 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

16.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

16.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics. USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

16.3 Flow reference input signal (INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDc.

16.4 Monitor output signals (MONITOR and MONITOR2)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, default settings is ±5 VDC (1V = 1A).

Output signal can be reconfigured via software, within a maximum range of ±5 VDC.

Option /W

The driver generates a second analog output signal (MONITOR2) proportional to the actual system pressure.

The output maximum range is ± 5 VDC; default setting is 0 \div 5 VDC

16.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 Vbc on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

16.6 Fault output signal (FAULT)

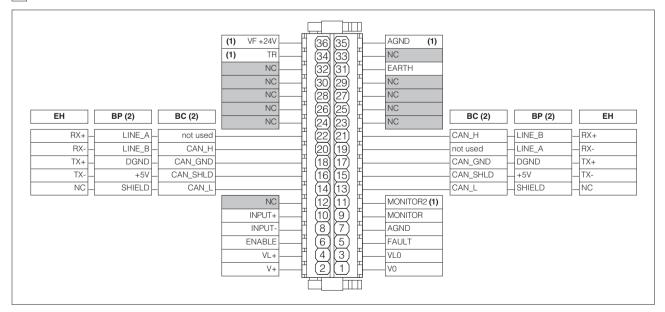
Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

16.7 Remote Pressure Transducer Input signal (TR) - only for /W option

Analog pressure transducers can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDc for standard and $4 \div 20$ mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ±20 mA. Note: transducer feedback can be read as a digital information through fieldbus communication - software selectable.

17 TERMINAL BOARD OVERVIEW



(1) Connections available only for /W option

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

18 ELECTRONIC CONNECTIONS

18.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 Vbc	Input - power supply
	3	VL0	Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
	9	MONITOR	Monitor output signal: ±5 Vpc maximum range, referred to AGND Default is: ±5 Vpc	Output - analog signal Software selectable
	10	INPUT+	Reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	11	MONITOR2	2nd monitor output signal: ±5 Vpc maximum range, referred to AGND (1) Default is: 0 ÷ 5 Vpc	Output - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

(1) 2nd monitor output signal is available only for /W option

18.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply		
	2	ID	Identification	5	
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -		
	5	D+	Data line +	(female)	

CABLE ENTRANCE

C2

18.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
()1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) pin 19 and 22 can be fed with external +5V supply of CAN interface

18.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
()1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

18.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
· ·	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	13	SHIELD		
	15	+5V	Power supply	
C2	17	DGND	Data line and termination signal zero	
	19	LINE_A	Bus line (high)	
	21	LINE B	Bus line (low)	

SIGNAL

CAN L

CAN_GND

not used

CAN_H

CAN_SHLD Shield

TECHNICAL SPECIFICATIONS

Bus line (low)

Bus line (high)

Signal zero data line

Pass-through connection (1)

PIN

13

15

17

19

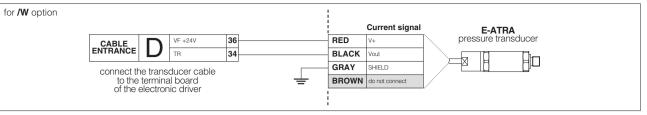
21

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

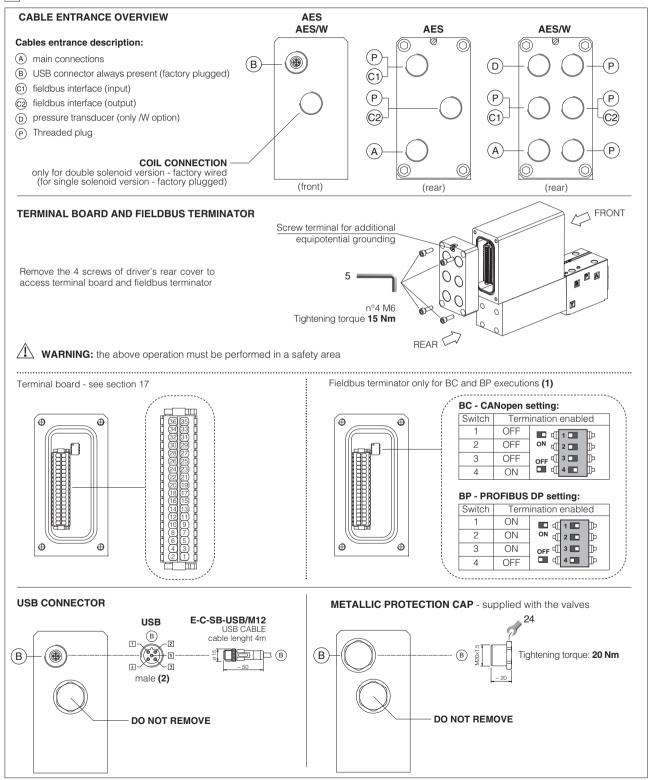
18.6 Remote pressure transducer connector - only for /W option

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	Voltage	Current
	34 TR		Signal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect
	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/
	36 VF +24V		Power supply +24Vbc	Output - power supply	Connect	Connect

E-ATRA remote pressure transducer connection - see tech table GX800



19 CONNECTIONS LAYOUT



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

19.1 Cable glands and threaded plug for AES - see tech table KX800

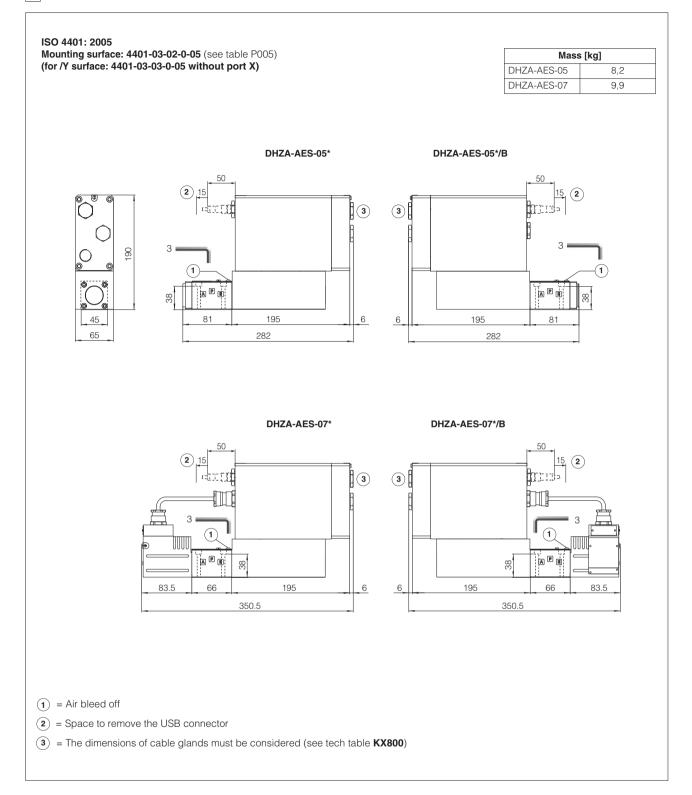
Communication	То	be ordere	ed separat	ely	Cable entrance		
interfaces		gland		ed plug	overview	Notes	
	quantity	entrance	quantity	entrance			
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers	
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

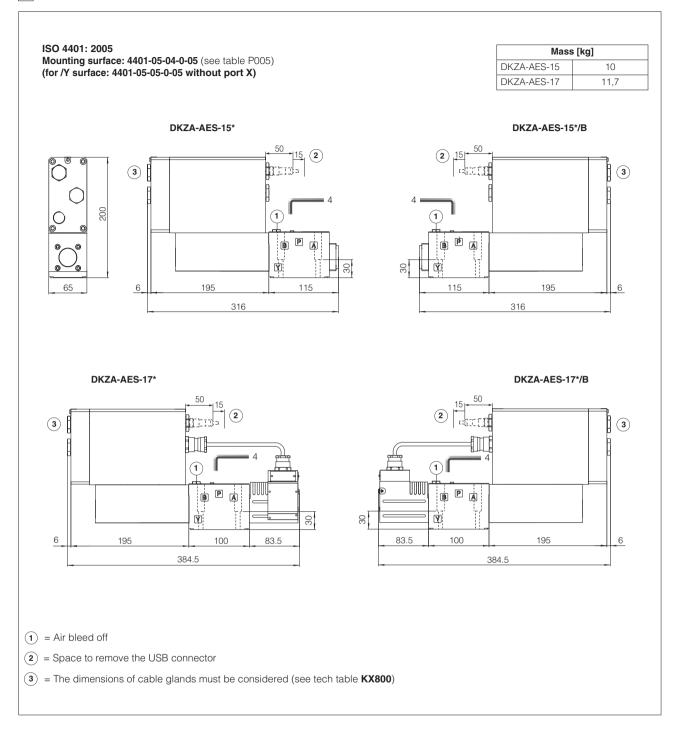
19.2 Cable glands and threaded plug for AES with /W option - see tech table KX800

	То	be ordere	ed separat	ely	Cable entrance	
Communication interfaces		gland entrance		ed plug entrance	overview	Notes
NP	2	D	none	none		Cable entrance P are factory plugged Cable entrance A, D are open for costumers
BC, BP, EH "via stub" connection	3	D C1 A	1	C2		Cable entrance P are factory plugged Cable entrance A, C1, C2, D are open for costumers
BC, BP, EH "daisy chain" connection	4	D C1 - C2 A	none	none		Cable entrance P are factory plugged Cable entrance A, C1, C2, D are open for costumers

20 FASTENING BOLTS AND SEALS

	DHZA	DKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø 7,5 mm (max) 1 OR 2025 Diameter of port Y: Ø = 3,2 mm (only for /Y option)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max) 1 OR 108 Diameter of port Y: Ø = 5 mm (only for /Y option)





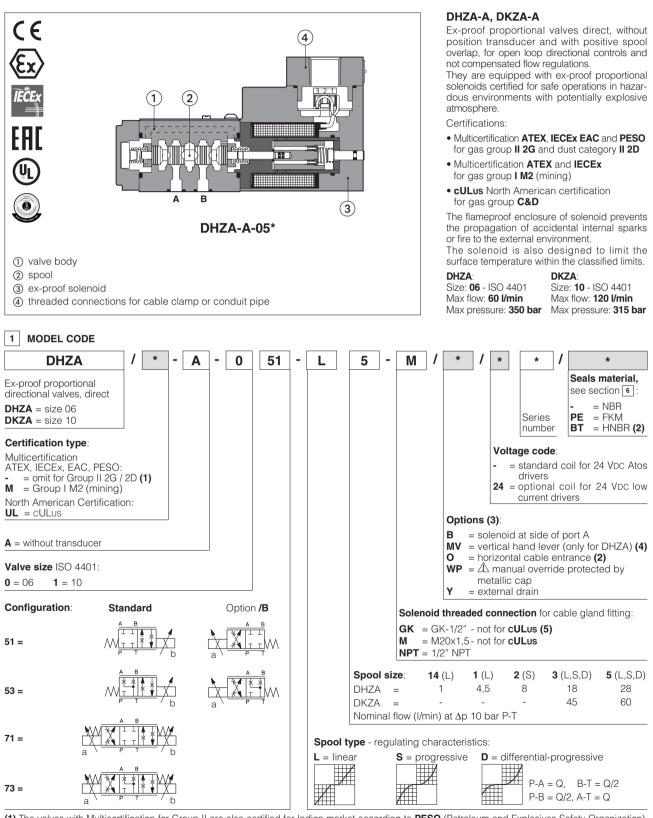
23 RELATED DOCUMENTATION

X010 X020 FX900 GS500 GS510	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO Operating and manintenance informationfor ex-proof proportional valves Programming tools Fieldbus	GX800 KX800 P005	Ex-proof pressure transducer type E-ATRA-7 Cable glands for ex-proof valves Mounting surfaces for electrohydraulic valves
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atos°A

Ex-proof proportional directional valves

direct, without transducer and with positive spool overlap - ATEX, IECEx, EAC, PESO or cULus



(1) The valves with Multicertification for Group II are also certified for Indian market according to PESO (Petroleum and Explosives Safety Organization). The PESO certificate can be downloaded from

(2) Not for multicertification M group I (mining)
 (3) Possible combined options: all combination are available, with exception of MV + WP
 (4) MV option is available only for DHZA with spool type S3, S5, D3, D5, L3, L5, not available in combination with WP option
 (5) Approved only for italian market

The pressure at T port makes difficult the manual override operation that can be possible only if its value is lower than 50 bar

2 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-AS-* /A	E-BM-AES-* /A
Туре	digital	digital
Format	DIN-ra	il panel
Data sheet	G030	GS050

3 GENERAL CHARACTERISTICS

Assembly position	Any position			
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100			
MTTFd valves according to EN ISO 13849	50 years, see technical table P007			
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$			
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$			
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200h			
Compliance	Explosion proof protection, see section 7 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"			
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006			

4 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve mo	odel		DHZA					DKZA		
Pressure	ure limits [bar] ports P , A , B = 350; T = 210 (250 with external drain /Y); Y = 10			ports P, A, B = 315; T = 210 (250 with external drain /Y); Y = 1						
Configura	ation			51, 53	, 71, 73		70	51, 53	, 71, 73	70
Spool typ	се	L14	L1	S2	L3,S3,D3	L5,S5,D5	L5	L3,S3,D3	L5,S5,D5	L3,L5,D5
Nominal	flow [l/min]									
	Δp = 10 bar	1	4,5	8	18	2	8	45	6	60
∆р Р-Т	$\Delta p = 30 \text{ bar}$	1,7	8	14	30	50		80	100	
Max per	rmissible flow	2,6	12	21	40	6	0	90	1:	20
Δp max l	P-T [bar]	70	70	70	50	5	0	40	4	10
Response	e time (1) [ms]				≤ 35				≤ 45	
Leakage	[cm³/min]		<30 (at	p = 100	bar); <135	(at p = 350	bar)	<80 (at p =	100 bar); <600 (at	p = 315 bar)
Hysteres	sis	≤ 5 [% of max regulation]								
Repeatal	bility	± 1 [% of max regulation]								

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 3

(1) 0-100% step signal

5 ELECTRICAL CHARACTERISTICS

Max. power		35W		
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account		
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved			
Duty factor	Continuous rating (ED=100%)	Continuous rating (ED=100%)		
Voltage code	standard	option /24		
Coil resistance R at 20°C	3,2 Ω	17,6 Ω		
Max. solenoid current	2,5 A	1,1 A		

6 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature		NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid normal operation		ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water (1)		NBR, HNBR	HFC	100 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

7 CERTIFICATION DATA

Valve type	DHZA	, DKZA	DHZA /M , DKZA /M	DHZA /UL	, DKZA /UL
Certifications	Multicertification Group II ATEX IECEX EAC PESO		Multicertification Group I ATEX IECEx		merican Lus
Solenoid certified code	OZ	A-A	OZAM-A	OZA	-A/EC
Type examination certificate (1)	ATEX: CESI 02 IECEx: IECEx C EAC: TC RU C- PESO: P33813	ES 10.0010x IT. 08.B.01784	ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324	- E366100
Method of protection	ATEX, EAC Ex II 2G Ex d I Ex II 2D Ex tb IIIC	IC T4/T3 Gb T135°C/T200°C Db	ATEX Ex M2 Ex db Mb IECEx	• UL 1203 Class I, Div.I, C Class I, Zone I,	Groups C & D , Groups IIA & IIE
	• IECEx Ex d IIC T4/T3		Ex db I Mb		
	• PESO Ex II 2G Ex d I	IC T4/T3 Gb			
Temperature class	T4	Т3	-	T4	Т3
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135 °C	≤ 200 °C
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C
Applicable standards	EN 60079-0 EN 60079-1 EN 60079-31		IEC 60079-0 IEC 60079-1 IEC 60079-31	CSA 22	and UL429, 2.2 n°30 2 n°139-13
Cable entrance: threaded connection vertical (standard) or horizontal (option /O)		$\mathbf{M} = \mathbf{M}$	GK-1/2" 20x1,5 : 1/2" NPT	1/2"	NPT

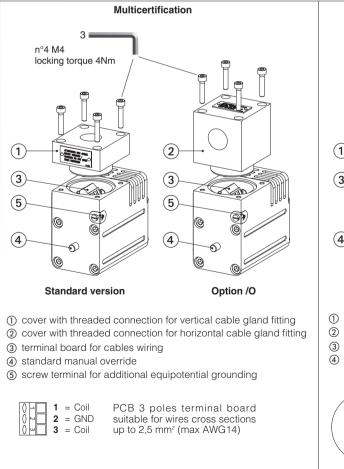
(1) The type examinator certificates can be downloaded from

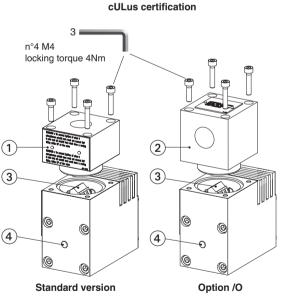
(2) The solenoids Group II and cULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

8 EX PROOF SOLENOIDS WIRING





① cover with threaded connection for vertical cable gland fitting

- (2) cover with threaded connection for horizontal cable gland fitting
- ③ terminal board for cables wiring
- (4) standard manual override

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Pay attention to respect the polarity

 1 = Coil + PCB 3 poles terminal board suggested cable section up to 1,5 mm²
 3 = Coil - (max AWG16), see section 9 note 1

alternative GND screw terminal connected to solenoid housing

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper Conductors
- Bronze braided armor
- · Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C)

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

9.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Multicertification

Max ambient temperature [°C]	Temperature class		Max surface te	mperature [°C]	Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	135 °C	90 °C	90 °C
45 °C	-	T4	-	135 °C	-	95 °C
55 °C	-	T3	-	200 °C	-	110 °C
60 °C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	T3	N.A.	200 °C	N.A.	120 °C

cULus certification

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature
55 °C	Τ4	135 °C	100 °C
70 °C	ТЗ	200 °C	100 °C

10 CABLE GLANDS - only Multicertification

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

11 OPTIONS

- **B** = Solenoid at side of port A of the main stage
- **MV** = Auxiliary vertical hand levers (only for DHZA)

This option allows to operate the valves in absence of electrical power supply, i.e. during commissioning, maintenance or in case of emergency.

When the valve is electrically operated the hand lever remains stopped in its rest position

The hand lever execution does not affect the performances of the original valves

Total angle stroke	[°deg]	± 28°	Lever actuating force	[N]	1 ÷ 8
Working angle stroke	[°deg]	± 15°	Lever device weight	[g]	880

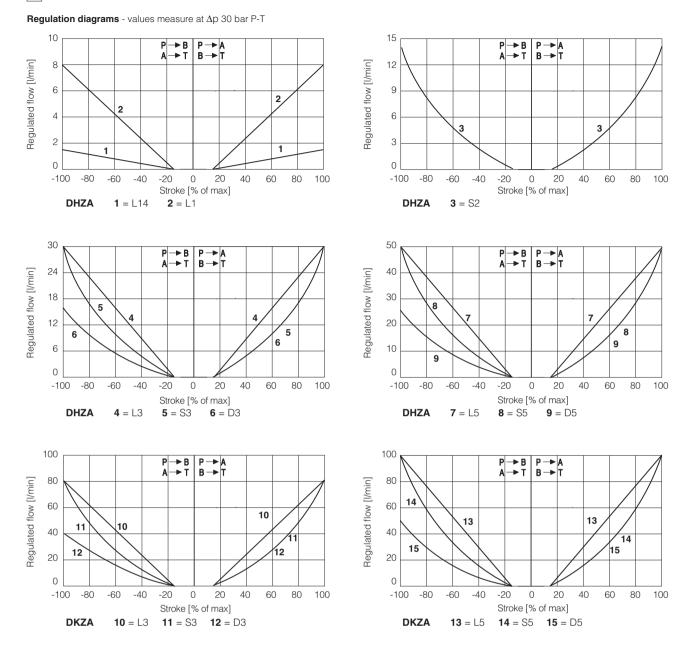
O = Horizontal cable entrance, to be selected in case of limited vertical space

WP = Manual override protect by metallic cap.

Y = External drain, to be selected if the pressure at T port is higher than the max allowed limits

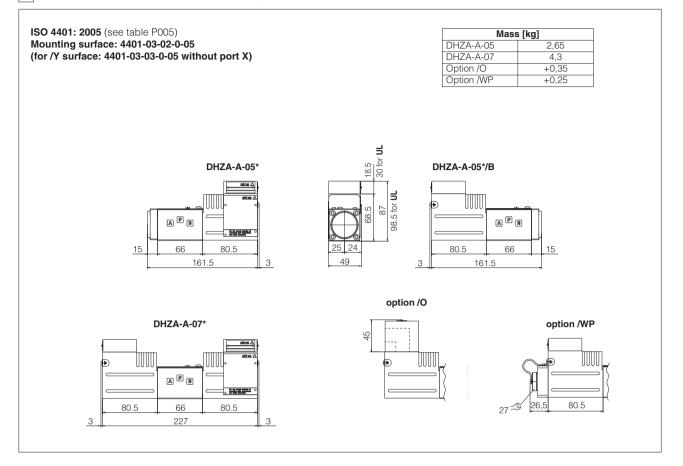
11.1 Possible combined options: all combination are available



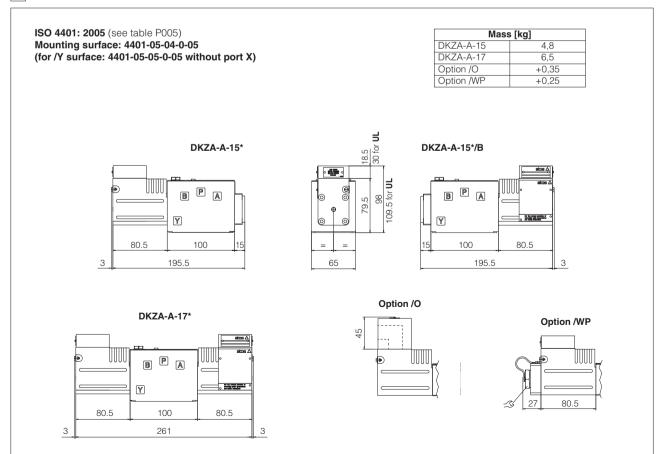


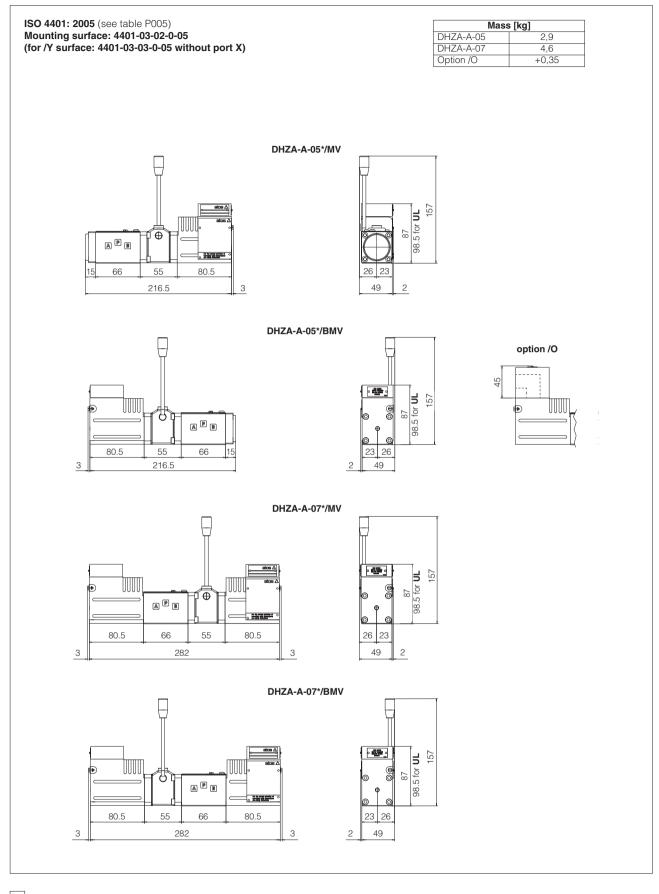
13 FASTENING BOLTS AND SEALS

	DHZA	DKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports P, A, B, T: Ø 7,5 mm (max) 1 OR 2025 Diameter of port Y: Ø = 3,2 mm (only for /Y option)	Seals: 5 OR 2050; Diameter of ports P, A, B, T: Ø 11,5 mm (max) 1 OR 108 Diameter of port Y: Ø = 5 mm (only for /Y option)



15 INSTALLATION DIMENSIONS FOR DKZA [mm]





17 RELATED DOCUMENTATION

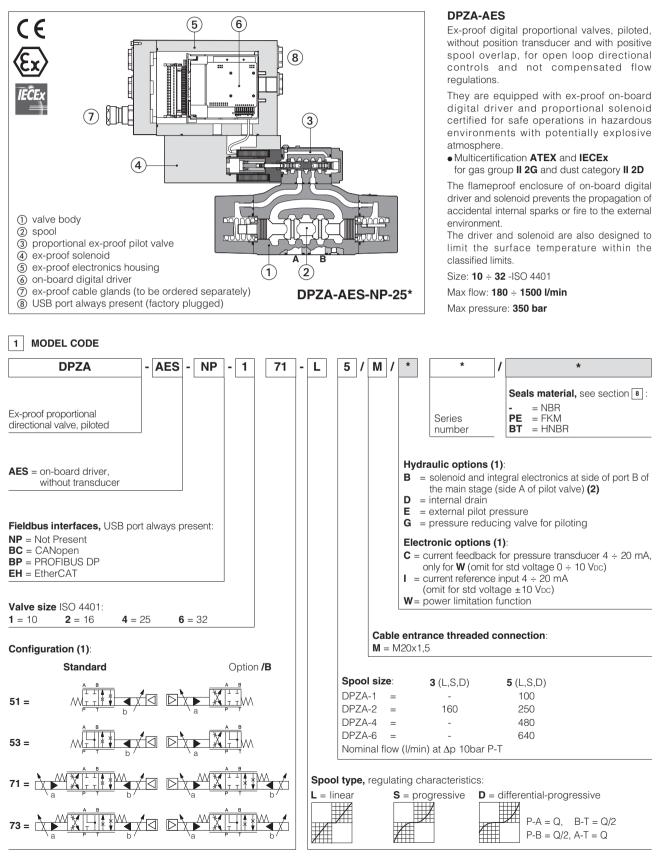
X010	Basics for electrohydraulics in hazardous environments
X020	Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO
X030	Summary of Atos ex-proof components certified to cULus
FX900	Operating and manintenance information for ex-proof proportional valves
KX800	Cable glands for ex-proof valves
P005	Mounting surfaces for electrohydraulic valves

Table FX210-2/E

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Ex-proof digital proportional directional valves

Piloted, with on-board driver, without position transducer and with positive spool overlap ATEX and IECEx



(1) For possible combined options, see section 14

(2) In standard configuration the solenoid (config. 51 and 53) and the on-board digital driver are at side A of the main stage (side B of pilot valve)

2 GENERAL NOTES

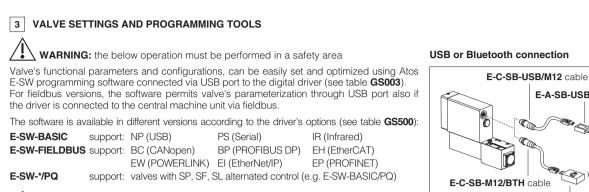
Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table FX900 and in the user manuals included in the E-SW-* programming software.

E-A-SB-USB/OPT isolator

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E-A-SB-USB/BTH adapter



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 GENERAL CHARACTERISTICS

Assembly position	Any position			
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100			
MTTFd valves according to EN ISO 13849	75 years, see technical table P007			
Ambient temperature range	Standard = -20° C \div $+60^{\circ}$ C /PE option = -20° C \div $+60^{\circ}$ C /BT option = -40° C \div $+60^{\circ}$ C			
Storage temperature range	Standard = -20° C \div $+70^{\circ}$ C /PE option = -20° C \div $+70^{\circ}$ C /BT option = -40° C \div $+70^{\circ}$ C			
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h			
Compliance	Explosion proof protection, see section 9 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"			
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006			

6	HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C
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Valve model		DPZA-*-1	DPZ	'A-*-2	DPZA-*-4	DPZA-*-6
Pressure limits	[bar]	ports P , A , B , X = 350; T = 250 (10 for option /D); Y = 10;				
Spool type		L5, S5, D5	L3, S3, D3		L5, S5, D5	
Nominal flow [I/min]			·		
	$\Delta p = 10 \text{ bar}$	100	160	250	480	640
Δp P-T	$\Delta p = 30 \text{ bar}$	160	270	430	830	1100
	max permissible flow	180	400	550	900	1500
∆p max P-T	[bar]	50	60	60	60	60
Piloting pressure	[bar]	min. =	25; max = 350 (o	ption /G advisable f	or pilot pressure > 1	50 bar)
Piloting volume	[cm ³]	1,4	3	,7	9,0	21,6
Piloting flow (1)	[l/min]	1,7	3	3,7	6,8	14,4
Leakage (2)	Main stage [l/min]	0,15/0,5	0,2	2/0,6	0,3/1,0	1,0/3,0
Response time (1) [ms]		≤ 90 ≤ 110 ≤ 130 ≤ 15			≤ 190	
Hysteresis		≤ 5 [% of max regulation]				
Repeatability			±	1 [% of max regulat	ion]	

(1) 0 ÷100 % step signal and pilot pressure 100 bar

(2) at p = 100/350 bar

7 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)					
Max power consumption	35 W	35 W				
Analog input signals		Voltage: range ±10 VDC (24 VMAX tollerant) Input impedance: Ri > 50 kΩ Current: range ±20 mA Input impedance: Ri = 500 Ω				
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards		
Monitor outputs	Voltage: maximum ra	nge ± 5 Voc @ max	5 mA			
Enable input	Range: 0 ÷ 9 VDC (OFF	state), 15 ÷ 24 VDC (ON	state), 9 ÷ 15 VDC (not ac	cepted); Input impedance: Ri > $87k\Omega$		
Fault output	Output range : 0 ÷ 24 external negative volta	Output range : $0 \div 24$ VDC (ON state \cong VL+ [logic power supply] ; OFF state \cong 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)				
Pressure transducer power supply (only /W option)	+24VDC @ max 100 r	+24Vbc @ max 100 mA (E-ATRA-7 see tech table GX800)				
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, current control monitoring, power supplies level, pressure transducer failure (/W option)					
Protection degree to DIN EN60529	IP66/67 with relevant	cable gland				
Duty factor	Continuous rating (ED	=100%)				
Tropicalization	Tropical coating on el	ectronics PCB				
Additional characteristics	Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply					
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)					
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT EC 61158		
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX		

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

8 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	I temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$			
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	Max fluid normal operation		ISO4406 class 18/16/13 NAS1638 class 7		
contamination level longer life		ISO4406 class 16/14/11 NAS1	catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM	HFDU, HFDR	- ISO 12922	
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922	

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

9 CERTIFICATION DATA

Valve type		DPZA					
Certifications				Multicertifica	tion Group II		
				ATEX	IECEx		
Solenoid certified co	ode			OZA	AES		
Type examination co	ertificate (1)	• ATEX: TUV I	T 18 ATEX 068 X	(IECEX: IEC	Ex TPS 19.0004X	
Method of protection		ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C Db					
	Single solenoid valve	Т6	-	TS	5	T4	-
Temperature class	Double solenoid valve	-	T4	-		-	Т3
Surface temperature	e	≤ 85 °C	≤ 135 °C	≤ 100	O° (≤ 135 °C	≤ 200 °C
Ambient temperature (2)		-40 ÷ +40 °C		-40 ÷ +55 °C -40 ÷ +70 °C		-70 °C	
Applicable Standards		EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079-31 EN 60079-1 IEC 60079-1				31	
Cable entrance: thre	eaded connection	M = M20x1,5					

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

10.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	Т6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

11 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

12 HYDRAULIC OPTIONS

- B = DPZA-*-*5 = solenoid and integral electronics at side of port B of the main stage.
 DPZA-*-*7 = integral electronics at side of port B of the main stage.
- D and E = Pilot and drain configuration can be modified as shown in section 13.
 The valve's standard configuration provides internal pilot and external drain.
 For different pilot / drain configuration select:
 - Option /D Internal drain.
 - Option /E External pilot (through port X).

G = Pressure reducing valve installed between pilot valve and main body with fixed setting: DPZA-1 and -2 = 28 bar

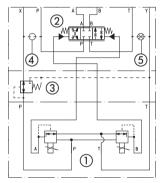
DPZA-4 and -6 = 40 bar

It is advisable for valves with internal pilot in case of system pressure higher than 150 bar.

FUNCTIONAL SCHEME

example of configuration 7*





Pilot valve
 Main stage

③ Pressure reducing valve

④ Plug to be added for external pilot trough port X

(5) Plug to be removed for internal drain through port T

13 ELECTRONIC OPTIONS

I = It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

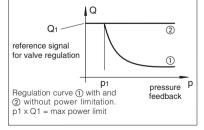
C = Only in combination with option /W

It is available to connect pressure transducer with $4 \div 20$ mA current output signal, instead of the standard $0 \div 10$ VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.

W = Only for valves coupled with pressure compensator type HC-011 or KC-011 (see tech table D150). It provides the hydraulic power limitation function. The driver receives the flow reference signal by the analog input INPUT+ and a pressure transducer, installed in the hydraulic system, has to be connected to the driver's analog input TR. When the actual requested hydraulic power pxQ (TR x INPUT+) reaches the max power limit (p1xQ1), internally set by software, the driver automatically reduces the flow regulation of the valve. The higher is the pressure feedback the lower is the valve's regulated flow:

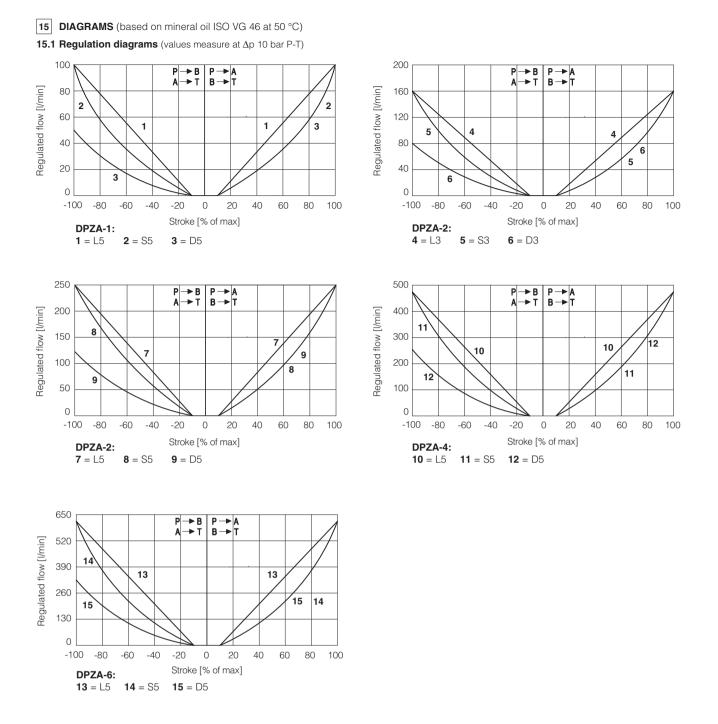
> Flow regulation = Min (<u>PowerLimit [sw setting]</u> Transducer Pressure [TR]; Flow Reference [INPUT+])





14 POSSIBLE COMBINED OPTIONS

Hydraulic options: all combination possible Electronics options: /IW, /CW, /CWI



Note: Hydraulic configuration vs. reference signal for configuration 71 and 73 (standard and option /B)

 $\begin{array}{ccc} \text{Reference signal} & 0 & \div & +10 \text{ V} \\ 12 & \div & 20 \text{ mA} \end{array} \Big\} \text{ P} \rightarrow \text{A} \text{ / B} \rightarrow \text{T} \\ \end{array} \\ \begin{array}{cccc} \text{Reference signal} & 0 & \div & -10 \text{ V} \\ 12 & \div & 4 \text{ mA} \end{array} \Big\} \text{ P} \rightarrow \text{B} \text{ / A} \rightarrow \text{T} \\ \end{array}$

16 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

16.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

16.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics. USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

16.3 Flow reference input signal (INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDc.

16.4 Monitor output signals (MONITOR and MONITOR2)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, default settings is ±5 VDc (1V = 1A).

Output signal can be reconfigured via software, within a maximum range of ±5 VDC.

Option /W

The driver generates a second analog output signal (MONITOR2) proportional to the actual system pressure.

The output maximum range is ±5 VDC; default setting is 0 ÷ 5 VDC

16.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

16.6 Fault output signal (FAULT)

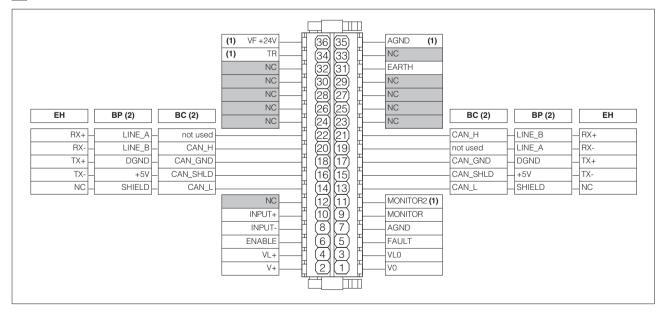
Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

16.7 Remote Pressure Transducer Input signal (TR) - only for /W option

Analog pressure transducers can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDc for standard and $4 \div 20$ mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA. Note: transducer feedback can be read as a digital information through fieldbus communication - software selectable.

17 TERMINAL BOARD OVERVIEW



(1) Connections available only for /W option

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

18 ELECTRONIC CONNECTIONS

18.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	
	1	V0	Power supply 0 Vbc	Gnd - power supply	
	2	V+	Power supply 24 VDC	Input - power supply	
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply	
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply	
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal	
	6	ENABLE	Enable (24 V_{DC}) or disable (0 V_{DC}) the driver, referred to VL0	Input - on/off signal	
	7	AGND	Analog ground	Gnd - analog signal	
/ \	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal	
	9	MONITOR	Monitor output signal: ±5 Vpc maximum range, referred to AGND Default is: ±5 Vpc	Output - analog signal Software selectable	
	10	INPUT+	IT+ Reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option		
	11	MONITOR2	TOR2 2nd monitor output signal: ±5 Vbc maximum range, referred to AGND (1) Output Default is: 0 ÷ 5 Vbc Software Software		
	31	EARTH	ternally connected to driver housing		

(1) 2nd monitor output signal is available only for /W option

18.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply		
	2	ID	Identification		
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -		
	5	D+	Data line +	(female)	

CABLE ENTRANCE

C2

PIN

13

15

17

19

21

SIGNAL

CAN L

CAN_SHLD

CAN_GND

not used

CAN_H

TECHNICAL SPECIFICATIONS

Bus line (low)

Bus line (high)

Signal zero data line

Pass-through connection (1)

Shield

18.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
C1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) pin 19 and 22 can be fed with external +5V supply of CAN interface

18.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

18.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
(C1)	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

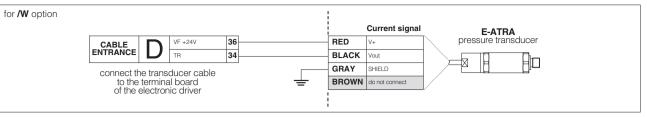
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	TX-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

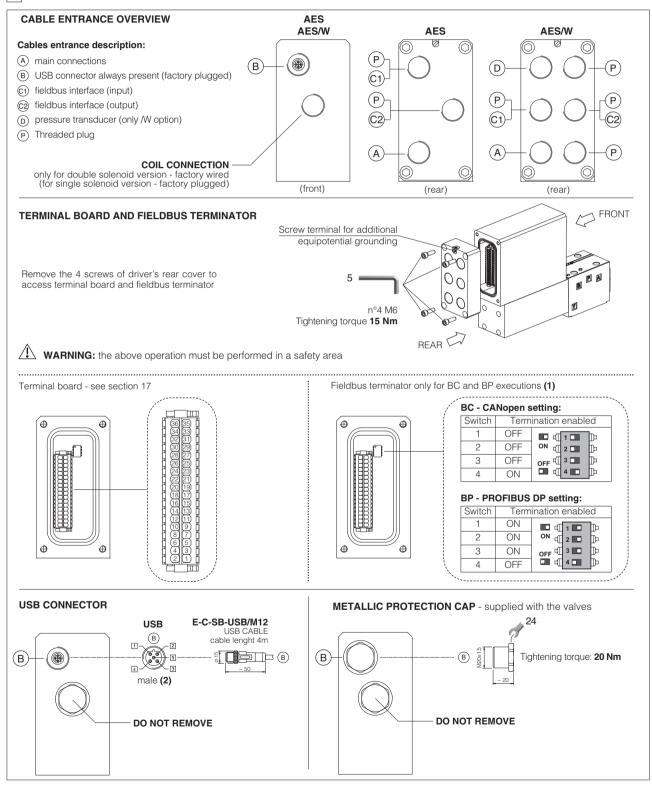
17.6 Remote pressure transducer connector - only for /W option

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	Voltage	Current
	34	TR	Signal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect
	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/
	36	VF +24V	Power supply +24VDC	Output - power supply	Connect	Connect

E-ATRA remote pressure transducer connection - see tech table GX800



19 CONNECTIONS LAYOUT



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

19.1 Cable glands and threaded plug for AES - see tech table KX800 $\,$

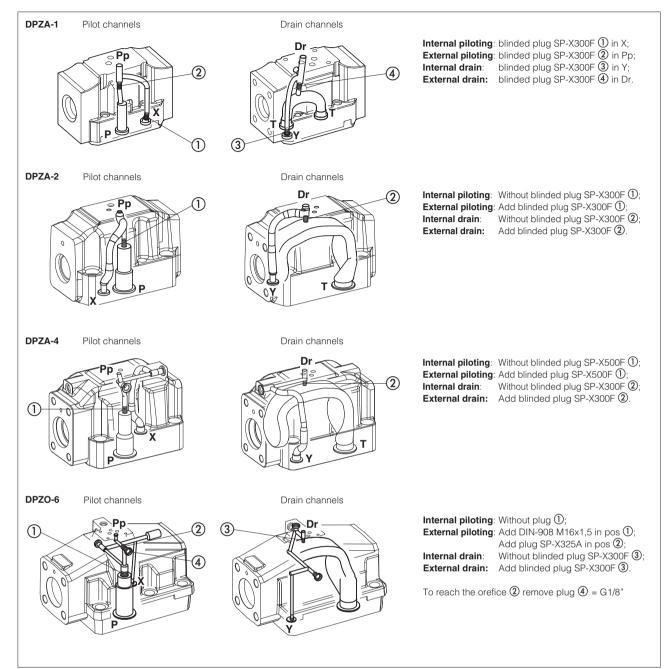
Communication	To be ordered separately			ely	Cable entrance		
interfaces		gland		ed plug	overview	Notes	
	quantity	entrance	quantity	entrance			
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers	
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

19.2 Cable glands and threaded plug for AES with /W option - see tech table KX800

	То	be ordere	ed separat	ely	Cable entrance	
Communication interfaces		gland entrance	Threaded plug		overview	Notes
NP	2	D	none	none		Cable entrance P are factory plugged Cable entrance A, D are open for costumers
BC, BP, EH "via stub" connection	3	D C1 A	1	C2		Cable entrance P are factory plugged Cable entrance A, C1, C2, D are open for costumers
BC, BP, EH "daisy chain" connection	4	D C1 - C2 A	none	none		Cable entrance P are factory plugged Cable entrance A, C1, C2, D are open for costumers

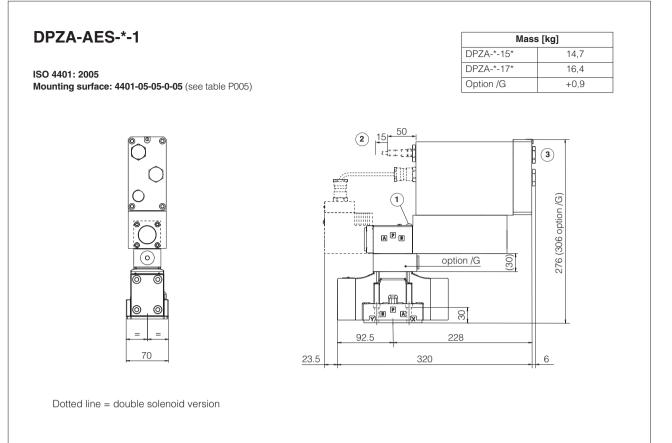
20 PLUGS LOCATION FOR PILOT/DRAIN CHANNELS

Depending on the position of internal plugs, different pilot/drain configurations can be obtained as shown below. To modify the pilot/drain configuration, proper plugs must only be interchanged. The plugs have to be sealed using loctite 270. Standard valves configuration provides internal pilot and external drain



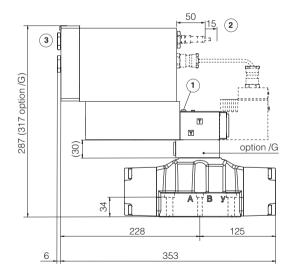
21 FASTENING BOLTS AND SEALS

Туре	Size	Fastening bolts	Seals
	1 = 10	4 socket head screws M6x40 class 12.9	5 OR 2050; Diameter of ports A, B, P, T: Ø 11 mm (max)
	1 = 10		2 OR 108 Diameter of ports X, Y: $\emptyset = 5 \text{ mm} (\text{max})$
	2 = 16	4 socket head screws M10x50 class 12.9 Tightening torque = 70 Nm	4 OR 130; Diameter of ports A, B, P, T: Ø 20 mm (max)
DPZA	2 = 10	2 socket head screws M6x45 class 12.9 Tightening torque = 15 Nm	2 OR 2043 Diameter of ports X, Y: $\emptyset = 7 \text{ mm} (\text{max})$
DFZA	4 = 25	6 socket head screws M12x60 class 12.9	4 OR 4112; Diameter of ports A, B, P, T: Ø 24 mm (max)
4 = 23	Tightening torque = 125 Nm	2 OR 3056 Diameter of ports X, Y: $\emptyset = 7 \text{ mm} (\text{max})$	
	6 = 32	6 socket head screws M20x90 class 12.9	4 OR 144; Diameter of ports A, B, P, T: Ø 34 mm (max)
0	U = 32	Tightening torque = 600 Nm	2 OR 3056 Diameter of ports X, Y: \emptyset = 7 mm (max)



DPZA-AES-*-2

ISO 4401: 2005 Mounting surface: 4401-07-07-0-05 (see table P005)



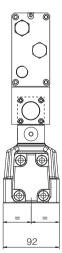
Dotted line = double solenoid version

 \bigcirc = Air bleed off

 $(\mathbf{2})$ = Space to remove the USB connector

 $(\hat{\mathbf{3}})$ = The dimensions of cable glands must be considered (see tech table **KX800**)

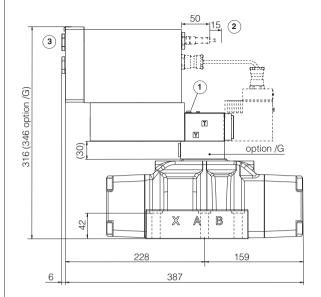
Mass [kg]						
DPZA-*-25*	18,9					
DPZA-*-27*	20,6					
Option /G	+0,9					



DPZA-AES-*-4

ISO 4401: 2005

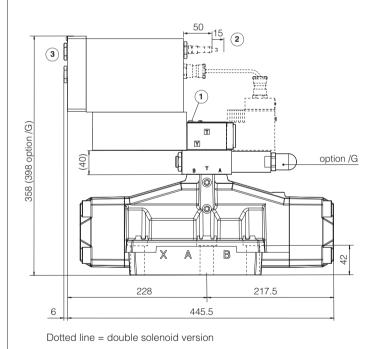
Mounting surface: 4401-08-08-0-05 (see table P005)



Dotted line = double solenoid version

DPZA-AES-*-6

ISO 4401: 2005 Mounting surface: 4401-10-09-0-05



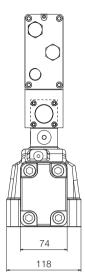
 $(\mathbf{1})$ = Air bleed off

 $\overline{(\mathbf{2})}$ = Space to remove the USB connector

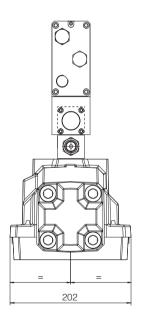


23 RELATED DOCUMENTATION

Mass [kg]					
DPZA-*-45*	24,1				
DPZA-*-47*	25,8				
Option /G	+0,9				



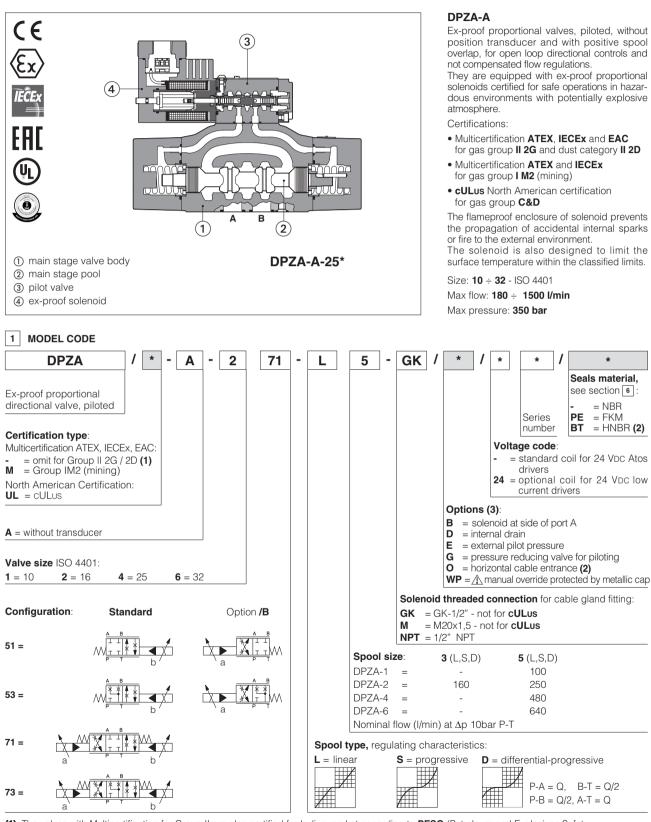
Mass [kg]						
DPZA-*-65*	49,2					
DPZA-*-67*	50,9					
Option /G	+0,9					



atos

Ex-proof proportional directional valves

piloted, without transducer and with positive spool overlap - ATEX, IECEx, EAC, PESO or cULus



(1) The valves with Multicertification for Group II are also certified for Indian market according to **PESO** (Petroleum and Explosives Safety Organization). The PESO certificate can be downloaded from

(2) Not for multicertification M group I (mining) (3) For possible combined options, see 11.1

AFor valve with internal drain (option /D) the pressure at T port makes difficult the manual override operation that can be possible only if the pressure at T port is lower than 50 bar.

2 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-AS-* /A	E-BM-AES-* /A		
Туре	digital	digital		
Format	DIN-rail panel			
Data sheet	G030	GS050		

3 GENERAL CHARACTERISTICS

Assembly position	Any position		
Subplate surface finishing to ISO 4401	.cceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100		
MTTFd valves according to EN ISO 13849	75 years, see technical table P007		
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$		
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$		
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200h		
Compliance	Explosion proof protection, see section 7 Flame proof enclosure "Ex d" Dust ignition protection by enclosure "Ex t"		
RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006			

4 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model	alve model		DPZ	ZA-*-2	DPZA-*-4	DPZA-*-6
Pressure limits	[bar]		ports P, A, B, X = 35	50; T = 250 (10 fo	r option /D); $\mathbf{Y} = 10$);
Spool type		L5, S5, D5	L3, S3, D3		L5, S5, D5	
Nominal flow	[l/min]					
	$\Delta p = 10 \text{ bar}$	100	160	250	480	640
Δp P-T	$\Delta p = 30 \text{ bar}$	160	270	430	830	1100
	Max permissible flow	180	400	550	900	1500
Δp max P-T	[bar]					
Piloting pressure	[bar]	min. =	25; max = 350 (o	ption /G advisable	for pilot pressure > 1	50 bar)
Piloting volume	[cm ³]	1,4	3	3,7	9,0	21,6
Piloting flow (1)	[l/min]	1,7	3	3,7	6,8	14,4
Leakage (2)	Main stage [l/min]	0,15/0,5	0,2	2/0,6	0,3/1,0	1,0/3,0
Response time (1)	[ms]	≤ 90	≤	110	≤ 130	≤ 190
Hysteresis			≤ :	5 [% of max regulat	ion]	
Repeatability			±	1 [% of max regulat	ion]	

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 2

(1) 0-100% step signal and pilot pressure 100 bar (2) at p = 100/350 bar

5 ELECTRICAL CHARACTERISTICS

Max. power	3!	35W		
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account		
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved			
Duty factor	Continuous rating (ED=100%)	Continuous rating (ED=100%)		
Voltage code	standard	option /24		
Coil resistance R at 20°C	3,2 Ω	17,6 Ω		
Max. solenoid current	2,5 A	1,1 A		

6 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$			
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 300 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1638 class 7 s		see also filter section at KTF	
contamination level	longer life	ISO4406 class 16/14/11 NAS1638 class 5 catalog		catalog	
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922	
Flame resistant with water (1)		NBR, HNBR	HFC	1 130 12922	

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

7 CERTIFICATION DATA

Valve type	DPZA		DPZA /M	DPZ	A/UL	
Certifications	Multicertification Group II ATEX IECEx EAC PESO		Multicertification Group I ATEX IECEx	North American cULus		
Solenoid certified code	OZA-A		OZAM-A	OZA	-A/EC	
Type examination certificate (1)	ATEX: CESI 02 ATEX 014 IECEX: IECEX CES 10.0010x EAC: TC RU C-IT. 08.B.01784 PESO: P338131		ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324	20170324 - E366100	
Method of protection	• ATEX , EAC		ATEX Ex M2 Ex db Mb IECEx	• UL 1203 Class I, Div.I, C Class I, Zone I,	Groups C & D Groups IIA & IIE	
	IECEx Ex d IIC T4/T3 Ex tb IIIC T135		Ex db I Mb			
	• PESO Ex II 2G Ex d I	IC T4/T3 Gb				
Temperature class	T4	Т3	-	T4	Т3	
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135 °C	≤ 200 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C	
Applicable standards	EN 60079-0 IEC 60079-0 EN 60079-1 IEC 60079-1 EN 60079-31 IEC 60079-31		N 60079-1 IEC 60079-1 CSA 22.2 n°30		2.2 n°30	
Cable entrance: threaded connection vertical (standard) or horizontal (option /O)	GK = GK-1/2" M = M20x1,5 NPT = 1/2" NPT			1/2"	NPT	

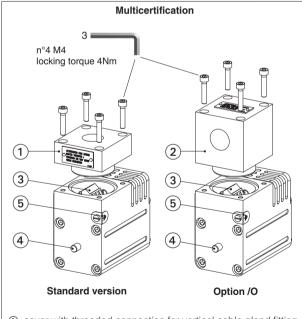
(1) The type examinator certificates can be downloaded from

(2) The solenoids Group II and cULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

8 EX PROOF SOLENOIDS WIRING

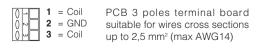


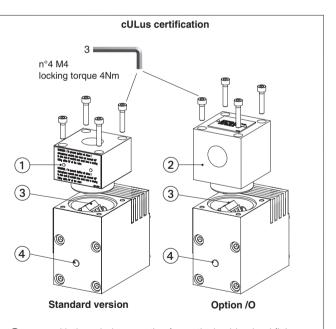
① cover with threaded connection for vertical cable gland fitting

- 2 cover with threaded connection for horizontal cable gland fitting
- ③ terminal board for cables wiring

(4) standard manual override

(5) screw terminal for additional equipotential grounding





① cover with threaded connection for vertical cable gland fitting

- 0 cover with threaded connection for horizontal cable gland fitting
- (\mathfrak{T}) terminal board for cables wiring
- (4) standard manual override



Pay attention to respect the polarity

1 = Coil +PCB 3 poles terminal board sugge-2 = GNDsted cable section up to 1,5 mm²3 = Coil -(max AWG16), see section 9 note 1

alternative GND screw terminal connected to solenoid housing

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper Conductors
- Bronze braided armor
- · Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C)

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

9.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products. **Multicertification**

Max ambient temperature [°C]	Temperature class		Max surface temperature [°C]		Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	-	90 °C	-
45 °C	-	T4	150 °C	135 °C	-	90 °C
55 °C	-	T3	150 °C	200 °C	-	110 °C
0° C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	T3	N.A.	200 °C	N.A.	120 °C

cULus certification

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature
55 °C	T4	135 °C	100 °C
70 °C	Т3	200 °C	100 °C

10 CABLE GLANDS - only Multicertification

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

11 OPTIONS

0

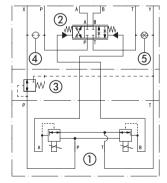
- B = DPZA-*-*5 = solenoid and integral electronics at side of port B of the main stage. DPZA-*-*7 = integral electronics at side of port B of the main stage.
- D and E = Pilot and drain configuration can be modified as shown in section 13. The valve's standard configuration provides internal pilot and external drain. For different pilot / drain configuration select:
 - Option /D Internal drain.
 - Option /E External pilot (through port X).
- G = Pressure reducing valve installed between pilot valve and main body with fixed setting: DPZA-1 and -2 = 28 bar
 DPZA-4 and -6 = 40 bar
 - It is advisable for valves with internal pilot in case of system pressure higher than 150 bar.
 - = Horizontal cable entrance, to be selected in case of limited verical space.
- WP = Manual override protected by metallic cap.

11.1 Possible combined options

/BD, /BE, /BG, /BO, /BWP /BDE, /BDG, /BDO, /BDWP, /BDEG, /BDEO, /BDEWP, /BDEGO, /BDEGWP, BDEGOWP /BEG, /BEO, /BEWP, /BEGO, /BEGWP, /BEGOWP /BGO, /BGWP, BGOWP /DE, /DG, /DO, /DWP, /DEG, /DEO, /DEWP, /DEGO, /DEGWP, /DEGOWP /EG, /EO, /EWP, /EGO, /EGWP, /EGOWP /GO, /GWP, /GOWP /OWP

FUNCTIONAL SCHEME

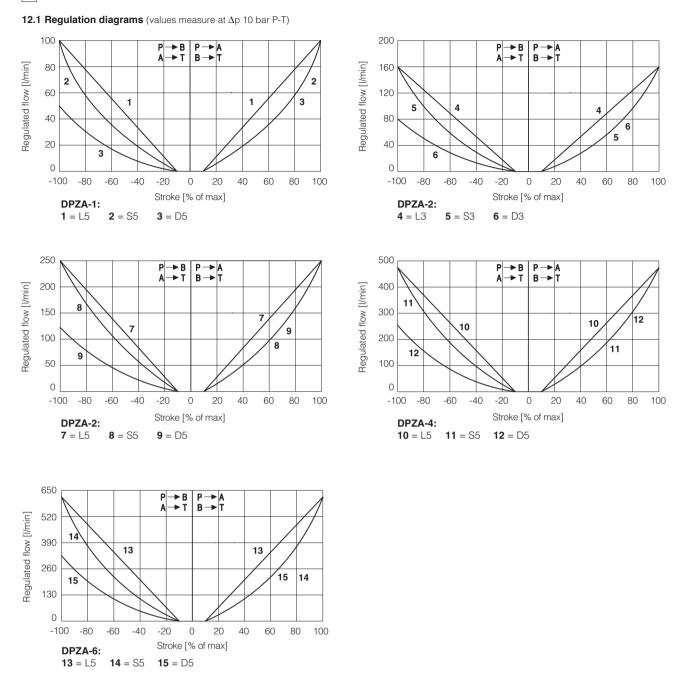
example of configuration 7* 3 positions, spring centered



Pilot valve
 Main stage

- ③ Pressure reducing valve④ Plug to be added for external pilot trough port X
- (5) Plug to be removed for internal drain through port T



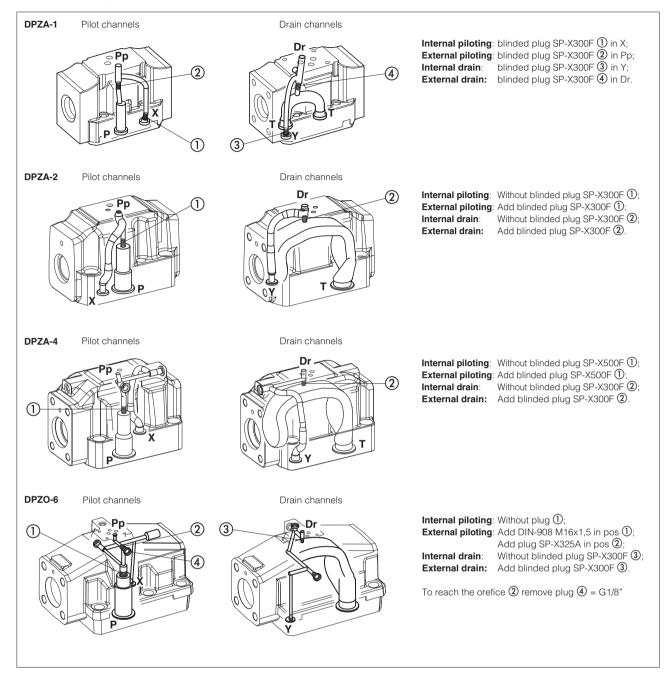


Note: Hydraulic configuration vs. reference signal for configuration 71 and 73 (standard and option /B)

 $\begin{array}{ccc} \text{Reference signal} & 0 & \div & +10 \text{ V} \\ 12 & \div & 20 \text{ mA} \end{array} \Big\} \text{ P} \rightarrow \text{A} \text{ / } \text{B} \rightarrow \text{T} \\ \end{array} \\ \begin{array}{cccc} \text{Reference signal} & 0 & \div & -10 \text{ V} \\ 12 & \div & 4 \text{ mA} \end{array} \Big\} \text{ P} \rightarrow \text{B} \text{ / } \text{A} \rightarrow \text{T} \\ \end{array}$

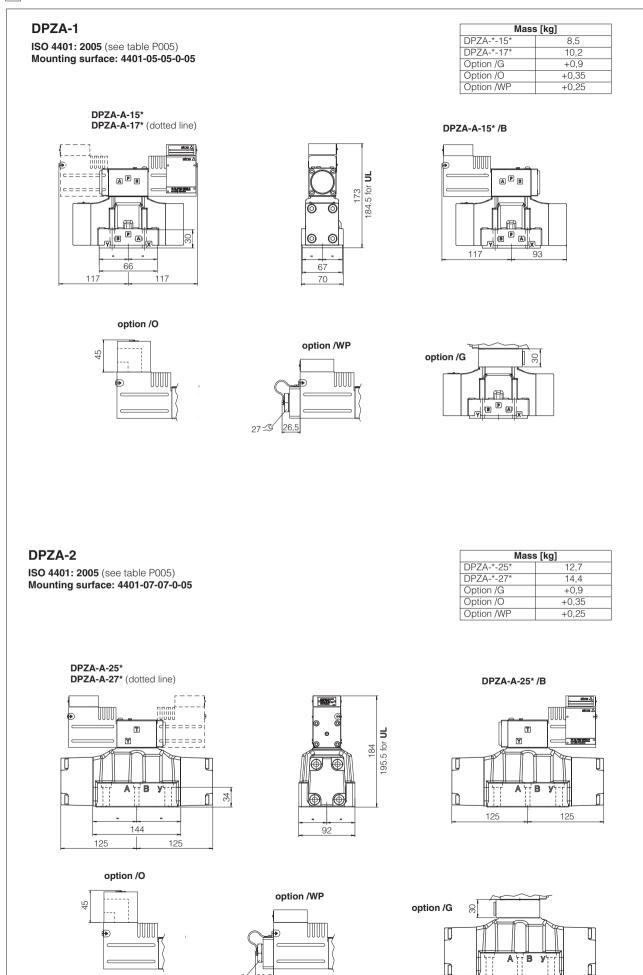
13 PLUGS LOCATION FOR PILOT/DRAIN CHANNELS

Depending on the position of internal plugs, different pilot/drain configurations can be obtained as shown below. To modify the pilot/drain configuration, proper plugs must only be interchanged. The plugs have to be sealed using loctite 270. Standard valves configuration provides internal pilot and external drain



14 FASTENING BOLTS AND SEALS

	DPZA-1	DPZA-2	DPZA-4	DPZA-6
	Fastening bolts:	Fastening bolts:	Fastening bolts:	Fastening bolts:
	4 socket head screws M6x60 class 12.9 Tightening torque = 15 Nm	4 socket head screws M10x50 class 12.9 Tightening torque = 70 Nm 2 socket head screws M6x45 class 12.9 Tightening torque = 15 Nm	6 socket head screws M12x60 class 12.9 Tightening torque = 125 Nm	6 socket head screws M20x90 class 12.9 Tightening torque = 600 Nm
	Seals:	Seals:	Seals:	Seals:
\cap	5 OR 2050 Diameter of ports A, B, P, T: Ø 11 mm (max)	4 OR 130 Diameter of ports A, B, P, T: Ø 20 mm (max)	4 OR 4112 Diameter of ports A, B, P, T: Ø 24 mm (max)	4 OR 144 Diameter of ports A, B, P, T: Ø 34 mm (max)
	2 OR 108 Diameter of ports X, Y: Ø 5 mm (max)	2 OR 2043 Diameter of ports X, Y: Ø 7 mm (max)	2 OR 3056 Diameter of ports X, Y: Ø 7 mm (max)	2 OR 3056 Diameter of ports X, Y: Ø 7 mm (max)

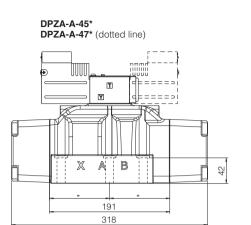


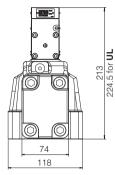
27*-S*

26,5

DPZA-4

ISO 4401: 2005 (see table P005) Mounting surface: 4401-08-08-0-05





Mass [kg]				
DPZA-*-45*	17,9			
DPZA-*-47*	19,6			
Option /G	+0,9			
Option /O	+0,35			
Option /WP	+0,25			

DPZA-A-45* /B

T

AB

191

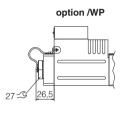
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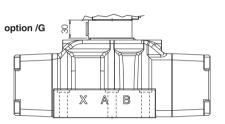
Y

 \mathbb{X}

option /O



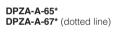


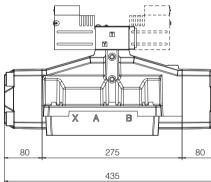


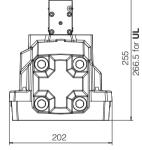
Mass [kg]				
DPZA-*-45*	43,0			
DPZA-*-47*	44,7			
Option /G	+0,9			
Option /O	+0,35			
Option /WP	+0,25			

ISO 4401: 2005 (see table P005) Mounting surface: 4401-10-09-0-05

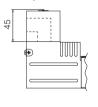
DPZA-6

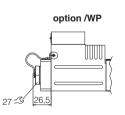


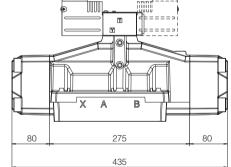




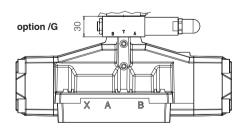
option /O







DPZA-A-65* /B



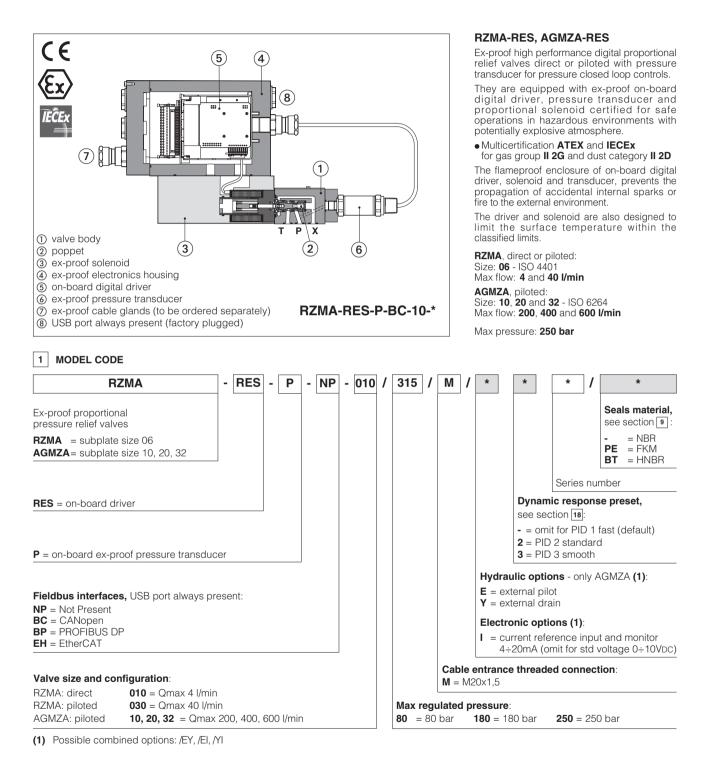
16 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments
X020	Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO
X030	Summary of Atos ex-proof components certified to cULus
FX900	Operating and manintenance information for ex-proof proportional valves
KX800	Cable glands for ex-proof valves
P005	Mounting surfaces for electrohydraulic valves

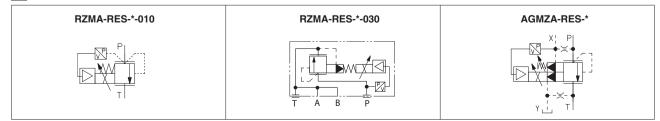
atos

Ex-proof digital proportional relief valves high performance

direct or piloted, with on board driver and pressure transducer - ATEX and IECEx



2 CONFIGURATIONS AND HYDRAULIC SYMBOLS (representation according to ISO 1219-1)



3 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

ig
angle WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

5 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

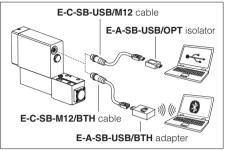
6 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	RZMA-010 150 years, RZMA-030 and AGZMA 75 years, see technical table P007				
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$				
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Surface protection	Zinc coating with black passivation - salt spay test (EN ISO 9227) > 200 h				
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006				

Valve model		RZMA			AGMZA		
Size code		010	010 030		10	20	32
Valve size		06 10 20 32				32	
Max regulated pressure	[bar]		80	180) 250		
Min regulated pressure	[bar]	ar] see min. pressure / flow diagrams at sections 20 21 22			s 20 21 22		
Max pressure at port P, A, B, X	[bar]	315					
Max pressure at port T, Y	[bar]			21	0		
Max flow	[l/min]	4	40		200	400	600
Response time 0-100% step signal (depending on installation) (1) [ms]		≤	60		≤90	≤ 110	≤ 125
Hysteresis[% of the max pressure]		≤0,3					•
Linearity[% of the max pressure]		≤1,0					
Repeatability[% of the max pressure	e]			≤ 0	,2		

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

USB or Bluetooth connection



8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)					
Max power consumption	35 W					
Analog input signals						
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account					
Monitor outputs	Voltage: range $0 \div 10$ VDC @ max 5 mA Current: range $0 \div 20$ mA @ max 500 Ω load resistance					
Enable input	Range: 0 ÷ 9 Vpc (OFF state), 15 ÷ 24 Vpc (ON state), 9 ÷ 15 Vpc (not accepted); Input impedance: Ri > 87 kΩ					
Fault output	Output range : 0 ÷ 24 VDC (ON state ≅ VL+ [logic power supply] ; OFF state ≅ 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)					
Pressure transducer power supply	+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)					
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, power supplies level, pressure transducer failure					
Protection degree to DIN EN60529	IP66/67 with relevant cable gland					
Duty factor	Continuous rating (ED=100%)					
Tropicalization	Tropical coating on electronics PCB					
Additional characteristics	Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply					
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)					
Communication interface	USB CANopen PROFIBUS DP EtherCAT, Atos ASCII coding EN50325-4 + DS408 EN50170-2/IEC61158 EC 61158					
Communication physical layer	not insulatedoptical insulatedoptical insulatedFast Ethernet, insulatedUSB 2.0 + USB OTGCAN ISO11898RS485100 Base TX					

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$			
Recommended viscosity		20÷100 mm²/s - max allowed ra	20÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s		
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at KTF	
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	catalog	
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922	
Flame resistant with water (1)		NBR, HNBR	HFC	130 12922	

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type	RZMA, AGMZA			
Certifications	Multicertification Group II			
	ATEX IECEx			
Solenoid certified code		OZA-RES		
Type examination certificate (1)	ATEX: TUV IT 18 ATEX 068 X IECEx: IECEx TPS 1		Ex TPS 19.0004X	
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db iECEx Ex db IIC T6/T5/T4 Gb Ex tb IIIC T85°C/T100°C/T135°C Db			
Temperature class	Т6	T5	T4	
Surface temperature	≤ 85 °C	≤ 100 °C	≤ 135 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +55 °C	-40 ÷ +70 °C	
Applicable standards	EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079-3 EN 60079-1 IEC 60079-1			
Cable entrance: threaded connection	M = M20x1,5			

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

in case the complete valve must wisthstand with minimum ambient temperature -40°C, select /BT in the model code.

🗥 WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	Т6	85 °C	80 °C
55 °C	Τ5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

13 HYDRAULIC OPTIONS - only for AGMZA

E = External pilot option to be selected when the pilot pressure is supplied from a different line respect to the P main line.

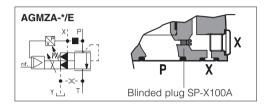
With option E the internal connection between port P and X of the valve is plugged. The pilot pressure must be connected to the X port available on the valve's mounting surface or on main body (threaded pipe connection G ¹/₄").

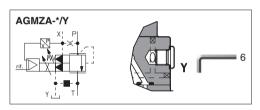
Y = The external drain is mandatory in case the main line T is subjected to pressure peaks or it is pressurized.

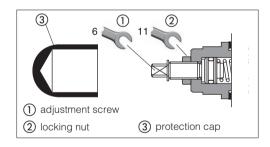
The Y drain port has a threaded connection G 1/4" available on the pilot stage body.

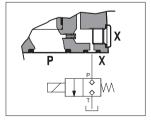
14 ELECTRONIC OPTIONS

= It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 Vbc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vbc or ±20 mA.It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.









PID	Dynamic response		
1	Fast - default (1)		
2	Standard		
3	Smooth		
4	Open Loop		

15 POSSIBLE COMBINED OPTIONS EY, /EI, /YI

16 MECHANICAL PRESSURE LIMITER - only for AGMZA

The AGMZA are provided with mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded.
- turn clockwise the adjustment screw ① until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal.
- turn clockwise the adjustment screw (1) of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working.

17 REMOTE PRESSURE UNLOADING - only for AGMZA

The **P** main line can be remotely unloaded by connecting the valve X port to a solenoid valve as shown in the below scheme (venting valve).

This function can be used in emergency to unload the system pressure by-passing the proportional control.

18 DYNAMIC RESPONSE - 4 pressure PIDs

The valve is provided with 4 PIDs configurations to match different hydraulic conditions. The required PID configuration can be selected before the valve commissioning, through Atos E-SW software via USB port. Only for **RES** the PID can be also selected in real time, through PLC via fieldbus.

(1) interchangeable with previous TERS version

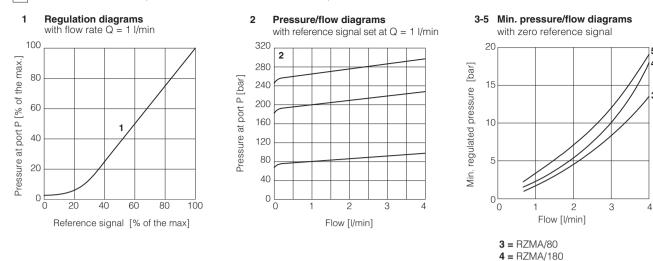
19 PRESSURE TRANSDUCER FAILURE

In case of pressure transducer failure, the valve's reaction can be configured through Atos E-SW software to:

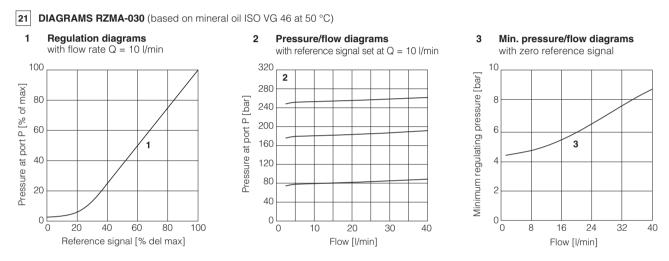
- cut off the current to solenoid, therefore the regulated pressure will be reduced to minimum value (default setting)

- automatically switch the pressure control from closed loop (PID1,2,3) to open loop (PID4), to let the valve to temporarily operate with reduced regulation accuracy

20 DIAGRAMS RZMA-010 (based on mineral oil ISO VG 46 at 50 °C)

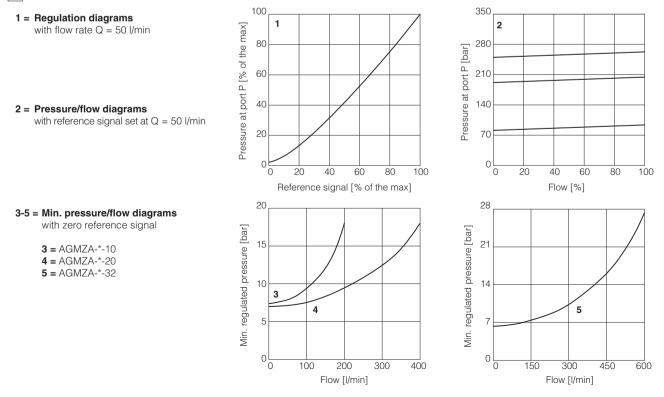


Note: the presence of counter pressure at port T can affect the pressure regulation and the minimum pressure



Note: the presence of counter pressure at port T can affect the pressure regulation and the minimum pressure

22 DIAGRAMS AGMZA (based on mineral oil ISO VG 46 at 50 °C)



5 = RZMA/250

23 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

23.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

23.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

23.3 Pressure reference input signal (P_INPUT+)

The driver controls in closed loop the current to the valve pressure proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ Vbc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 Vbc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ Vbc.

23.4 Pressure monitor output signal (P_MONITOR)

The driver generates an analog output signal proportional to the actual pressure of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, defaults settings are $0 \div 10$ Vbc for standard and $4 \div 20$ mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of $0 \div 10$ Vbc or $0 \div 20$ mA.

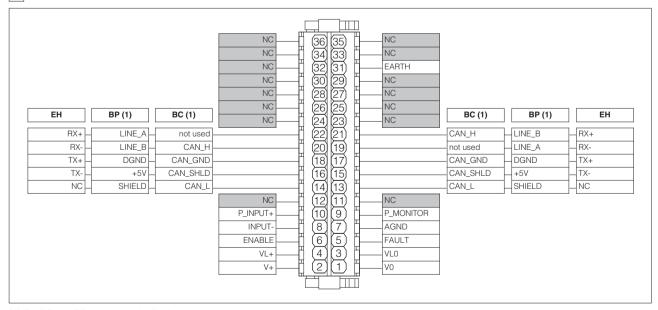
23.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

23.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

24 TERMINAL BOARD OVERVIEW



(1) For BC and BP executions the fieldbus connections have an internal pass-through connection

25 ELECTRONIC CONNECTIONS

25.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2 V+ Power supply 24 Vbc		Input - power supply	
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
Δ	6 ENABLE		Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
	7 AGND		Analog ground	Gnd - analog signal
	8	INPUT-	Negative pressure reference input signal for INPUT+	Input - analog signal
	9	P_MONITOR	Pressure monitor output signal: 0 \div 10 Vpc / 0 \div 20 mA maximum range, referred to AGND Default is: 0 \div 10 Vpc or 4 \div 20 mA	Output - analog signal Software selectable
	10	P_INPUT+	Pressure reference input signal: $\pm 10 \text{ Vpc} / \pm 20 \text{ mA}$ maximum range Defaults are: $0 \div 10 \text{ Vpc}$ for standard and $4 \div 20 \text{ mA}$ for /l option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

25.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply		
	2	ID	Identification	S I I	
$ \mathbf{B} $	3	GND_USB	Signal zero data line		
	4	D-	Data line -		
	5	D+	Data line +	(female)	

25.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
C () ()	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

CABLE ENTRANCE PIN SIGNAL TECHNICAL SPECIFICATIONS 13 CAN_L Bus line (low) 15 CAN_SHLD Shield C217 CAN_GND Signal zero data line 19 not used Pass-through connection (1) 21 CAN_H Bus line (high)

(1) pin 19 and 22 can be fed with external +5V supply of CAN interface

25.4 BP fieldbus execution connections

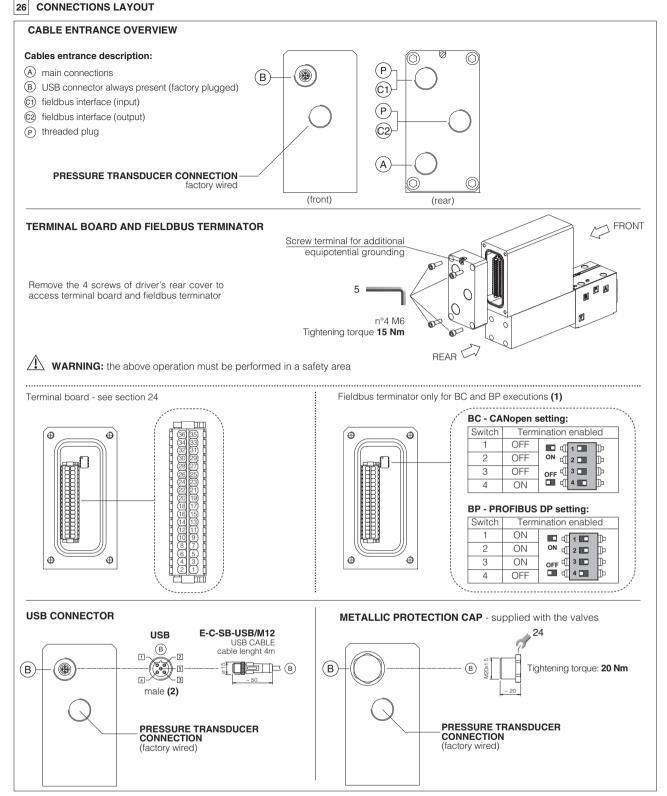
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

25.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	13	SHIELD		
	15	+5V	Power supply	
C2	17	DGND	Data line and termination signal zero	
	19	LINE_A	Bus line (high)	
	21	LINE_B	Bus line (low)	

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

26.1 Cable glands and threaded plug - see tech table KX800

Communication	To be ordered separately Cable entrance						
interfaces		gland	Thread		overview	Notes	
	quantity	entrance	quantity	entrance			
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers	
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

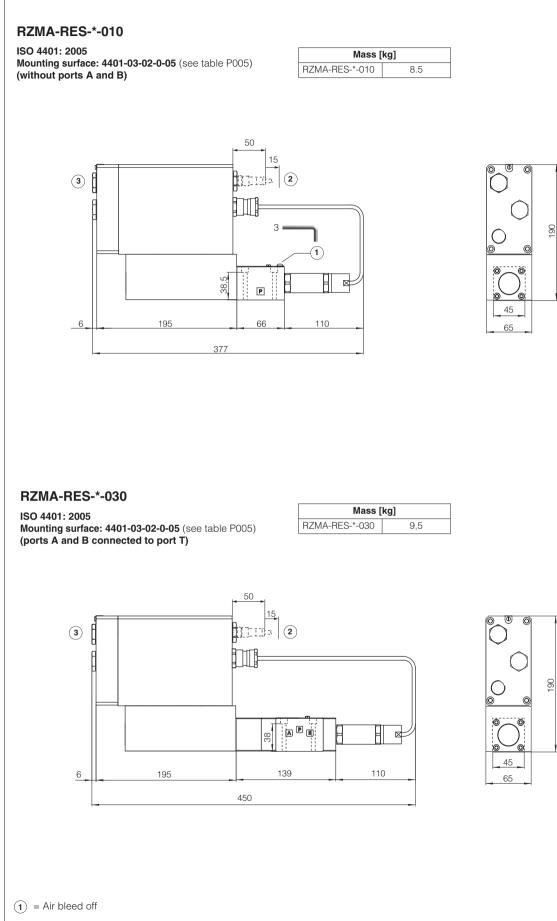
27 FASTENING BOLTS AND SEALS

27.1 RZMA valves

	RZMA-RES-*-010	RZMA-RES-*-030
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm
0	Seals: 2 OR 108 Diameter of ports P, T: Ø 5 mm	Seals: 4 OR 108 Diameter of ports P, T: Ø 7,5 mm

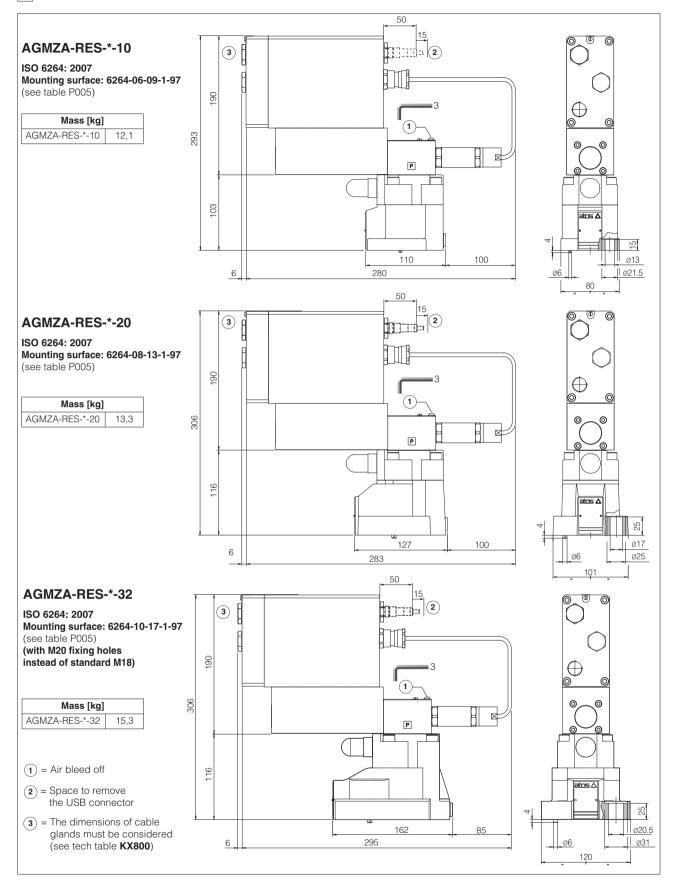
27.2 AGMZA valves

	AGMZA-RES-*-10	AGMZA-RES-*-20	AGMZA-RES-*-32
	Fastening bolts:	Fastening bolts:	Fastening bolts:
	4 socket head screws M12x35 class 12.9	4 socket head screws M16x50 class 12.9	4 socket head screws M20x60 class 12.9
	Tightening torque = 125 Nm	Tightening torque = 300 Nm	Tightening torque = 600 Nm
0	Seals:	Seals:	Seals:
	2 OR 123	2 OR 4112	2 OR 4131
	Diameter of ports P, T: Ø 14 mm	Diameter of ports P, T: Ø 24 mm	Diameter of ports P, T: Ø 28 mm
	1 OR 109/70	1 OR 109/70	1 OR 109/70
	Diameter of port X: Ø 3,2 mm	Diameter of port X: Ø 3,2 mm	Diameter of port X: Ø 3,2 mm



 $(\mathbf{2})$ = Space to remove the USB connector

(3) = The dimensions of cable glands must be considered (see tech table **KX800**)



30 RELATED DOCUMENTATION

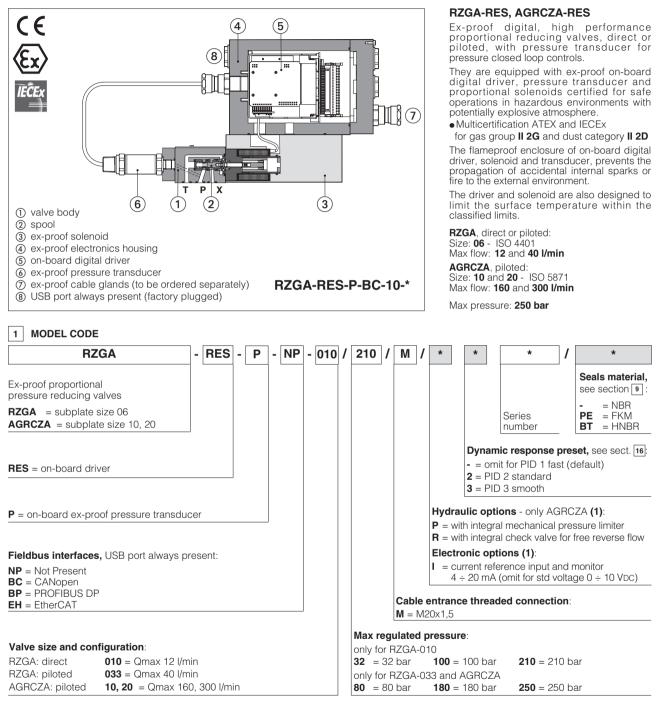
X010 X020	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO
FX900	Operating and manintenance informationfor ex-proof proportional valves
GS500	Programming tools
GS510	Fieldbus

GX800Ex-proof pressure transducer type E-ATRA-7KX800Cable glands for ex-proof valvesP005Mounting surfaces for electrohydraulic valves

atos

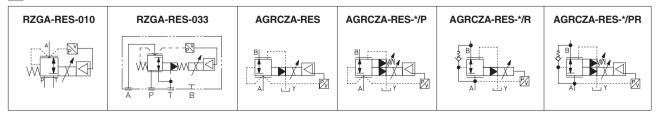
Ex-proof digital proportional reducing valves high performance

direct or piloted, with on-board driver and pressure transducer - ATEX and IECEx



(1) Possible combined options: /IP, /IR, /PR

2 CONFIGURATIONS AND HYDRAULIC SYMBOLS (representation according to ISO 1219-1)

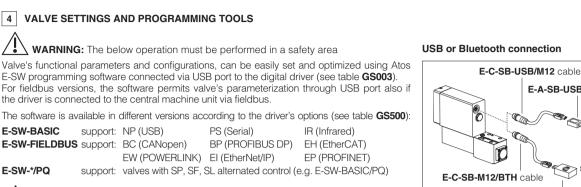


3 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

E-A-SB-USB/OPT isolator

E-A-SB-USB/BTH adapter



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

5 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

6 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	RZGA-010 150 years, RZGA-033 and AGRCZA 75 years see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

7	HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C
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Valve model				RZGA				AGRCZA
Size code				010		033	10	20
Valve size				06		06	10	20
Max regulated pr	ressure	[bar]	32	100	210	80) 180	250
Max pressure at	port P, A, B, X	[bar]					315	
Max pressure at	Max pressure at port T, Y [bar]			210				
Min regulated pre	essure	[bar]	0,8 2,5			1,0		
Max flow		[l/min]		12		40	160	300
Response time 0-100% step signal (depending on installation) (1) [ms]		≤ 50 ≤ 60				≤ 60		
Hysteresis [% of the max pressure]		≤0,3						
_inearity [% of the max pressure]			≤ 1,0					
Repeatability	[% of the max p	ressure]	≤ 0,2					

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

8 ELECTRICAL CHARACTERISTICS

Nominal	: +24 VDC						
Rectified and filtered							
35 W							
Voltage: range ±10 V Current: range ±20 n	/DC (24 VMAX tollerant) nA	Input impedance Input impedance	$\begin{array}{ll} \text{e:} & \text{Ri} > 50 \text{ k}\Omega \\ \text{e:} & \text{Ri} = 500 \ \Omega \end{array}$				
			ls, the European standards				
		ad resistance					
Range: 0 ÷ 9 VDC (OFF	state), 15 ÷ 24 VDC (ON	state), 9 ÷ 15 VDC (not acc	cepted); Input impedance: Ri > 87 k Ω				
Output range : 0 ÷ 24 VDC (ON state ≅ VL+ [logic power supply] ; OFF state ≅ 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)							
+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)							
			nce signal, over/under temperature,				
IP66/67 with relevant of	cable gland						
Continuous rating (ED	=100%)						
Tropical coating on ele	ectronics PCB						
Short circuit protectior	n of solenoid current su	oply; current control by F	P.I.D. with rapid solenoid switching;				
protection against rev	erse polarity of power s	upply					
According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 610006-3)							
USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, EC 61158				
not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX				
	Rectified and filtered 35 W Voltage: range ±10 V Current: range ±20 m H (180°) Due to the or ISO 13732-1 and EN9 Voltage: range 0 ÷ 1 Current: range 0 ÷ 24 external negative volta +24VDC @ max 100 m Solenoid not connecte power supplies level, IP66/67 with relevant of Continuous rating (ED Tropical coating on ell Short circuit protection protection against rev According to Directive USB Atos ASCII coding not insulated	Rectified and filtered : VRMS = 20 ÷ 32 VMAX35 WVoltage: range ± 10 VDC (24 VMAX tollerant) Current: range ± 20 mAH (180°) Due to the occuring surface tempera ISO 13732-1 and EN982 must be taken into a Voltage: range 0 ÷ 10 VDC @ max 5 mA Current: range 0 ÷ 20 mA @ max 500 Ω loa Range: 0 ÷ 9 VDC (OFF state), 15 ÷ 24 VDC (ON state \cong VL+ external negative voltage not allowed (e.g. du +24VDC @ max 100 mA (E-ATRA-7 see tech Solenoid not connected/short circuit, cable b power supplies level, pressure transducer fail IP66/67 with relevant cable glandContinuous rating (ED=100%) Tropical coating on electronics PCB Short circuit protection of solenoid current supprotection against reverse polarity of power s According to Directive 2014/30/UE (Immunity USB Not sASCII coding Not insulated	Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)35 WVoltage: range ±10 VDC (24 VMAX tollerant)Input impedanceInput impedanceCurrent: range ±20 mAInput impedanceH (180°) Due to the occuring surface temperatures of the solenoid colISO 13732-1 and EN982 must be taken into accountVoltage: range 0 ÷ 10 VDC @ max 5 mACurrent: range 0 ÷ 20 MA @ max 500 Ω load resistanceRange: 0 ÷ 9 VDC (OFF state), 15 ÷ 24 VDC (ON state), 9 ÷ 15 VDC (not accOutput range : 0 ÷ 24 VDC (ON state ≅ VL+ [logic power supply]; Cexternal negative voltage not allowed (e.g. due to inductive loads)+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)Solenoid not connected/short circuit, cable break with current referepower supplies level, pressure transducer failureIP66/67 with relevant cable glandContinuous rating (ED=100%)Tropical coating on electronics PCBShort circuit protection of solenoid current supply; current control by Pprotection against reverse polarity of power supplyAccording to Directive 2014/30/UE (Immunity: EN 61000-6-2; EmissionUSBCANopenPROFIBUS DPEN50325-4 + DS408EN50170-2/IEC61158not insulated				

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷100 mm²/s - max allowed range 15 ÷ 500 mm²/s				
Max fluid normal oper		ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922		

🕂 The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type	RZMA, AGMZA						
Certifications	Multicertification Group II ATEX IECEx						
Solenoid certified code		OZA-RES					
Type examination certificate (1)	ATEX: TUV IT 18 ATEX 068 X IECEx: IECEx TPS 19.0004X						
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C Db						
Temperature class	Т6	Т	5	Τ4			
Surface temperature	≤ 85 °C	≤ 10	0 °C	≤ 135 °C			
Ambient temperature (2)	-40 ÷ +40 °C -40 ÷ +55 °C -40 ÷ +7						
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079- EN 60079-1 IEC 60079-1						
Cable entrance: threaded connection	M = M20x1,5						

(1) The type examinator certificates can be downloaded from

(1) The type examinator outmoties can be downloaded norm
 (2) The driver and solenoids are certified for minimum ambient temperature -40°C. In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

🗥 WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	Т6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table KX600 Note: a Loctite sealant type 545, should be used on the cable gland entry threads



13 HYDRAULIC OPTIONS - only for AGRCZA

Ρ = The AGRCZA are provided with mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded
- turn clockwise the adjustment screw (1) until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal
- turn clockwise the adjustment screw (1) of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working
- **R** = The AGRCZA are provided with integral check value for free reverse flow $A \rightarrow B$

① Check valve - cracking pressure = 0,5 bar 2 Plug

14 ELECTRONIC OPTIONS

= It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 Vpc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vpc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

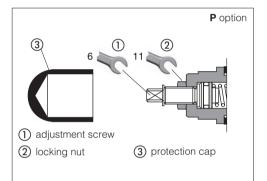
15 POSSIBLE COMBINED OPTIONS

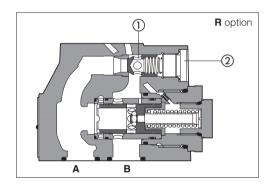
/IP, /IR, /PR

DYNAMIC RESPONSE - 4 pressure PIDs 16

The valve is provided with 4 PIDs configurations to match different hydraulic conditions. The required PID configuration can be selected before the valve commissioning, through Atos E-SW software via USB port. Only for **RES** the PID can be also selected in real time, through PLC via fieldbus.

(1) interchangeable with previous TERS version





PID	Dynamic response			
1	Fast - default (1)			
2	Standard			
3	Smooth			
4	Open Loop			

17 PRESSURE TRANSDUCER FAILURE

In case of pressure transducer failure, the valve's reaction can be configured through Atos E-SW software to:

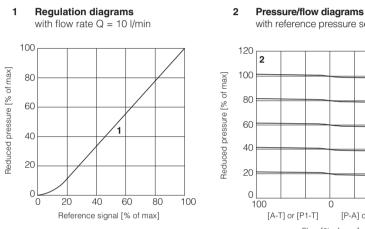
- cut off the current to solenoid, therefore the regulated pressure will be reduced to minimum value (default setting)

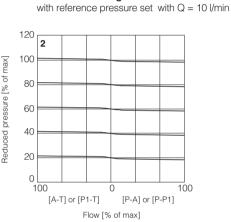
- automatically switch the pressure control from closed loop (PID1,2,3) to open loop (PID4), to let the valve to temporarily operate with reduced regulation accuracy

18 DIAGRAMS RZGA-010 (based on mineral oil ISO VG 46 at 50 °C)

Regulation diagrams with flow rate Q = 1 l/min Pressure/flow diagrams 1 2 with reference signal set at Q = 1 l/min 100 Regulated pressure at port A [% of the max] 2 1 Pressure at port A [% of the max] 100 80 80 60 60 40 40 20 20 0 0 0 20 40 60 80 100 12 8 4 [A→T] 0 Flow [I/min] Reference signal [% of the max]

19 DIAGRAMS RZGA-033 (based on mineral oil ISO VG 46 at 50 °C)

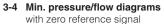




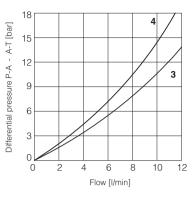
8 [P→A]

12

4

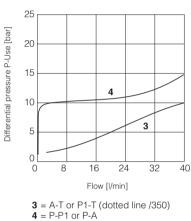






3 = Pressure drops vs. flow $P \rightarrow A$ **4** = Pressure drops vs. flow $A \rightarrow T$

3-4 Pressure drop/flow diagram

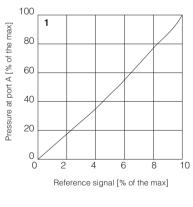




Note: the presence of counter pressure at port T can affect the effective pressure regulation

20 DIAGRAMS AGRCZA (based on mineral oil ISO VG 46 at 50 °C)

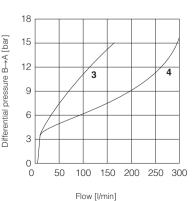
- **Regulation diagrams** 1 with flow rate Q = 10 l/min
- Pressure/flow diagrams 2 with reference pressure set with Q = 10 l/min

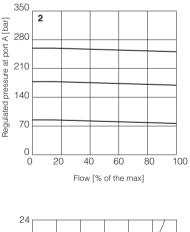


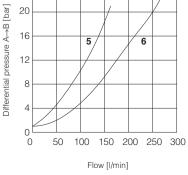


Differential pressure B→A **3** = AGRCZA-*-10 **4** = AGRCZA-*-20

Differential pressure $A \rightarrow B$ (through check valve) 5 = AGRCZA-*-10/*/R 6 = AGRCZA-*-20/*/R







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21 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

21.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

21.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

21.3 Pressure reference input signal (P_INPUT+)

The driver controls in closed loop the current to the valve pressure proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ Vbc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 Vbc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ Vbc.

21.4 Pressure monitor output signal (P_MONITOR)

The driver generates an analog output signal proportional to the actual pressure of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, defaults settings are 0 ÷10 Vbc for standard and 4 ÷ 20 mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of 0 ÷10 Vbc or 0 ÷ 20 mA.

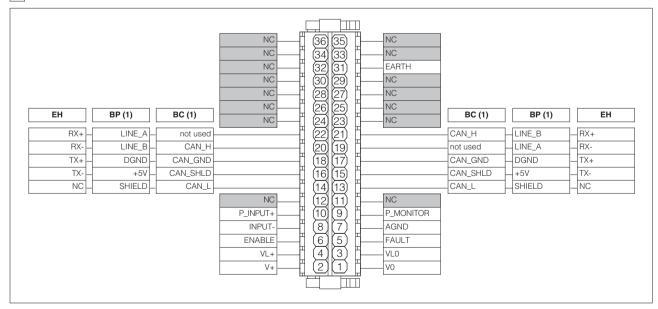
21.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

21.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

22 TERMINAL BOARD OVERVIEW



(1) For BC and BP executions the fieldbus connections have an internal pass-through connection

23 ELECTRONIC CONNECTIONS

23.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 Vbc	Input - power supply
	3	VL0	Power supply 0 VDc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
Δ	6	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative pressure reference input signal for INPUT+	Input - analog signal
	9	P_MONITOR	Pressure monitor output signal: 0 \div 10 Vpc / 0 \div 20 mA maximum range, referred to AGND Default is: 0 \div 10 Vpc or 4 \div 20 mA	Output - analog signal Software selectable
	10	P_INPUT+	Pressure reference input signal: $\pm 10 \text{ Vpc} / \pm 20 \text{ mA maximum range}$ Defaults are: $0 \div 10 \text{ Vpc}$ for standard and $4 \div 20 \text{ mA for /I option}$	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

23.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply		
	2	ID	Identification	(The second sec	
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -		
	5	D+	Data line +	(female)	

23.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
()1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	CAN_L	Bus line (low)
	15	CAN_SHLD	Shield
C2	17	CAN_GND	Signal zero data line
	19	not used	Pass-through connection (1)
	21	CAN_H	Bus line (high)

(1) pin 19 and 22 can be fed with external +5V supply of CAN interface

23.4 BP fieldbus execution connections

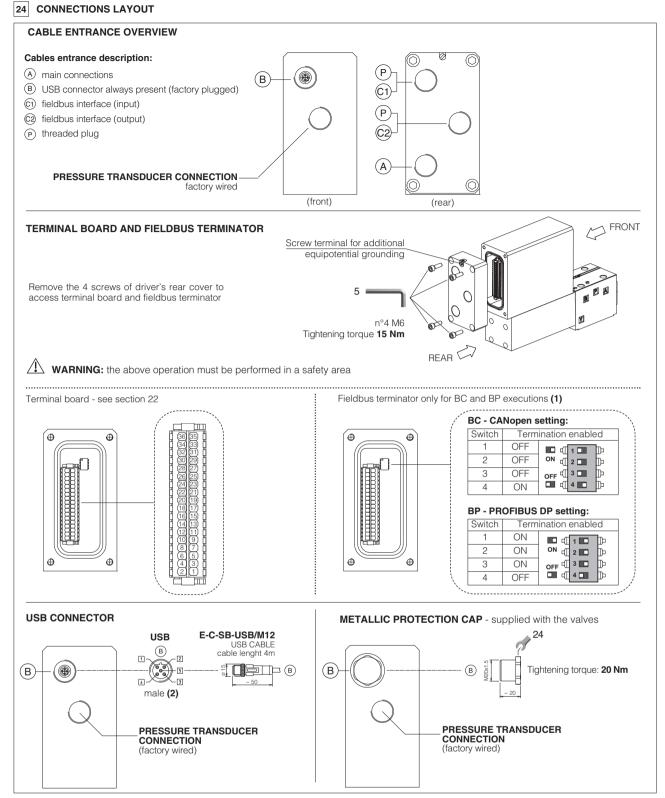
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
~ (16	+5V	Power supply
()1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

23.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

24.1 Cable glands and threaded plug - see tech table KX800

O	То	be ordere	ed separat	ely	Oshila antranaa	
Communication interfaces		gland entrance	Thread quantity	ed plug entrance	Cable entrance overview	Notes
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

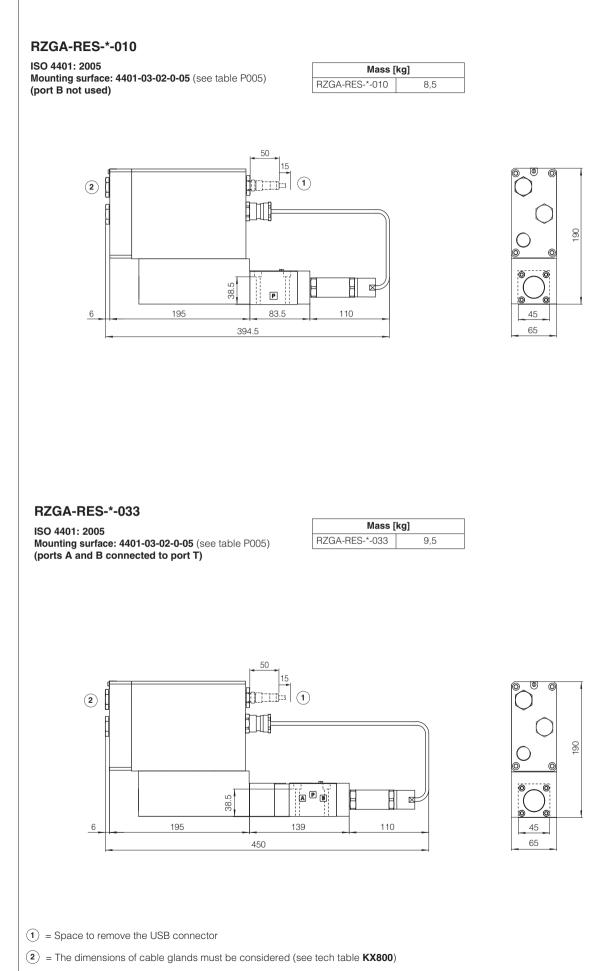
25 FASTENING BOLTS AND SEALS

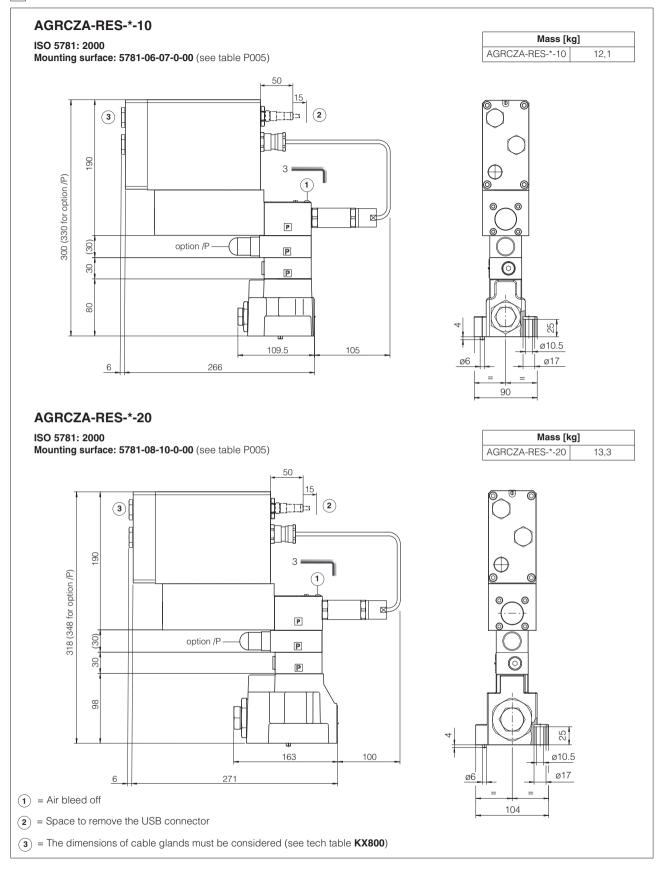
25.1 RZGA valves

	RZGA-RES-*-010	RZGA-RES-*-033
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm
0	Seals: 4 OR 108 Diameter of ports P, A, T: Ø 5 mm	Seals: 4 OR 108 Diameter of ports P, A, T: Ø7,5 mm

25.2 AGRCZA valves

	AGRCZA-RES-*-10	AGRCZA-RES-*-20
	Fastening bolts: 4 socket head screws M10x45 class 12.9 Tightening torque = 70 Nm	Fastening bolts: 4 socket head screws M10x45 class 12.9 Tightening torque = 70 Nm
0	Seals: 2 OR 3068 Diameter of ports A, B: Ø 14 mm 2 OR 109/70 Diameter of port X, Y: Ø 5 mm	Seals: 2 OR 4100 Diameter of ports A, B: Ø 22 mm 2 OR 109/70 Diameter of port X, Y: Ø 5 mm





28 RELATED DOCUMENTATION

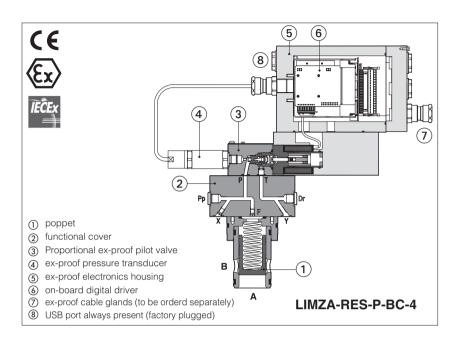
GX80 C KX80 P005	X010 X020 FX900 GS500 GS510
	GS510

GX800Ex-proof pressure transducer type E-ATRA-7KX800Cable glands for ex-proof valvesP005Mounting surfaces for electrohydraulic valves

atos

Ex-proof digital proportional pressure cartridges high performance

with on-board driver and pressure transducer - ATEX and IECEx



LICZA-RES, LIMZA-RES, LIRZA-RES

2-way ex-proof digital proportional pressure cartridges, high performance with pressure transducer, respectively performing: pressure compensator, relief or reducing

functions. They are equipped with ex-proof on-board digital driver, pressure transducer and proportional solenoid certified for safe

proportional solenoid certified for safe operations in hazardous environments with potentially explosive atmosphere.

Multicertification ATEX and IECEx

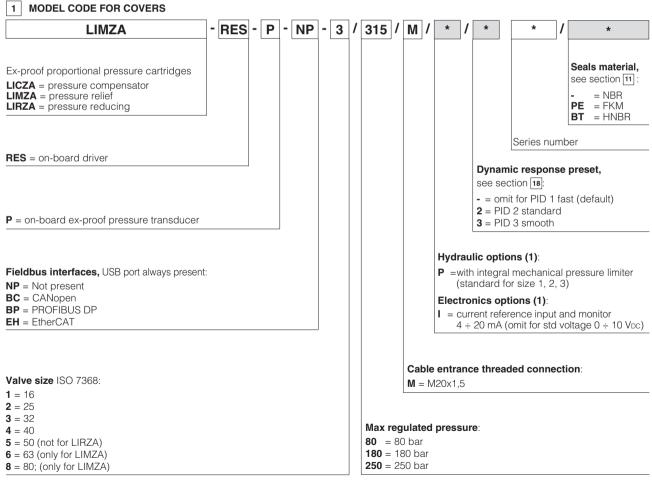
for gas group II 2G and dust category II 2D

The flameproof enclosure of on-board digital driver, solenoid and transducer, prevents the propagation of accidental internal sparks or fire to the external environment.

The driver and solenoid are also designed to limit the surface temperature within the classified limits.

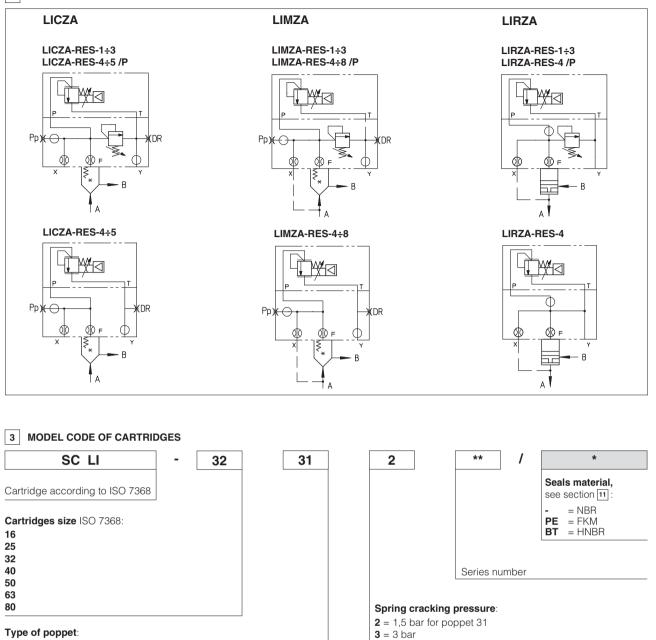
Size: 16 ÷ 80 - ISO7368

Max flow: up to **4500 l/min** Max pressure: **250 bar**



(1) Possible combined options: /IP





31 = for LIMZA and LICZA **36** = for LICZA **37** = for LIRZA

4 TYPE OF POPPET

Type of poppet	31	36	37
Functional sketch (Hydraulic symbol)			
Typical section			
Area ratio A: Ap	1:1	1:1	1:1

4 = 4 bar

6 = 6 bar for poppet 31 and 36

7 = 7 bar for poppet 37

5 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

6 VALVE SETTINGS AND PROGRAMMING TOOLS

WARNING: the below operation must be performed in a safety area

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

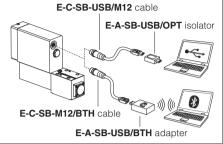
The software is available in different versions according to the driver's options (see table GS500):

			-	
E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET IRT)
E-SW-*/PQ	support:	valves with SP, SF, S	SL alternated control (e	e.g. E-SW-BASIC/PQ)
•				

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

USB or Bluetooth connection



7 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

8 GENERAL CHARACTERISTICS

Assembly position	Any position						
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100						
MTTFd valves according to EN ISO 13849	75 years, see technical table P007						
Ambient temperature range	Standard = -20° C ÷ $+60^{\circ}$ C /PE option = -20° C ÷ $+60^{\circ}$ C /BT option = -40° C ÷ $+60^{\circ}$ C						
Storage temperature range	Standard = -20° C ÷ $+70^{\circ}$ C /PE option = -20° C ÷ $+70^{\circ}$ C /BT option = -40° C ÷ $+70^{\circ}$ C						
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h						
Compliance	Explosion proof protection, see section 12 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"						
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006						

9 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model					LICZA						LIMZA					LIR	ZA	
Valve size		[l/min]	1	2	3	4	5	1	2	3	4	5	6	8	1	2	3	4
Max flow		[bar]	200	400	750	1000	2000	200	400	750	1000	2000	3000	4500	160	300	550	800
Min regulated p	pressure									see	sectio	n 20						
Max regulated pres. at port A [bar]			80; 180; 250 80; 180; 250							80; 180; 250								
Max pressure [bar]		Ports: T, Y = 210																
		Ports: P, A, B, X = 350																
Response time 0-100% step signal (1) (depending on installation) [ms]		≤ 100 ÷ 350			≤ 100 ÷ 350													
											≤ 100 ÷ 250							
Hysteresis [% of regulated max pres.]		≤0,5																
Linearity [% of regulated max pres.]		≤ 1,0																
Repeatibility	[% of regulated m	ax pres.]	≤0,2															

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

10 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)							
Max power consumption	5 W							
Analog input signals	oltage: range ± 10 VDC (24 VMAX tollerant) Input impedance: Ri > 50 k Ω Input impedance: Ri = 500 Ω							
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards SO 13732-1 and EN982 must be taken into account							
Monitor outputs	Voltage: range 0 \div 10 VDC @ max 5 mA Current: range 0 \div 20 mA @ max 500 Ω load resistance							
Enable input	Range: 0 ÷ 9 VDc (OFF state), 15 ÷ 24 VDc (ON state), 9 ÷ 15 VDc (not accepted); Input impedance: Ri > 87 k							
Fault output	Output range : $0 \div 24 \text{ V}_{DC}$ (ON state \cong VL+ [logic power supply] ; OFF state \cong 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)							
Pressure transducer power supply	+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)							
Alarms	Solenoid not connected/short circuit, cable break with current reference s valve spool transducer malfunctions	signal, over/under temperature,						
Protection degree to DIN EN60529	P66/67 with relevant cable gland							
Duty factor	Continuous rating (ED=100%)							
Tropicalization	Tropical coating on electronics PCB							
Additional characteristics	Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid s protection against reverse polarity of power supply							
Electromagnetic compatibility (EMC)								
Communication interface	Atos ASCII coding EN50325-4 + DS408 EN50170-2/IEC61158 EC 6	erCAT, 61158						
Communication physical layer		t Ethernet, insulated Base TX						

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

11 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$					
Recommended viscosity		20 ÷100 mm²/s - max allowed ra	ange 15 ÷ 500 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF				
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog				
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard			
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524			
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922			
Flame resistant with water (1)		NBR, HNBR	HFC	130 12922			

🗥 The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

12 CERTIFICATION DATA

Valve type	LICZA, LIMZA, LIRZA							
Certifications	Multicertification Group II ATEX IECEx							
Solenoid certified code		OZA	-RES					
Type examination certificate (1)	• ATEX: TUV IT 18 ATEX 068 >	• ATEX: TUV IT 18 ATEX 068 X • IECEx: IECEx TPS 19.0004X						
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db							
Temperature class	T6	TS	i	Τ4				
Surface temperature	≤ 85 °C	≤ 100	°C	≤ 135 °C				
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +	55 °C	-40 ÷ +70 °C				
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079-31 EN 60079-1 IEC 60079-1 IEC 60079-1 IEC 60079-31							
Cable entrance: threaded connection		$\mathbf{M} = \mathbf{M}$	20x1,5					

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C. In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

MARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

13.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	Т6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

14 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX600 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

15 HYDRAULIC OPTIONS

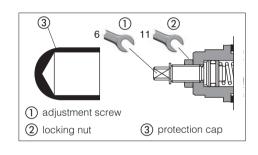
P = Integral mechanical pressure limiter (standard for size 1, 2 and 3)

The LICZA, LIMZA and LIRZA standard size 1, 2, 3 and option /P are provided with mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded.
- turn clockwise the adjustment screw ① until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal.
- turn clockwise the adjustment screw ① of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working.



16 ELECTRONIC OPTIONS

It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 Vpc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vpc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

17 POSSIBLE COMBINED OPTIONS

/IP

Т

18 DYNAMIC RESPONSE - 4 pressure PIDs

The valve is provided with 4 PIDs configurations to match different hydraulic conditions. The required PID configuration can be selected before the valve commissioning, through Atos E-SW software via USB port. Only for **RES** the PID can be also selected in real time, through PLC via fieldbus.

(1) interchangeable with previous TERS version

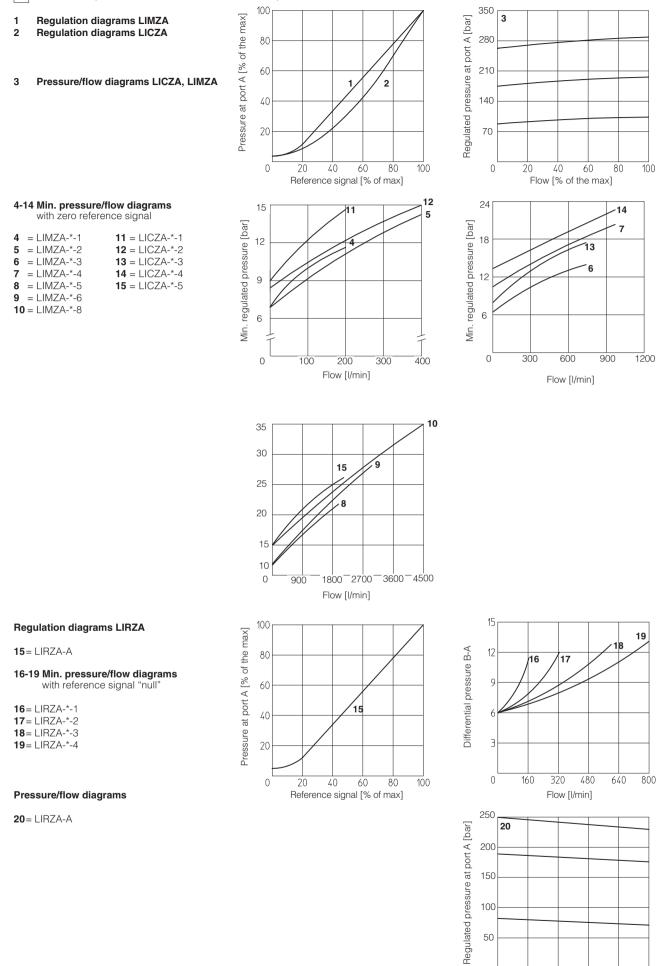
PID	Dynamic response					
1	Fast - default (1)					
2	Standard					
3	Smooth					
4	Open Loop					

19 PRESSURE TRANSDUCER FAILURE

In case of pressure transducer failure, the valve's reaction can be configured through Atos E-SW software to:

- cut off the current to solenoid, therefore the regulated pressure will be reduced to minimum value (default setting)

- automatically switch the pressure control from closed loop (PID1,2,3) to open loop (PID4), to let the valve to temporarily operate with reduced regulation accuracy DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)



Flow [% of the max]

21 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

21.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

21.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

21.3 Pressure reference input signal (P_INPUT+)

The driver controls in closed loop the current to the valve pressure proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ Vbc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 Vbc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ Vbc.

21.4 Pressure monitor output signal (P_MONITOR)

The driver generates an analog output signal proportional to the actual pressure of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, defaults settings are 0 ÷10 Vbc for standard and 4 ÷ 20 mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of 0 ÷10 Vbc or 0 ÷ 20 mA.

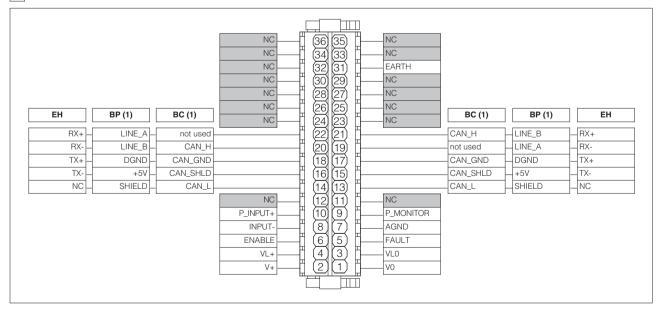
21.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

21.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

22 TERMINAL BOARD OVERVIEW



(1) For BC and BP executions the fieldbus connections have an internal pass-through connection

23 ELECTRONIC CONNECTIONS

23.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 VDc	Gnd - power supply
	2	V+	Power supply 24 Vbc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
Δ	6	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative pressure reference input signal for INPUT+	Input - analog signal
	9	P_MONITOR	Pressure monitor output signal: 0 ÷10 Vpc / 0 ÷ 20 mA maximum range, referred to AGND Default is: 0 ÷10 Vpc or 4 ÷ 20 mA	Output - analog signal Software selectable
	10	P_INPUT+	Pressure reference input signal: $\pm 10 \text{ Vpc} / \pm 20 \text{ mA maximum range}$ Defaults are: $0 \div 10 \text{ Vpc}$ for standard and $4 \div 20 \text{ mA for /I option}$	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

23.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply	12	
	2	ID	Identification	(To a los	
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -	4 - <u>3</u>	
	5	D+	Data line +	(female)	

23.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
C1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	13	CAN_L	Bus line (low)	
	15	CAN_SHLD	Shield	
C2	17	CAN_GND	Signal zero data line	
	19	not used	Pass-through connection (1)	
	21	CAN_H	Bus line (high)	

(1) pin 19 and 22 can be fed with external +5V supply of CAN interface

23.4 BP fieldbus execution connections

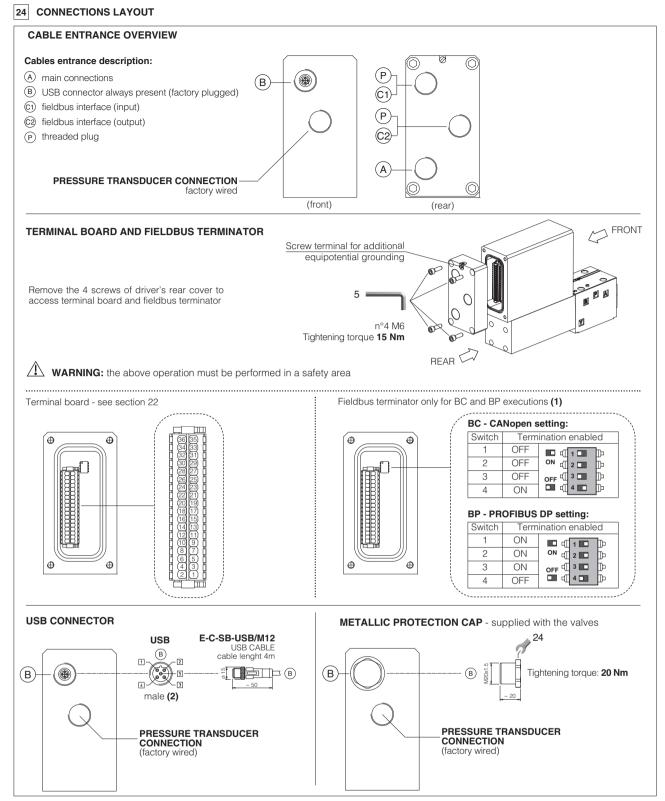
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

23.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
()1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS		
	13	SHIELD			
	15	+5V	Power supply		
C2	17	DGND	Data line and termination signal zero		
	19	LINE_A	Bus line (high)		
	21	LINE_B	Bus line (low)		

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

24.1 Cable glands and threaded plug - see tech table KX800

Communication	To be ordered separately		Cable entrance				
interfaces		gland entrance	Thread quantity		overview	Notes	
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers	
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

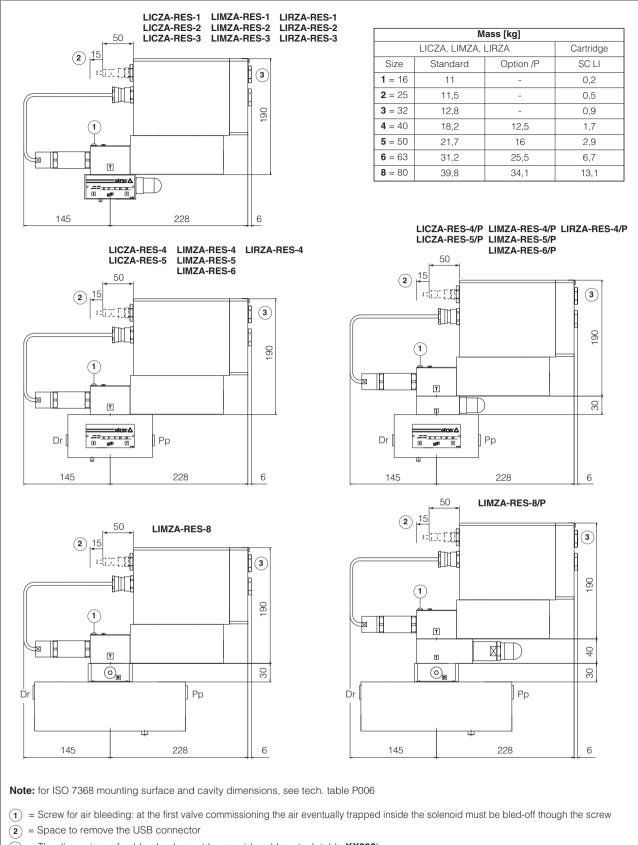
25 FASTENING BOLTS AND SEALS

Туре	Size	Fastening bolts	Seals		
	1 = 16	4 socket head screws M8x45 class 12.9 Tightening torque = 35 Nm	2 OR 108		
LIMZA LICZA	2 = 25	4 socket head screws M12x45 class 12.9 Tightening torque = 125 Nm	2 OR 108		
LIRZA	3 = 32	4 socket head screws M16x55 class 12.9 Tightening torque = 300 Nm	2 OR 2043		
	4 = 40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	2 OR 3043		
LIMZA LICZA	5 = 50	4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	2 OR 3043		
LIMZA	6 = 63	4 socket head screws M30x90 class 12.9 Tightening torque = 2100 Nm	2 OR 3050		
LIWZA	8 = 80	8 socket head screws M24x90 class 12.9 Tightening torque = 1000 Nm	2 OR 4075		

26 COVERS DIMENSIONS [mm]

Size	AxA	ØB	С	D	Port Pp - Dr	ł – – – – – – – – – – – – – – – – – – –
1 = 16	65x80	3	4	40	-	
2 = 25	85x85	5	6	40	-	$\square \square Dr \bigcup \overset{@}{\boxtimes} \underbrace{\times \stackrel{F}{\longrightarrow} \stackrel{Z}{\longrightarrow} \stackrel{Z}{\longrightarrow} \overset{@}{\boxtimes} \bigcup Pp$
3 = 32	100×100	5	6	50	-	
4 = 40	125x125	5	6	60	G 1/4"	
5 = 50	140x140	6	4	70	G 1/4"	3.5 AxA 3.5
6 = 63	180x180	6	4	80	G 3/8"	Notes:
8 = 80	ø250	8	6	80	G 3/8"	size 1 cover is not squared but retangular, dimensions 65x80 size 8 cover is not squared but circular, dimension Ø250

27 INSTALLATION DIMENSIONS [mm]



(3) = The dimensions of cable glands must be considered (see tech table KX800)

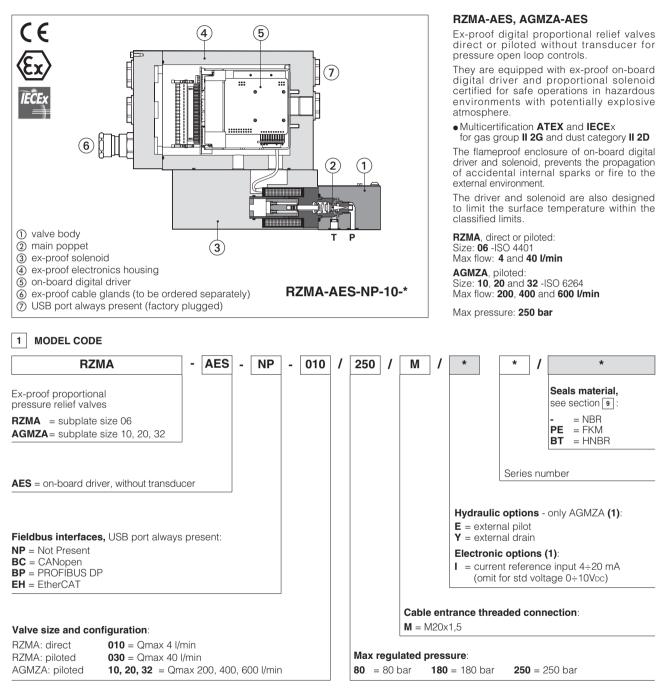
28 RELATED DOCUMENTATION

X010 X020 FX900 GS500 GS510	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO Operating and manintenance informationfor ex-proof proportional valves Programming tools Fieldbus	GX800 KX800 P006	Ex-proof pressure transducer type E-ATRA-7 Cable glands for ex-proof valves Mounting surfaces and cavities for cartridge valves
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atos

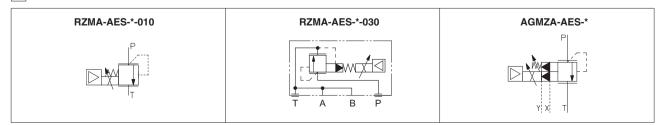
Ex-proof digital proportional relief valves

direct or piloted, with on-board driver and without transducer - ATEX and IECEx



(1) Possible combined options: /EY, /EI, /YI

2 CONFIGURATIONS AND HYDRAULIC SYMBOLS (representation according to ISO 1219-1)



3 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table FX900 and in the user manuals included in the E-SW-* programming software.

E-A-SB-USB/OPT isolator

Car

E-A-SB-USB/BTH adapter



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

5 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

6 GENERAL CHARACTERISTICS

Assembly position	Any position			
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100			
MTTFd valves according to EN ISO 13849	RZMA-010 150 years, RZMA-030 and AGMZA 75 years, see technical table P007			
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$			
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$			
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h			
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"			
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006			

7	HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C
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Valve model		RZ	RZMA		AGMZA		
Size code		010	010 030		20	32	
Valve size		0	06 10 20		20	32	
Max regulated pressure	[bar]		80 180 250				
Min regulated pressure	[bar]	see	see min. pressure / flow diagrams at sections 18 19 20				
Max pressure at port P, A, B, X	[bar]	315					
Max pressure at port T, Y	[bar]	210					
Max flow	[l/min]	4	40	200	400	600	
Response time 0-100% step signal (depending on installation) (1)	[ms]	≤ 80 ≤ 130 ≤ 145 ≤ 160				≤ 160	
Hysteresis [% of the max pressure]		≤ 1,5					
Linearity [% of the max pressure]		≤3					
Repeatability [% of the max pressur	e]		≤2				

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)							
Max power consumption	35 W	35 W						
Analog input signals	Voltage: range ± 10 VDc (24 VMAx tollerant)Input impedance: Ri > 50 k Ω Current: range ± 20 mAInput impedance: Ri = 500 Ω							
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards				
Monitor outputs	Voltage: maximum ra	nge ± 5 Voc @ max	5 mA					
Enable input	Range: 0 ÷ 9 VDC (OFF	state), 15 ÷ 24 VDC (ON	state), 9 ÷ 15 VDC (not ac	cepted); Input impedance: Ri > $87k\Omega$				
Fault output	Output range : $0 \div 24$ VDC (ON state \cong VL+ [logic power supply]; OFF state \cong 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)							
Alarms		ed/short circuit, cable b ring, power supplies lev		ce signal, over/under temperature,				
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland						
Duty factor	Continuous rating (ED	=100%)						
Tropicalization	Tropical coating on el	ectronics PCB						
Additional characteristics	Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switch protection against reverse polarity of power supply							
Electromagnetic compatibility (EMC)	IC) According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)							
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT EC 61158				
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX				

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluic	I temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$			
Recommended viscosity		20 ÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at KTF	
contamination level	longer life	ISO4406 class 16/14/11 NAS1638 class 5		catalog	
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without wa	ater	FKM	HFDU, HFDR	ISO 12922	
Flame resistant with water	(1)	NBR, HNBR	HFC	130 12922	

🕂 The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar

-max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type	RZMA, AGMZA					
Certifications		Multicertification Group II				
Solenoid certified code		ATEX OZA	IECEx A-AES			
Type examination certificate (1)	ATEX: TUV IT 18 ATEX 068 X IECEx: IECEx TPS 19.0004X					
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C Db					
Temperature class	Т6	T5		Τ4		
Surface temperature	≤ 85 °C	≤ 100	°C	≤ 135 °C		
Ambient temperature (2)	-40 ÷ +40 °C -40 ÷ +55 °C		-40 ÷ +70 °C			
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 EN 60079-1 IEC 60079-1		IEC 60079-31			
Cable entrance: threaded connection	M = M20x1,5					

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C. In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

AGMZA-*/E

3

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C T5		100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

12 CABLE GLANDS

Cable glands with threaded connections M20x1.5 for standard or armoured cables have to be ordered separately, see tech table KX600 Note: a Loctite sealant type 545, should be used on the cable gland entry threads

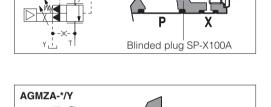
13 HYDRAULIC OPTIONS - only for AGMZA

E = External pilot option to be selected when the pilot pressure is supplied from a different line respect to the P main line.

With option E the internal connection between port P and X of the valve is plugged. The pilot pressure must be connected to the X port available on the valve's mounting surface or on main body (threaded pipe connection G 1/4").

Y = The external drain is mandatory in case the main line T is subjected to pressure peaks or it is pressurized.

The Y drain port has a threaded connection G 1/4" available on the pilot stage body.





= It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 Vpc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vpc or ±20 mÅ. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

/EY, /EI, /YI

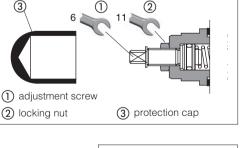
16 MECHANICAL PRESSURE LIMITER - only for AGMZA

The AGMZA are provided with mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

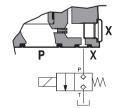
At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded.
- turn clockwise the adjustment screw (1) until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal.
- turn clockwise the adjustment screw (1) of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working.



 $\widehat{2}$

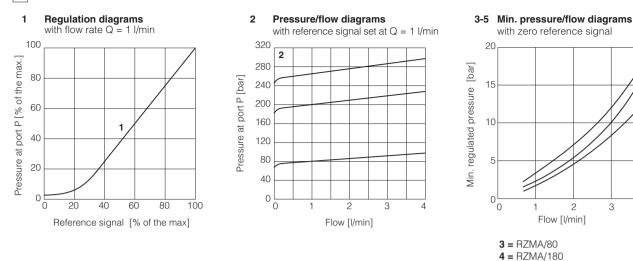


17 REMOTE PRESSURE UNLOADING - only for AGMZA

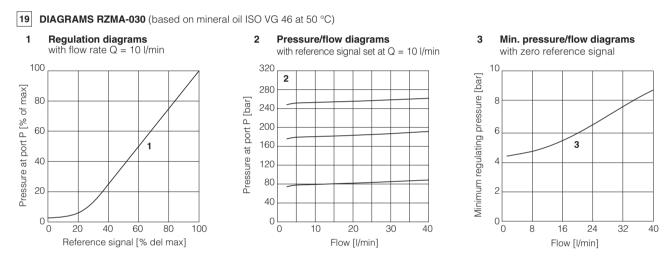
The P main line can be remotely unloaded by connecting the valve X port to a solenoid valve as shown in the below scheme (venting valve).

This function can be used in emergency to unload the system pressure by-passing the proportional control.

18 DIAGRAMS RZMA-010 (based on mineral oil ISO VG 46 at 50 °C)

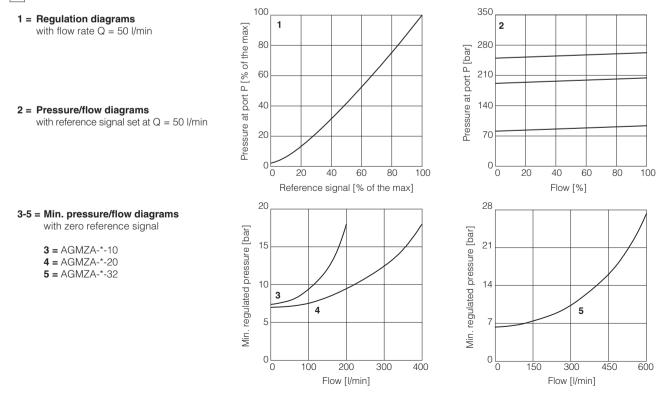


Note: the presence of counter pressure at port T can affect the pressure regulation and the minimum pressure



Note: the presence of counter pressure at port T can affect the pressure regulation and the minimum pressure

20 DIAGRAMS AGMZA (based on mineral oil ISO VG 46 at 50 °C)



4

5 = RZMA/250

21 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

21.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

21.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

21.3 Flow reference input signal (INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDc.

21.4 Monitor output signal (MONITOR)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference). Monitor output signal is factory preset according to selected valve code, default settings is $0 \div 5$ VDC (1V = 1A). Output signal can be reconfigured via software, within a maximum range of ± 5 VDC.

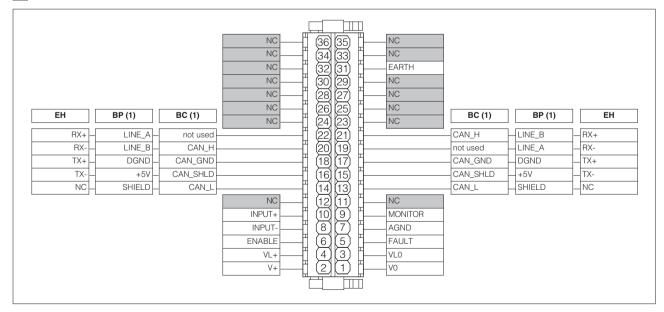
21.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

21.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

22 TERMINAL BOARD OVERVIEW



(1) For BC and BP executions the fieldbus connections have an internal pass-through connection

23 ELECTRONIC CONNECTIONS

23.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 VDC	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vpc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
Δ	6	ENABLE	Enable (24 VDc) or disable (0 VDc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
	9	MONITOR	Monitor output signal: ±5 Vpc maximum range, referred to AGND Default is: ±5 Vpc	Output - analog signal Software selectable
	10	INPUT+	Reference input signal: ± 10 Vpc / ± 20 mA maximum range Defaults are: ± 10 Vpc for standard and 4 $\div 20$ mA for /l option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

23.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply	1-2	
	2	ID	Identification	(The second sec	
B	3	3 GND_USB Sig	Signal zero data line		
	4	D-	Data line -	4 - 3 (famala)	
	5	D+	Data line +	(female)	

23.3 BC fieldbus execution connections

	CABLE ITRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
		14	CAN_L	Bus line (low)
	C1	16	CAN_SHLD	Shield
(18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)	
		22	not used	Pass-through connection (1)

E	CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
		13	CAN_L	Bus line (low)
	•	15	CAN_SHLD	Shield
	(2)	17	CAN_GND	Signal zero data line
		19	not used	Pass-through connection (1)
		21	CAN_H	Bus line (high)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

23.4 BP fieldbus execution connections

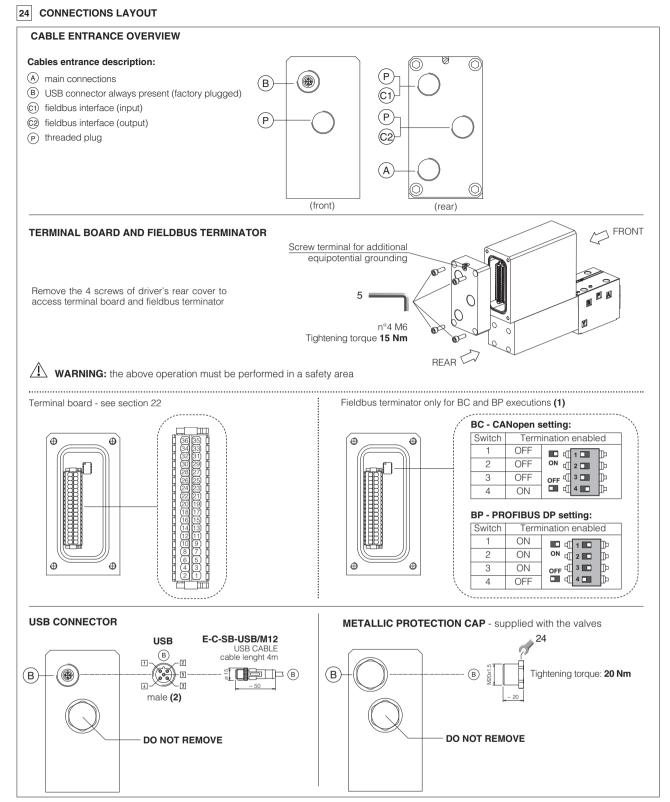
CABLE ENTRANCE	PIN	SIGNAL TECHNICAL SPECIFICATION		
C1	14	SHIELD		
	16	+5V	Power supply	
	18	DGND	Data line and termination signal zero	
	20	LINE_B	Bus line (low)	
	22	LINE_A	Bus line (high)	

23.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	14	NC	do not connect	
	16	тх-	Transmitter	
(C)1	18	TX+	Transmitter	
	20	RX-	Receiver	
(input)	22	RX+	Receiver	

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
C2	13	SHIELD		
	15	+5V	Power supply	
	17	DGND	Data line and termination signal zero	
	19	LINE_A	Bus line (high)	
	21	LINE_B	Bus line (low)	

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	TX-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

24.1 Cable glands and threaded plug - see tech table KX800

Communication	To be ordered separately				Cable entrance	Notes	
interfaces	Cable gland		Threaded plug quantity entrance		overview	10165	
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers	
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

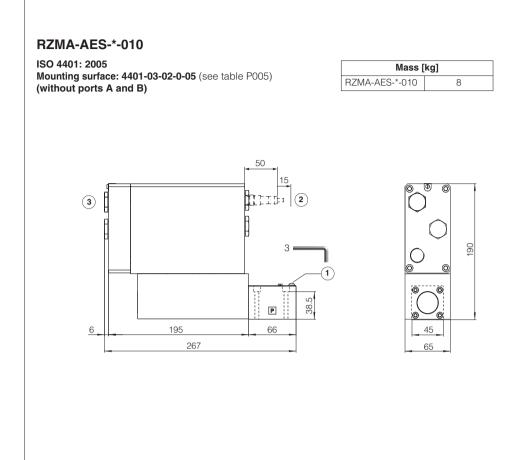
25 FASTENING BOLTS AND SEALS

25.1 RZMA valves

RZMA-AES-*-010	RZMA-AES-*-030
Fastening bolts:	Fastening bolts:
4 socket head screws M5x50 class 12.9	4 socket head screws M5x50 class 12.9
Tightening torque = 8 Nm	Tightening torque = 8 Nm
	Seals:
2 OR 108 Diameter of ports P, T: Ø 5 mm	4 OR 108 Diameter of ports P, T: Ø 7,5 mm
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm Seals: 2 OR 108

25.2 AGMZA valves

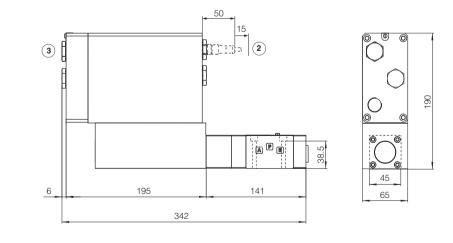
	AGMZA-AES-*-10	AGMZA-AES-*-20	AGMZA-AES-*-32
	Fastening bolts:	Fastening bolts:	Fastening bolts:
	4 socket head screws M12x35 class 12.9	4 socket head screws M16x50 class 12.9	4 socket head screws M20x60 class 12.9
	Tightening torque = 125 Nm	Tightening torque = 300 Nm	Tightening torque = 600 Nm
0	Seals:	Seals:	Seals:
	2 OR 123	2 OR 4112	2 OR 4131
	Diameter of ports P, T: Ø 14 mm	Diameter of ports P, T: Ø 24 mm	Diameter of ports P, T: Ø 28 mm
	1 OR 109/70	1 OR 109/70	1 OR 109/70
	Diameter of port X: Ø 3,2 mm	Diameter of port X: Ø 3,2 mm	Diameter of port X: Ø 3,2 mm



RZMA-AES-*-030

ISO 4401: 2005 Mounting surface: 4401-03-02-0-05 (see table P005) (ports A and B connected to port T)

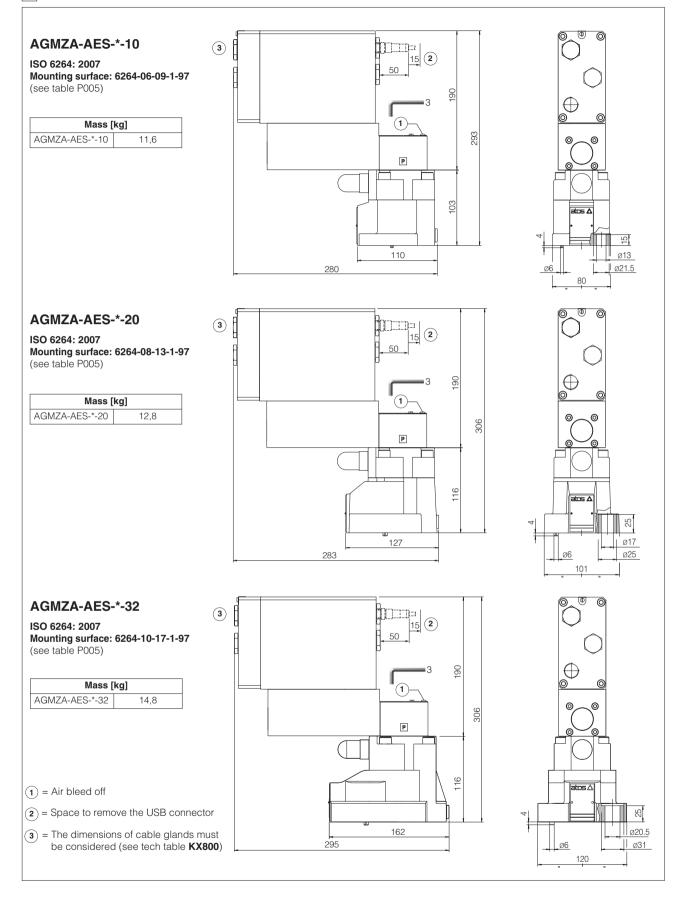
Mass [kg]				
RZMA-AES-*-030	9			



 $(\mathbf{1}) = \text{Air bleed off}$

 $(\mathbf{2})$ = Space to remove the USB connector

 $(\mathbf{\widehat{3}})\,$ = The dimensions of cable glands must be considered (see tech table KX800)



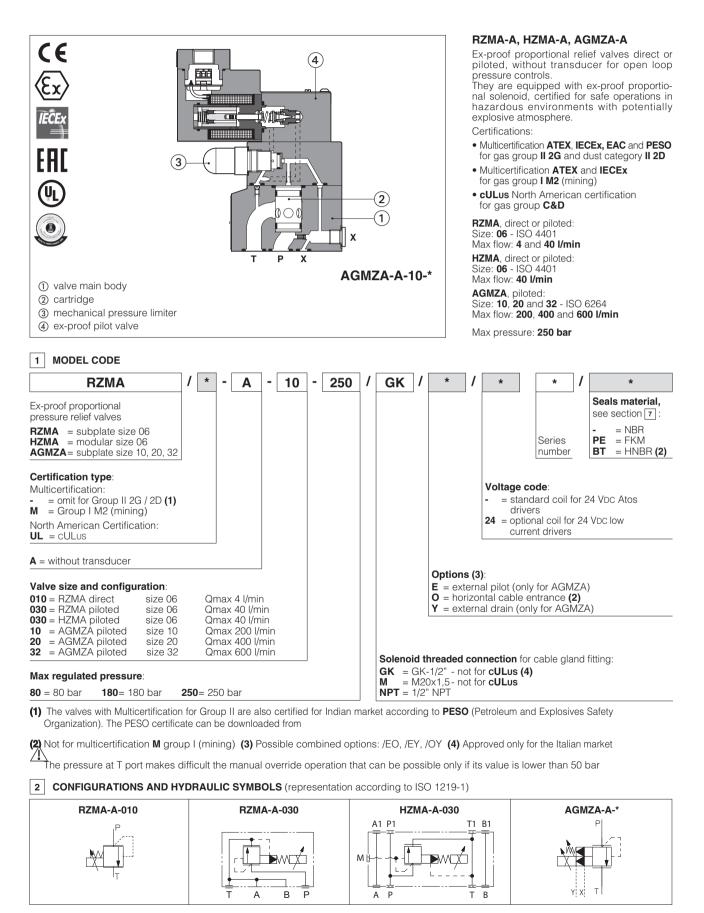
28 RELATED DOCUMENTATION

X010 X020 FX900 GS500	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO Operating and manintenance informationfor ex-proof proportional valves Programming tools	GS510 KX800 P005	Fieldbus Cable glands for ex-proof valves Mounting surfaces for electrohydraulic valves
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atos®

Ex-proof proportional relief valves

direct or piloted, without transducer - ATEX, IECEx, EAC, PESO or cULus



3 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-AS-* /A	E-BM-AES-* /A			
Туре	digital	digital			
Format	DIN-rail panel				
Data sheet	G030 GS050				

4 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	75 years; 150 years only for RZMA-010, see technical table P007				
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200h				
Compliance	Explosion proof protection, see section -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006				

5 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		RZI	AN	HZMA		AGMZA	
Size code		010	030	030	10	20	32
Valve size			06	-	10	20	32
Max regulated pressure	[bar]			80 18	80 250		
Min regulated pressure	[bar]		see min. p	essure / flow dia	grams at section	S 15 16 17	
Max pressure at port P, A, B, X	[bar]	315					
Max pressure at port T, Y	[bar]	210					
Max flow	[l/min]	4	40	40	200	400	600
Response time 0-100% step signal (depending on installation) (1)	[ms]		≤	80	≤ 130	≤ 145	≤ 160
Hysteresis[% of the max pressure]		≤ 1,5					
Linearity[% of the max pressure]		≤3					
Repeatability[% of the max pressure]		≤2					

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 3

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

6 ELECTRICAL CHARACTERISTICS

Max. power	35	35W					
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account					
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved						
Duty factor	Continuous rating (ED=100%)						
Voltage code	standard	standard option /24					
Coil resistance R at 20°C	3,2 Ω	3,2 Ω 17,6 Ω					
Max. solenoid current	2,5 A	1,1 A					

7 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$					
Recommended viscosity		20 ÷ 100 mm ² /s - max allowed range 15 ÷ 380 mm ² /s					
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF				
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard			
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524			
Flame resistant without water		FKM HFDU, HFDR		- ISO 12922			
Flame resistant with water (1)		NBR, HNBR HFC		100 12922			

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

8 CERTIFICATION DATA

Valve type	RZMA, HZMA, AGMZA		RZMA /M , HZMA /M , AGMZA /M	RZMA /UL , HZMA	RZMA /UL , HZMA /UL , AGMZA /UL	
Certifications		ation Group II EAC PESO	Multicertification Group I ATEX IECEx		merican Lus	
Solenoid certified code	MZ	A-A	MZAM-A	OZA-	A/EC	
Type examination certificate (1)	ATEX: CESI 02 IECEx: IECEx C EAC: TC RU C- PESO: P338131	ES 10.0010x IT. 08.B.01784	ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324	- E366100	
Method of protection	 ATEX, EAC EX II 2G EX d IIC T4/T3 Gb EX II 2D EX tb IIIC T135°C/T200°C Db IECEX EX d IIC T4/T3 Gb EX tb IIIC T135°C/T200°C Db PESO EX II 2G EX d IIC T4/T3 Gb 		ATEX 2014/34/EU Ex M2 Ex db Mb IECEx Ex db Mb	UL 1203 Class I, Div.I, Groups C & D Class I, Zone I, Groups IIA & IIB		
Temperature class	T4	Т3	-	T4	Т3	
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135 °C	≤ 200 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C	
Applicable standards	EN 60079-0 EN 60079-1 EN 60079-31		IEC 60079-0 IEC 60079-1 IEC 60079-31	UL 1203 and UL429, CSA 22.2 n°30-1986 CSA 22.2 n°139-13		
Cable entrance: threaded connection vertical (standard) or horizontal (option /O)		GK = GI M = M20 NPT = 1	Dx1,5	1/2"	NPT	

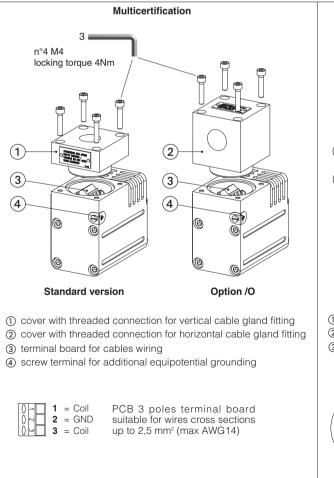
(1) The type examinator certificates can be downloaded from

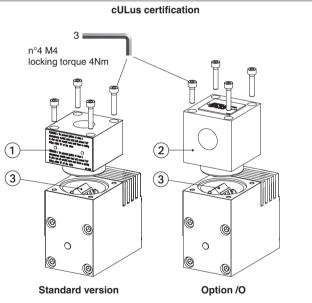
(2) The solenoids Group II and cULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

9 EX PROOF SOLENOIDS WIRING





cover with threaded connection for vertical cable gland fitting
 cover with threaded connection for horizontal cable gland fitting
 terminal board for cables wiring

Pay attention to respect the polarity

PCB 3 poles terminal board suggested cable section up to 1,5 mm²
 (max AWG16), see section 10 note 1

alternative GND screw terminal connected to solenoid housing

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper Conductors
- Bronze braided armor
- · Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C)

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

10.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Multicertification

Max ambient temperature [°C]	Temperature class		Max surface te	mperature [°C]	Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	-	90 °C	-
45 °C	-	T4	150 °C	135 °C	-	90 °C
55 °C	-	T3	150 °C	200 °C	-	110 °C
60 °C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	T3	N.A.	200 °C	N.A.	120 °C

cULus certification

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature
55 °C	Τ4	135 °C	100 °C
70 °C	T3	200 °C	100 °C

11 CABLE GLANDS - only Multicertification

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX600**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

12 OPTIONS

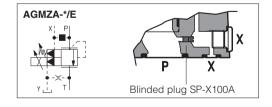
For alla valves:

O = Horizontal cable entrance to be selected in case of limited vertical space.

Only for AGMZA:

E = External pilot option to be selected when the pilot pressure is supplied from a different line respect to the P main line.

With option E the internal connection between port P and X of the valve is plugged. The pilot pressure must be connected to the X port available on the valve's mounting surface or on main body (threaded pipe connection G $\frac{1}{4}$ ").



Only for AGMZA:

 Y = The external drain is mandatory in case the main line T is subjected to pressure peaks or it is pressurized.
 The Y drain port has a threaded connection G ¹/₄" available on the pilot stage body.



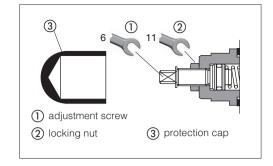
13 MECHANICAL PRESSURE LIMITER - only for AGMZA

The AGMZA are provided with mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

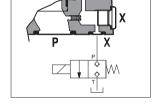
- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded.
- turn clockwise the adjustment screw () until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal.
- turn clockwise the adjustment screw (1) of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working.



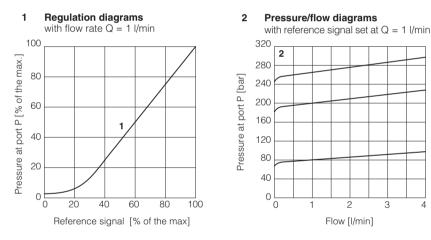
14 **REMOTE PRESSURE UNLOADING** - only for AGMZA

The P main line can be remotely unloaded by connecting the valve X port to a solenoid valve as shown in the below scheme (venting valve).

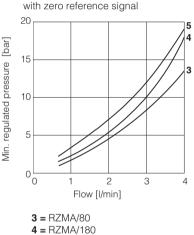
This function can be used in emergency to unload the system pressure by-passing the proportional control.



15 DIAGRAMS RZMA-010 (based on mineral oil ISO VG 46 at 50 °C)



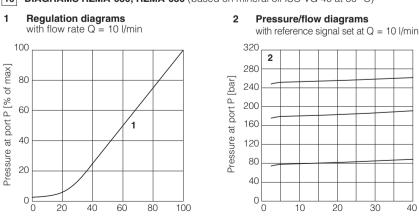
3-5 Min. pressure/flow diagrams



4

Note: the presence of counter pressure at port T can affect the pressure regulation and the minimum pressure

16 DIAGRAMS RZMA-030, HZMA-030 (based on mineral oil ISO VG 46 at 50 °C)

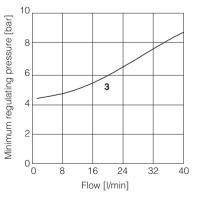


Reference signal [% del max]

Min. pressure/flow diagrams with zero reference signal

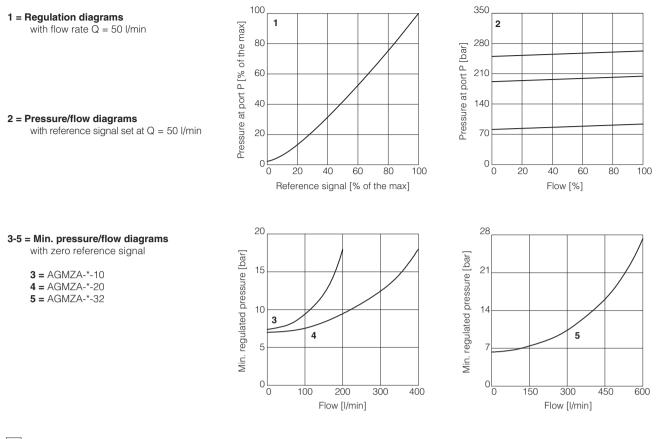
5 = RZMA/250

3



Note: the presence of counter pressure at port T can affect the pressure regulation and the minimum pressure

Flow [I/min]



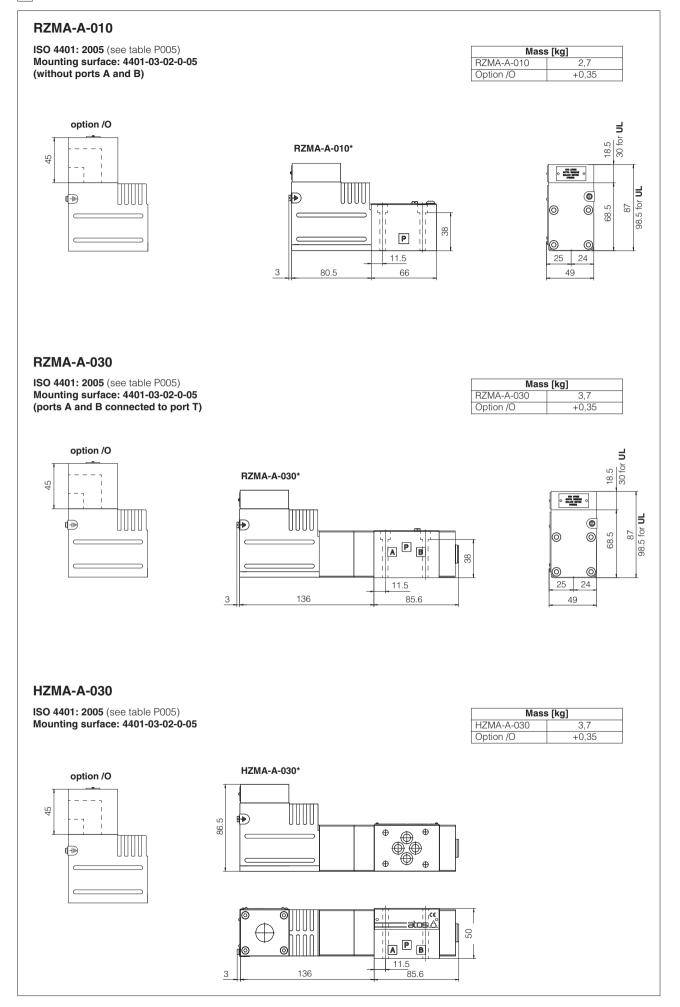
18 FASTENING BOLTS AND SEALS

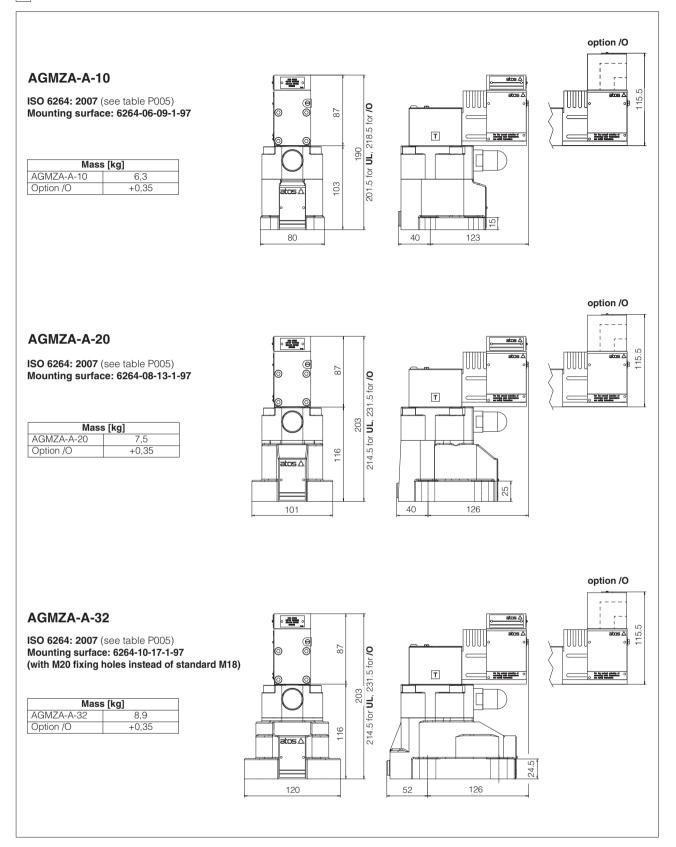
18.1 RZMA and HZMA valves

	RZMA-A-010	RZMA-A-030	HZMA-A-030
	Fastening bolts:	Fastening bolts:	Fastening bolts:
	4 socket head screws M5x50 class 12.9	4 socket head screws M5x50 class 12.9	4 socket head screws M5 class 12.9
	Tightening torque = 8 Nm	Tightening torque = 8 Nm	Tightening torque = 8 Nm
0	Seals:	Seals:	Seals:
	2 OR 108	4 OR 108	4 OR 108
	Diameter of ports P, T: Ø 5 mm	Diameter of ports P, T: Ø 7,5 mm	Diameter of ports P, A, B, T: Ø 6,5 mm

18.2 AGMZA valves

	AGMZA-A-10	AGMZA-A-20	AGMZA-A-32
	Fastening bolts:	Fastening bolts:	Fastening bolts:
	4 socket head screws M12x35 class 12.9	4 socket head screws M16x50 class 12.9	4 socket head screws M20x60 class 12.9
	Tightening torque = 125 Nm	Tightening torque = 300 Nm	Tightening torque = 600 Nm
0	Seals:	Seals:	Seals:
	2 OR 123	2 OR 4112	2 OR 4131
	Diameter of ports P, T: Ø 14 mm	Diameter of ports P, T: Ø 24 mm	Diameter of ports P, T: Ø 28 mm
	1 OR 109/70	1 OR 109/70	1 OR 109/70
	Diameter of port X: Ø 3,2 mm	Diameter of port X: Ø 3,2 mm	Diameter of port X: Ø 3,2 mm





21 RELATED DOCUMENTATION

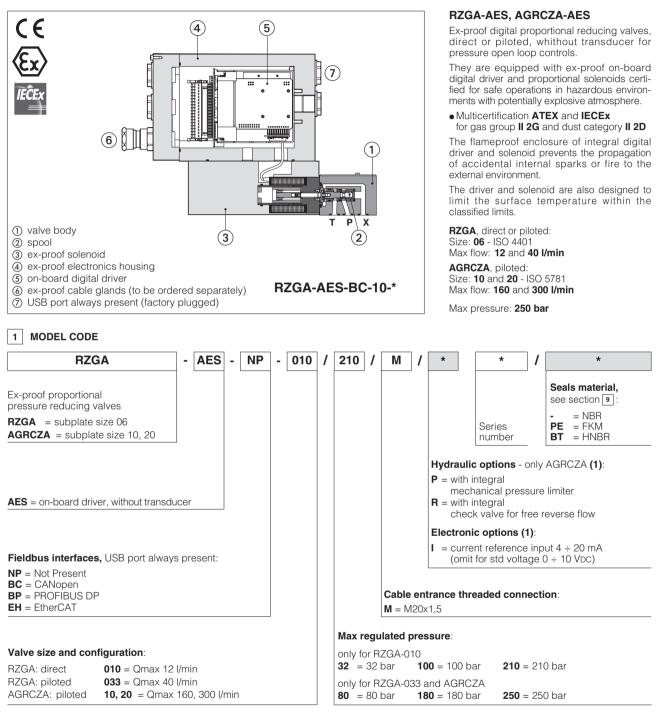
X010	Basics for electrohydraulics in hazardous environments
X020	Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO
X030	Summary of Atos ex-proof components certified to cULus
FX900	Operating and manintenance information for ex-proof proportional valves
KX800	Cable glands for ex-proof valves
P005	Mounting surfaces for electrohydraulic valves

Table FX050-2/E

atos

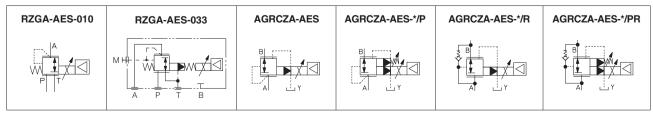
Ex-proof digital proportional reducing valves

direct or piloted, with on-board driver and without pressure transducer - ATEX and IECEx



(1) Possible combined options: /IP, /IR, /PR





3 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table FX900 and in the user manuals included in the E-SW-* programming software.



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

5 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

6 GENERAL CHARACTERISTICS

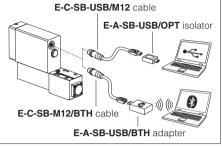
Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	RZGA-010 150 years, RZGA-033 and AGRCZA 75 years, see technical table P007					
Ambient temperature range	Standard = -20° C ÷ $+60^{\circ}$ C /PE option = -20° C ÷ $+60^{\circ}$ C /BT option = -40° C ÷ $+60^{\circ}$ C					
Storage temperature range	Standard = -20° C ÷ $+70^{\circ}$ C /PE option = -20° C ÷ $+70^{\circ}$ C /BT option = -40° C ÷ $+70^{\circ}$ C					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

7	HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C
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Valve model		RZGA AGRCZA					RCZA
Size code			010 033 10 20				20
Valve size			06		06	10	20
Max regulated pressure	[bar]	32	100	210	80	180	250
Min regulated pressure	[bar]		see min. pressure / flow diagrams at sections 16 17 18				17 18
Max pressure at port P, A, B, X	[bar]	315					
Max pressure at port T, Y	[bar]				21	0	
Max flow	[l/min]		12		40	160	300
Response time 0-100% step signal (depending on installation) (1)	[ms]	≤ 55 ≤ 70				≤ 70	
Hysteresis[% of the max pressure]		≤ 1,5					
Linearity[% of the max pressure]		≤3					
Repeatability[% of the max pressure	e]	≤ 2					

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

USB or Bluetooth connection



8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)									
Max power consumption	35 W									
Analog input signals		Voltage: range ± 10 VDC (24 VMAX tollerant)Input impedance:Ri > 50 k Ω Current: range ± 20 mAInput impedance:Ri = 500 Ω								
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards						
Monitor outputs	Voltage: maximum ra	nge ± 5 Vpc @ max	5 mA							
Enable input	Range: 0 ÷ 9 VDC (OFF	state), 15 ÷ 24 VDC (ON	state), 9 ÷ 15 VDC (not ac	cepted); Input impedance: $Ri > 87k\Omega$						
Fault output	Output range : 0 ÷ 24 external negative volta	Output range : $0 \div 24$ V _{DC} (ON state \cong VL+ [logic power supply] ; OFF state \cong 0 V) @ max 50 mA external negative voltage not allowed (e.g. due to inductive loads)								
Alarms		Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, current control monitoring, power supplies level								
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland								
Duty factor	Continuous rating (ED	=100%)								
Tropicalization	Tropical coating on el	ectronics PCB								
Additional characteristics		Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply								
Electromagnetic compatibility (EMC)	According to Directive	e 2014/30/UE (Immunity	: EN 61000-6-2; Emissio	n: EN 61000-6-3)						
Communication interface	USB Atos ASCII coding									
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX						

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	l temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at KTF		
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type	RZMA, AGMZA						
Certifications		Multicertification Group II ATEX IECEx					
Solenoid certified code		OZA	-AES				
Type examination certificate (1)	• ATEX: TUV IT 18 ATEX 068	ATEX: TUV IT 18 ATEX 068 X IECEx: IECEx TPS 19.0004X					
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C Db						
Temperature class	Т6	T5		Τ4			
Surface temperature	≤ 85 °C	≤ 100 °	С	≤ 135 °C			
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +40 °C -40 ÷ +55 °C		-40 ÷ +70 °C			
Applicable standards	EN 60079-0 EN 60079-31 IEC 60079-0 IEC 6007 EN 60079-1 IEC 60079-1						
Cable entrance: threaded connection	M = M20×1,5						

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

🕐 WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

19 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

19.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

19.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

/ A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

19.3 Flow reference input signal (INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDC for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDC.

19.4 Monitor output signal (MONITOR)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference). Monitor output signal is factory preset according to selected valve code, default settings is $0 \div 10$ VDC (1V = 1A). Output signal can be reconfigured via software, within a maximum range of ± 5 VDC.

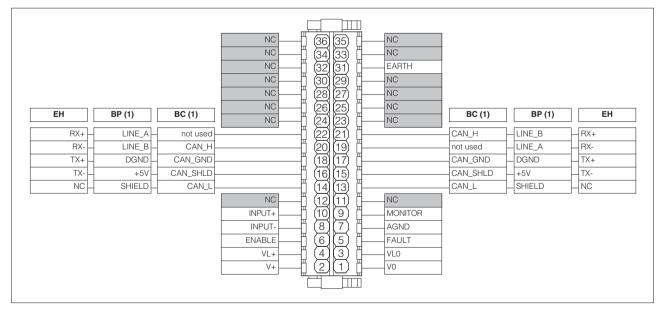
19.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

19.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

20 TERMINAL BOARD OVERVIEW



(1) For BC and BP executions the fieldbus connections have an internal pass-through connection

21 ELECTRONIC CONNECTIONS

21.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 VDc	Gnd - power supply
	2	V+	Power supply 24 Vbc	Input - power supply
	3	VL0	Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vpc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
Δ	6	ENABLE	Enable (24 VDc) or disable (0 VDc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
	9	MONITOR	Monitor output signal: ±5 Vbc maximum range, referred to AGND Default is: ±5 Vbc	Output - analog signal Software selectable
	10	INPUT+	Reference input signal: ± 10 Vpc / ± 20 mA maximum range Defaults are: ± 10 Vpc for standard and 4 $\div 20$ mA for /l option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

21.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply	12	
	2	ID	Identification	5	
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -		
	5	D+	Data line +	(female)	

21.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
()1	18	CAN_GND	Signal zero data line
01	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

	CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
Γ		13	CAN_L	Bus line (low)
		15	CAN_SHLD	Shield
	(2)	17	CAN_GND	Signal zero data line
	U L	19	not used	Pass-through connection (1)
		21	CAN_H	Bus line (high)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

21.4 BP fieldbus execution connections

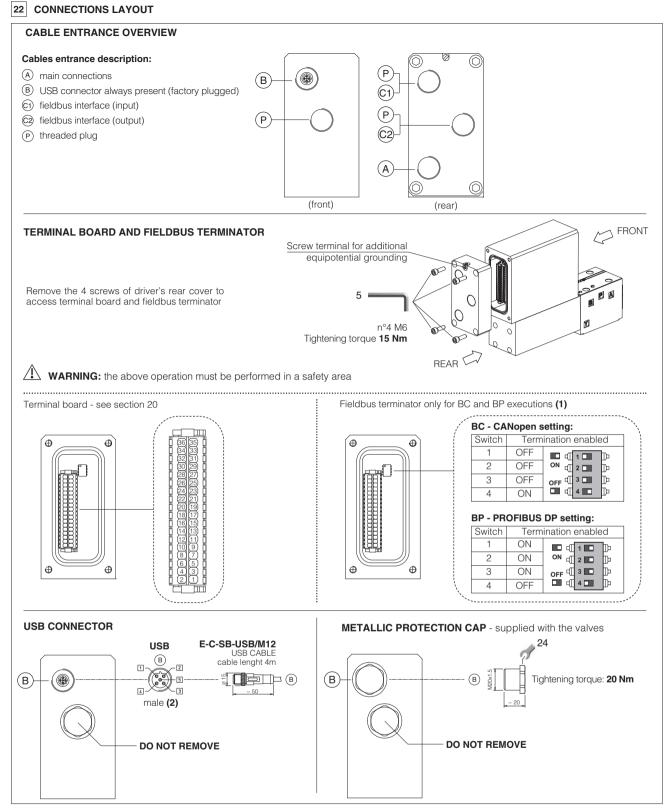
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
U .	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

CABLE ENTRANCE PIN SIGNAL TECHNICAL SPECIFICATIONS 13 SHIELD +5V 15 Power supply 22 17 DGND Data line and termination signal zero 19 LINE_A Bus line (high) 21 LINE_B Bus line (low)

21.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

22.1 Cable glands and threaded plug - see tech table KX800

Communication		be ordere			Cable entrance	Notes
interfaces		gland		ed plug	overview	NOLES
	quantity	entrance	quantity	entrance		
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

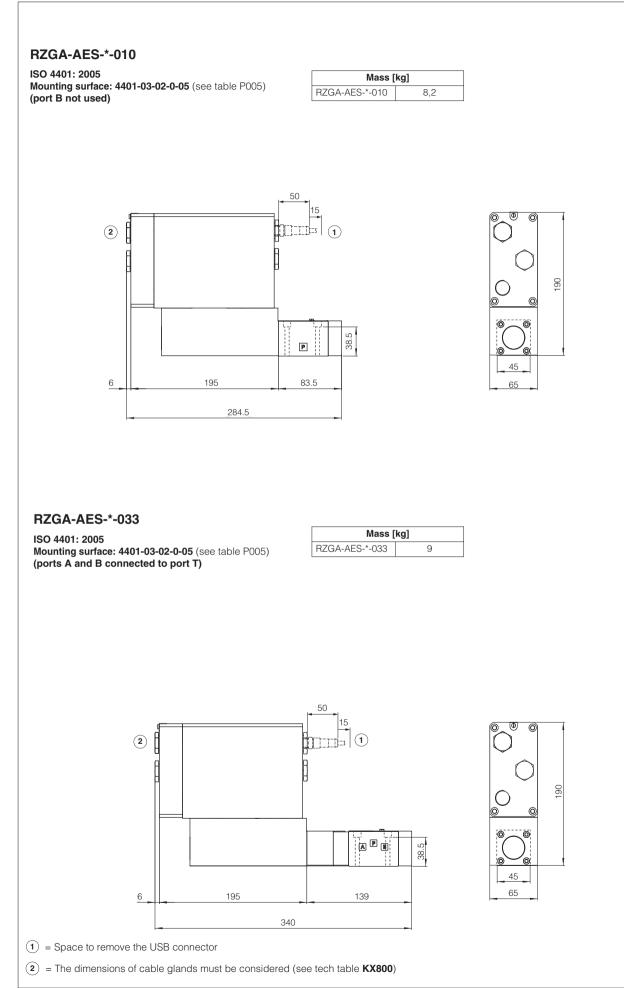
23 FASTENING BOLTS AND SEALS

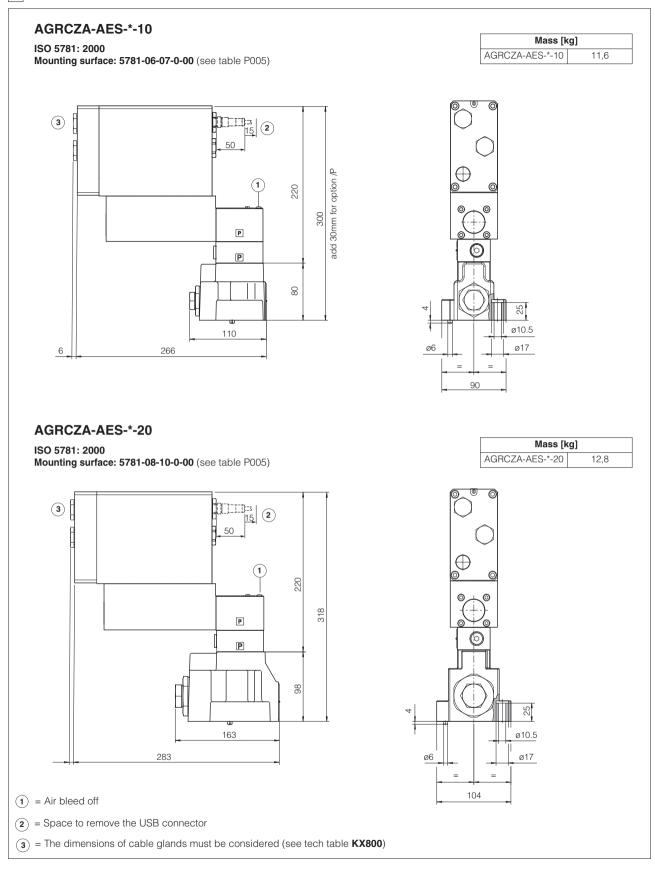
23.1 RZGA valves

	RZGA-AES-*-010	RZGA-AES-*-033
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm
0	Seals: 4 OR 108 Diameter of ports P, A, T: Ø 5 mm	Seals: 4 OR 108 Diameter of ports P, A, T: Ø 7,5 mm

23.2 AGRCZA valves

	AGRCZA-AES-*-10	AGRCZA-AES-*-20
	Fastening bolts: 4 socket head screws M10x45 class 12.9 Tightening torque = 70 Nm	Fastening bolts: 4 socket head screws M10x45 class 12.9 Tightening torque = 70 Nm
0	Seals: 2 OR 3068 Diameter of ports A, B: Ø 14 mm 2 OR 109/70 Diameter of port X, Y: Ø 5 mm	Seals: 2 OR 4100 Diameter of ports A, B: Ø 22 mm 2 OR 109/70 Diameter of port X, Y: Ø 5 mm





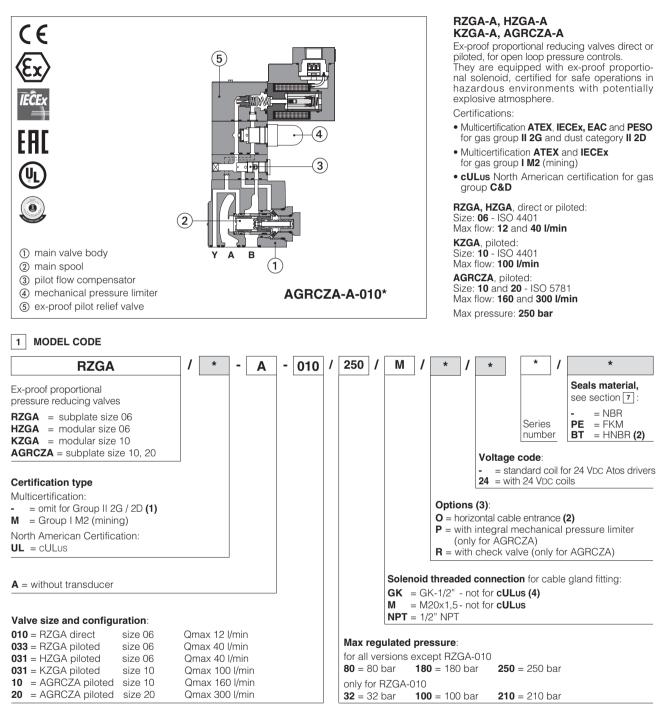
26 RELATED DOCUMENTATION

X010 X020 FX900 GS500	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO Operating and manintenance informationfor ex-proof proportional valves Programming tools	GS510 KX800 P005	Fieldbus Cable glands for ex-proof valves Mounting surfaces for electrohydraulic valves
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atos°A

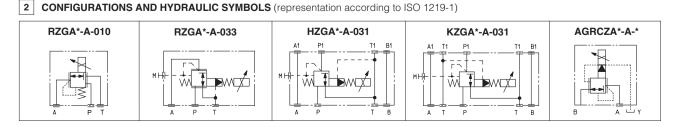
Ex-proof proportional reducing valves

direct or piloted, without transducer - ATEX, IECEx, EAC, PESO or cULus



(1) The valves with Multicertification for Group II are also certified for Indian market according to **PESO** (Petroleum and Explosives Safety Organization). The PESO certificate can be downloaded from

(2) Not for multicertification M group I (mining) (3) Possible combined options: /OP, /OR, /PR, /OPR (4) Approved only for the Italian market



3 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves. Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-AS-* /A	E-BM-AES-* /A		
Туре	digital	digital		
Format	DIN-rail panel			
Data sheet	G030	GS050		

4 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	75 years; 150 years only for RZGA-010, see technical table P007				
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200h				
Compliance	Explosion proof protection, see section -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t" RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006				

5 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		RZGA		HZGA	KZGA	AG	RCZA
Size code		010	033	031		10	20
Valve size		06		10			20
lax regulated pressure	[bar]	32; 100; 210		80	180	250	
Max pressure at port P, A, B, X [bar]				31	5		
Max pressure at port T, Y [bar]		210					
Min regulated pressure [bar]		0,8	2,5	2,5 3		1,0	
flax flow	[l/min]	12	40	40	100	160	300
Response time 0-100% step signal (depending on installation) (1) [ms]		≤ 55 ≤ 70					
Hysteresis[% of the max pressure]		≤ 1,5					
Linearity[% of the max pressure]		≤3					
epeatability[% of the max pressur	≤2						
Hysteresis[% of the max pressure]				≤;	3	210	

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 3

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

6 ELECTRICAL CHARACTERISTICS

Max. power		35W			
Insulation class	0 1	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account			
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved				
Duty factor	Continuous rating (ED=100%)	Continuous rating (ED=100%)			
Voltage code	standard	standard option /24			
Coil resistance R at 20°C	3,2 Ω	3,2 Ω 17,6 Ω			
Max. solenoid current	2,5 A	2,5 A 1,1 A			

7 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	I temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$			
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF		
contamination level longer life		ISO4406 class 16/14/11 NAS1	catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM HFDU, HFDR		ISO 12922	
Flame resistant with water	(1)	NBR, HNBR	HFC	130 12922	

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

8 CERTIFICATION DATA

Valve type	RZGA, HZGA, KZGA, AGRCZA		RZGA /M , HZGA /M , KZGA /M , AGRCZA /M	RZGA /UL , HZGA /UL , KZGA /UL , AGRCZA /UL	
Certifications	Multicertification Group II ATEX IECEX EAC PESO		Multicertification Group I ATEX IECEx	North American cULus	
Solenoid certified code	MZ	A-A	MZAM-A	OZA-A/EC	
Type examination certificate (1)			ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324 - E366100	
Method of protection			ATEX Ex I M2 Ex db I Mb IECEx Ex db I Mb	• UL 1203 Class I, Div.I, Groups C & D Class I, Zone I, Groups IIA & IIB	
Temperature class	T4	Т3	-	T4	Т3
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135 °C	≤ 200 °C
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C
Applicable standards	EN 60079-0IEC 60079-0EN 60079-1IEC 60079-1EN 60079-31IEC 60079-31		UL 1203 and UL429, CSA 22.2 n°30-1986 CSA 22.2 n°139-13		
Cable entrance: threaded connection vertical (standard) or horizontal (option /O)		GK = G M = M20 NPT = 1	Dx1,5	1/2"	NPT

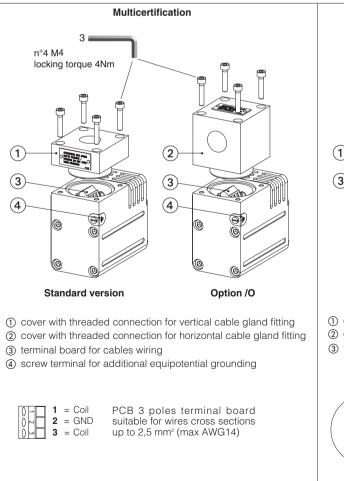
(1) The type examinator certificates can be downloaded from

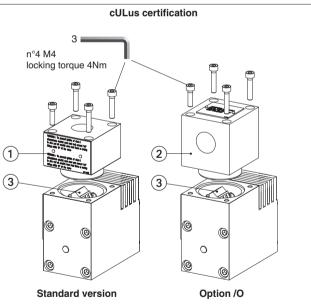
(2) The solenoids Group II and CULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

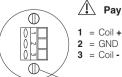
/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

9 EX PROOF SOLENOIDS WIRING





cover with threaded connection for vertical cable gland fitting
 cover with threaded connection for horizontal cable gland fitting
 terminal board for cables wiring



Pay attention to respect the polarity

 PCB 3 poles terminal board suggested cable section up to 1,5 mm² (max AWG16), see section 10 note 1

alternative GND screw terminal connected to solenoid housing

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper ConductorsBronze braided armor
- Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C)

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

10.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products. **Multicertification**

Max ambient temperature [°C]	Temperature class		Max surface temperature [°C]		Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	-	90 °C	-
45 °C	-	T4	150 °C	135 °C	-	90 °C
55 °C	-	Т3	150 °C	200 °C	-	110 °C
60 °C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	Т3	N.A.	200 °C	N.A.	120 °C

cULus certification

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature
55 °C	T4	135 °C	100 °C
70 °C	Т3	200 °C	100 °C

11 CABLE GLANDS - only Multicertification

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

12 OPTIONS

O = Horizontal cable entrance , to be selected in case of limited verical space.

P = Integral mechanical pressure limiter

The AGRCZA-*/**P** are provided with mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

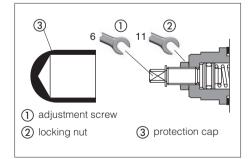
- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded.
- turn clockwise the adjustment screw () until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal.
- turn clockwise the adjustment screw (1) of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working.

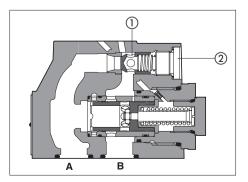
R = Integral check valve for free reverse flow

The AGRCZA-*/R are provided with integral check value for free reverse flow $A \rightarrow B$

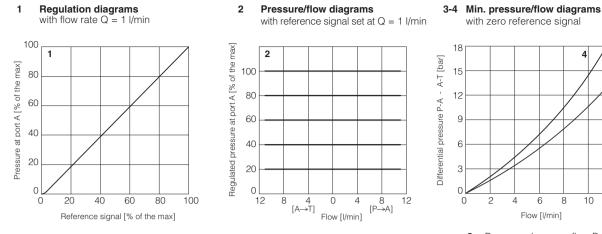
① Check valve - cracking pressure = 0,5 bar
② Plug

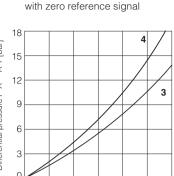
12.1 Possible combined options: /OP, /OR, /PR, /OPR





[13] DIAGRAMS RZGA-010 (based on mineral oil ISO VG 46 at 50 °C)





3 = Pressure drops vs. flow $P \rightarrow A$ **4** = Pressure drops vs. flow $A \rightarrow T$

Flow [l/min]

4 6 8 10 12

14 DIAGRAMS RZGA-033, HZGA, KZGA (based on mineral oil ISO VG 46 at 50 °C)

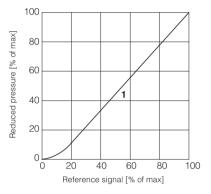
14.1 Regulation diagrams

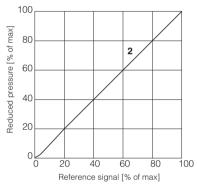
with flow rate Q = 10 l/min

1 = RZGA, HZGA **2** = KZGA

Note

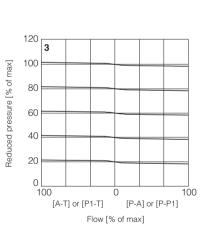
The presence of counter pressure at port T can affect the effective pressure regulation.





14.2 Pressure/flow diagrams

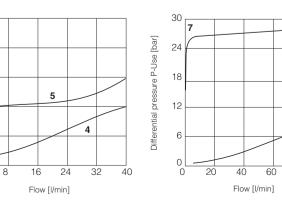
with reference pressure set with Q = 10 l/min 3 = RZGA, KZGA



14.3 Pressure drop/flow diagram

RZGA, HZGA **4** = A-T or P1-T **5** = P-P1 or P-A





6

80

100

25

20

15

10

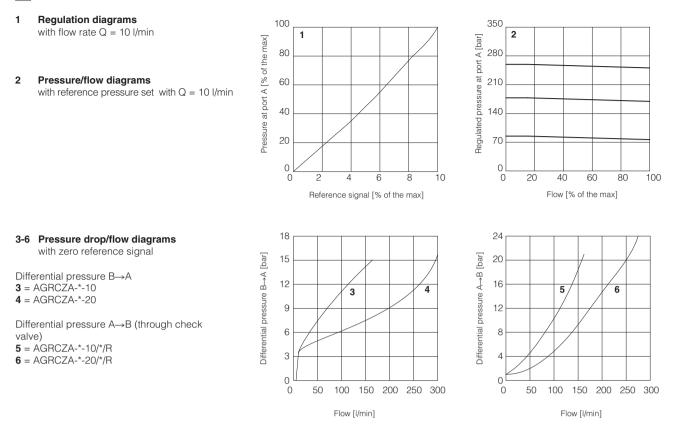
5

0

0

Differential pressure P-Use [bar]

15 DIAGRAMS AGRCZA (based on mineral oil ISO VG 46 at 50 °C)



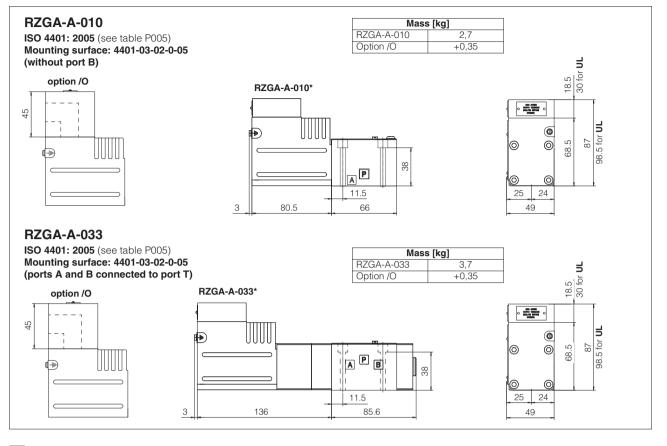
16 FASTENING BOLTS AND SEALS

16.1 RZGA, HZGA and KZGA valves

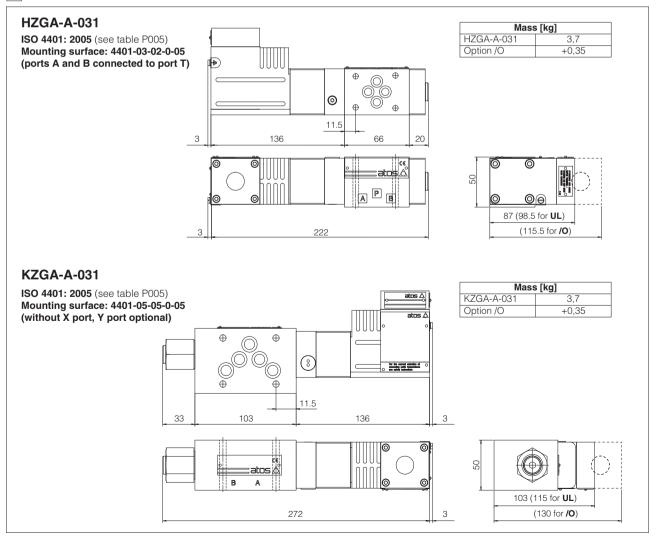
	RZGA-A-010	RZGA-A-033	HZGA-A-031	KZGA-A-031	
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M5 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6 class 12.9 Tightening torque = 16 Nm	
0	Seals: 2 OR 108 Diameter of ports P, T: Ø 5 mm (max)	Seals: 4 OR 108 Diameter of ports P, T: Ø 7,5 mm (max)	Seals: 4 OR 108 Diameter of ports P, T: Ø 7,5 mm	Seals: 5 OR 2050 Diameter of ports P, A, B, T: Ø 11,5 mm (max) 1 OR 108 Diameter of port Y: Ø 5 mm	

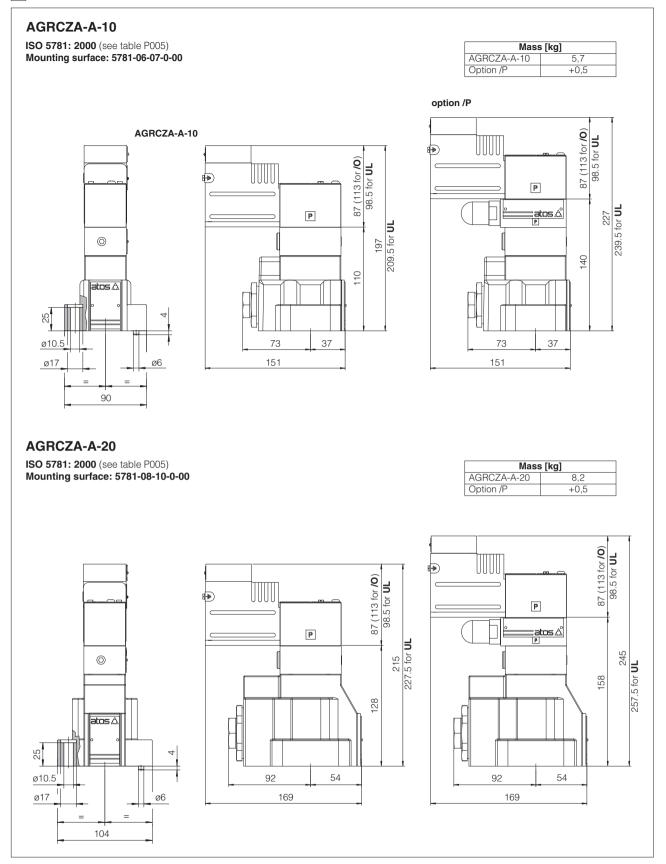
16.2 AGRCZA valves

	AGRCZA-A-10	AGRCZA-A-20
	Fastening bolts: 4 socket head screws M110x45 class 12.9 Tightening torque = 70 Nm	Fastening bolts: 4 socket head screws M110x45 class 12.9 Tightening torque = 70 Nm
0	Seals: 2 OR 3068 Diameter of ports A, B: Ø 14 mm 2 OR 109/70 Diameter of ports X, Y: Ø 5 mm	Seals: 2 OR 4100 Diameter of ports A, B: Ø 22 mm 2 OR 109/70 Diameter of ports X, Y: Ø 5 mm



18 INSTALLATION DIMENSIONS FOR HZGA and KZGA [mm]





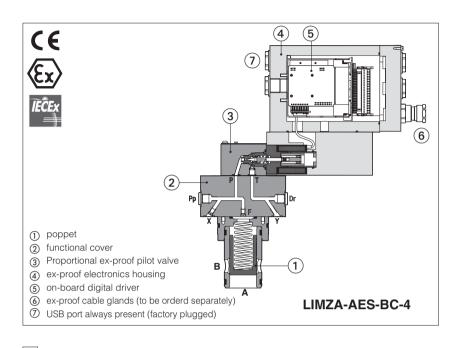
20 RELATED DOCUMENTATION

X010Basics for electrohydraulics in hazardous environmentsX020Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESOX030Summary of Atos ex-proof components certified to cULusFX900Operating and manintenance norms for ex-proof proportional valvesKX800Cable glands for ex-proof valvesP005Mounting surfaces for electrohydraulic valves

atos°A

Ex-proof digital proportional pressure cartridges

with on-board driver and without transducer - **ATEX and IECEx**



LICZA-AES, LIMZA-AES, LIRZA-AES

2-way ex-proof digital proportional pressure cartridges without transducer respectively performing: pressure compensator, relief or reducing functions.

They are equipped with ex-proof on-board digital driver and proportional solenoid certified for safe operations in hazardous environments with potentially explosive atmosphere.

Multicertification ATEX and IECEx

for gas group II 2G and dust category II 2D

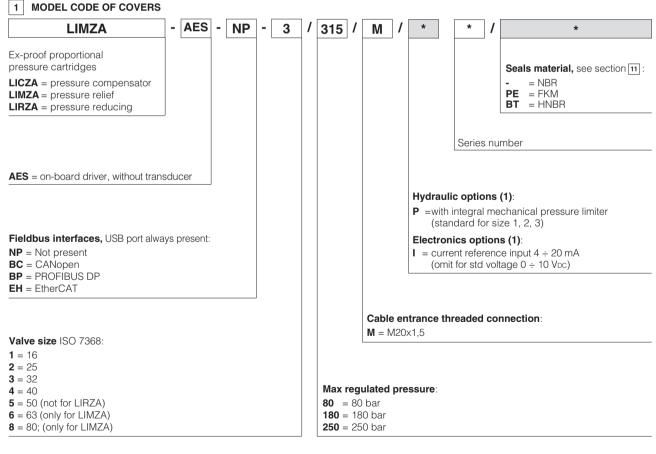
The flameproof enclosure of on-board digital driver and solenoid, prevents the propagation of accidental internal sparks or fire to the external environment.

The driver and solenoid are also designed to limit the surface temperature within the classified limits.

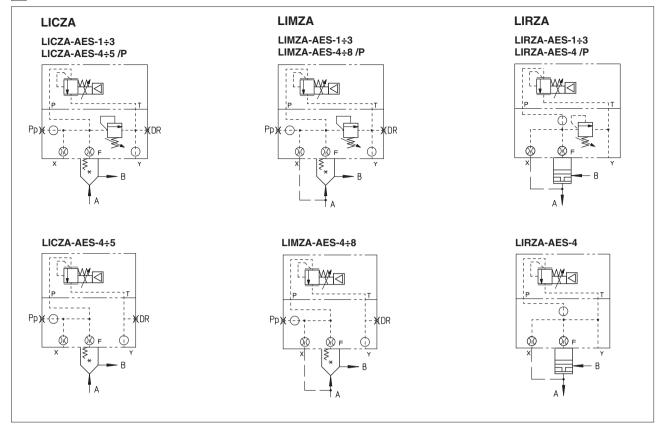
Size: 16 ÷ 80 - ISO7368

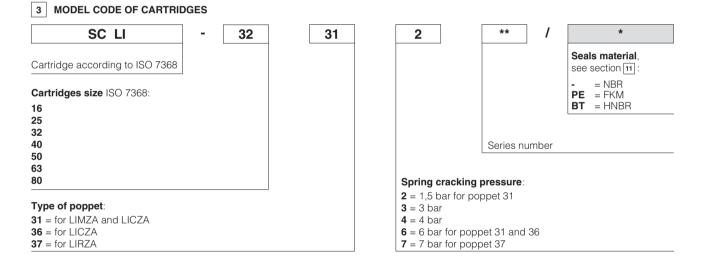
Max flow: up to 4500 l/min

Max pressure: 250 bar



(1) Possible combined options: /IP





4 TYPE OF POPPET

Type of poppet	31	36	37
Functional sketch (Hydraulic symbol)			
Typical section			
Area ratio A: Ap	1:1	1:1	1:1

5 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table FX900 and in the user manuals included in the E-SW-* programming software.

VALVE SETTINGS AND PROGRAMMING TOOLS 6

WARNING: the below operation must be performed in a safety area

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table GS003). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

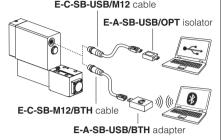
The software is available in different versions according to the driver's options (see table GS500):

			0	
E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)
E-SW-*/PQ	support:	valves with SP, SF, S	SL alternated control (e	e.g. E-SW-BASIC/PQ)
۸				

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved





7 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

8 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	75 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section 12 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

9 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model			LICZA			LIMZA					LIRZA							
Valve size [l/min]			1	2	3	4	5	1	2	3	4	5	6	8	1	2	3	4
Max flow		[bar]	200	400	750	1000	2000	200	400	750	1000	2000	3000	4500	160	300	550	800
Min regulated p	ressure									see	sectio	n 18						
Max regulated pres. at port A [bar]				80; 180; 250 80; 180; 250						80; 180; 250								
Max pressure [bar]		Ports: T, Y = 210																
Max pressure	Max pressure [bar]		Ports: P, A, B, X = 350															
Response time	0-100% step signal (1	,				< 100 + 400												
(depending on installation) [ms]		[ms]	≤ 120 ÷ 430			≤ 120 ÷ 480				≤ 120 ÷ 380								
Hysteresis [% of regulated max pres.]			≤2			≤ 1,5					≤2							
Linearity [% of regulated max pres.]			≤ 3			≤ 3					≤ 3							
Repeatibility [% of regulated max pres.]			≤2			≤2			≤2									

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

10 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal Rectified and filtered	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)						
Max power consumption	35 W	35 W						
Analog input signals	Voltage: range ±10 V Current: range ±20 r	/DC (24 VMAX tollerant) nA	Input impedance Input impedance					
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards				
Monitor outputs	Voltage: maximum ra	nge ± 5 Voc @ max	5 mA					
Enable input	Range: 0 ÷ 9 VDC (OFF	state), 15 ÷ 24 VDC (ON	state), 9 ÷ 15 VDC (not ac	cepted); Input impedance: $Ri > 87k\Omega$				
Fault output	Output range : $0 \div 24$ VDC (ON state \cong VL+ [logic power supply] ; OFF state \cong 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)							
Alarms		ed/short circuit, cable b ring, power supplies lev		ce signal, over/under temperature,				
Protection degree to DIN EN60529	IP66/67 with relevant	cable gland						
Duty factor	Continuous rating (ED	=100%)						
Tropicalization	Tropical coating on el	ectronics PCB						
Additional characteristics		Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply						
Electromagnetic compatibility (EMC)	According to Directive	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)						
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT EC 61158				
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX				

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

11 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20÷100 mm²/s - max allowed ra	20÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1638 class 5		catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without wa	ter	FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

12 CERTIFICATION DATA

Valve type	LICZA, LIMZA, LIRZA							
Certifications		Multicertification Group II ATEX IECEX						
Solenoid certified code		OZA-AES						
Type examination certificate (1)	• ATEX: TUV IT 18 ATEX 068	Х	IECEX: IEC	IECEX: IECEX TPS 19.0004X				
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C E							
Temperature class	T6	T5		T4				
Surface temperature	≤ 85 °C	≤ 100	°C	≤ 135 °C				
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +5	55 °C	-40 ÷ +70 °C				
Applicable Standards	EN 60079-0 EN 60079-31 EN 60079-1		IEC 60079-0 IEC 60079-31 IEC 60079-1					
Cable entrance: threaded connection		$\mathbf{M} = \mathbf{M}$	20x1,5					

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

13.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]	
40 °C	T6	85 °C	80 °C	
55 °C	T5	100 °C	90 °C	
70 °C	Τ4	135 °C	110 °C	

14 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

15 HYDRAULIC OPTIONS

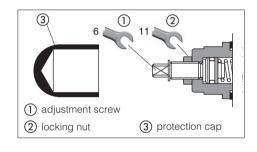
P = Integral mechanical pressure limiter (standard for size 1, 2 and 3)

The LICZA, LIMZA and LIRZA standard size 1, 2, 3 and option /P are provided with mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded.
- turn clockwise the adjustment screw () until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal.
- turn clockwise the adjustment screw ① of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working.



16 ELECTRONIC OPTIONS

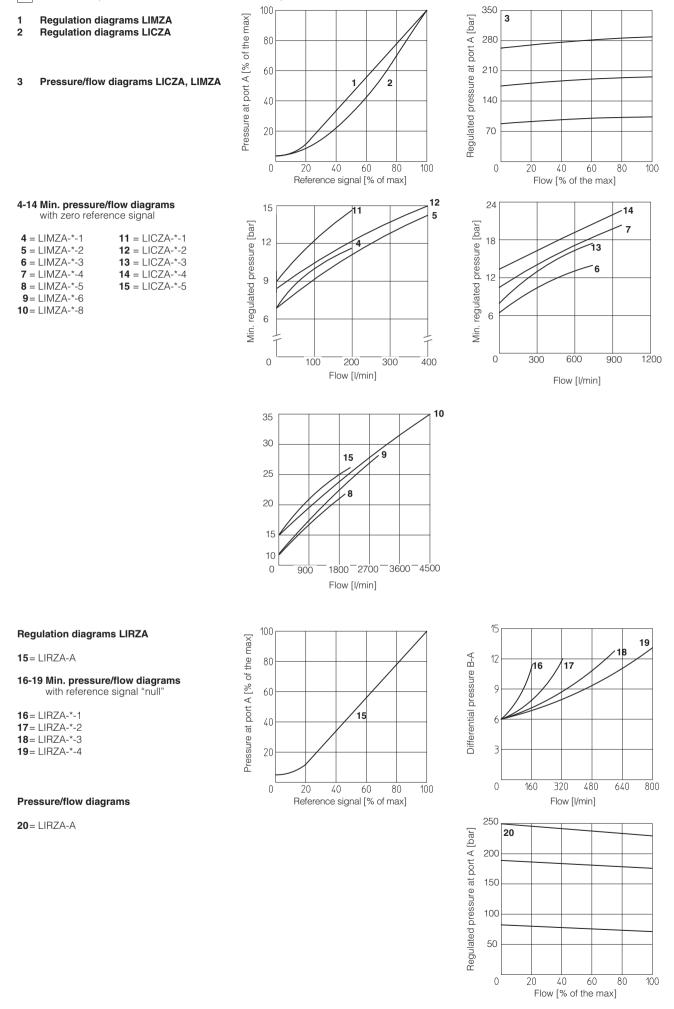
It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 Vpc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vpc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.



/IP

Т

18 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)



19 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

19.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

19.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

19.3 Flow reference input signal (INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDC for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDC.

19.4 Monitor output signal (MONITOR)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference). Monitor output signal is factory preset according to selected valve code, default settings is ± 5 VDC (1V = 1A). Output signal can be reconfigured via software, within a maximum range of $0 \div 5$ VDC.

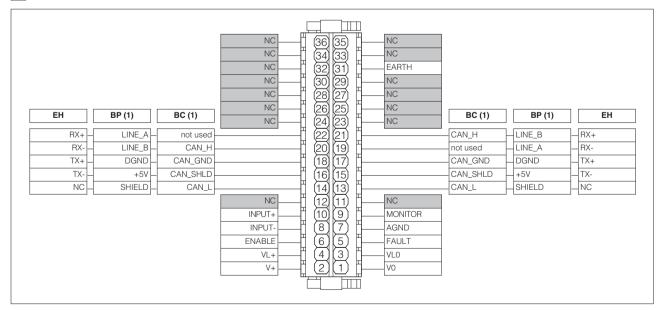
19.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

19.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

20 TERMINAL BOARD OVERVIEW



(1) For BC and BP executions the fieldbus connections have an internal pass-through connection

21 ELECTRONIC CONNECTIONS

21.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 VDC	Gnd - power supply
	2	V+	Power supply 24 Vbc	Input - power supply
	3	VL0	Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vpc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
Δ	6	ENABLE	Enable (24 VDC) or disable (0 VDC) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
	9	MONITOR	Monitor output signal: ±5 Vpc maximum range, referred to AGND Default is: ±5 Vpc	Output - analog signal Software selectable
	10	INPUT+	Reference input signal: $\pm 10 \text{ Vbc} / \pm 20 \text{ mA}$ maximum range Defaults are: $\pm 10 \text{ Vbc}$ for standard and $4 \div 20 \text{ mA}$ for /l option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

21.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply		
	2	ID	Identification	∫ ((°⊂)) s	
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -		
	5	D+	Data line +	(female)	

21.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	14	CAN_L	Bus line (low)	
	16	CAN_SHLD	Shield	
()1	18	CAN_GND	Signal zero data line	
	20	CAN_H	Bus line (high)	
	22	not used	Pass-through connection (1)	

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	13	CAN_L	Bus line (low)	
	15 CA		Shield	
C2	17	CAN_GND	Signal zero data line	
	19	not used	Pass-through connection (1)	
	21	CAN_H	Bus line (high)	

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

21.4 BP fieldbus execution connections

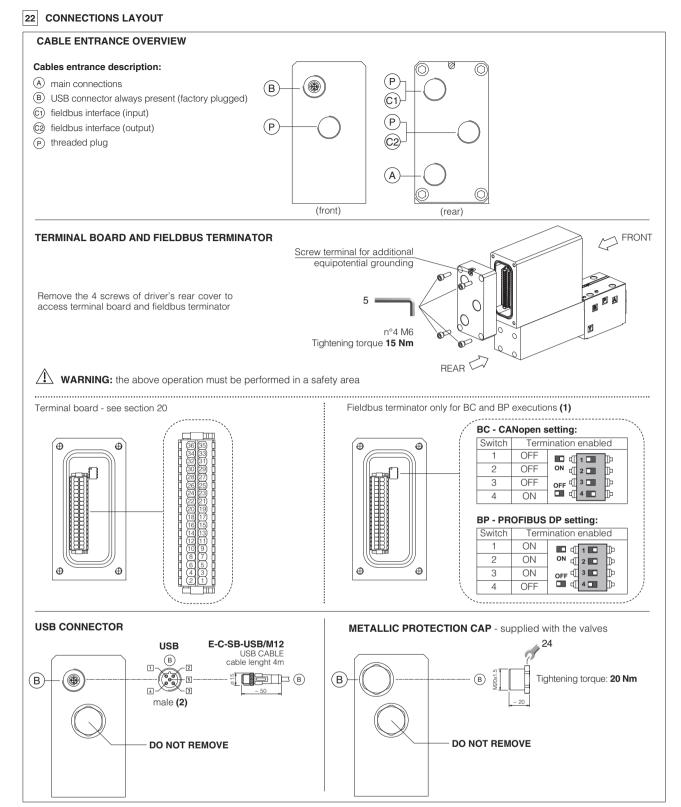
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	14	SHIELD		
	16	+5V	Power supply	
(C)1	18	DGND	Data line and termination signal zero	
	20	LINE_B	Bus line (low)	
	22	LINE_A	Bus line (high)	

21.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	
	14	NC	do not connect	
	16	тх-	Transmitter	
(C1)	18	TX+	Transmitter	
	20	RX-	Receiver	
(input)	22	RX+	Receiver	

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver



(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

22.1 Cable glands and threaded plug - see tech table KX800

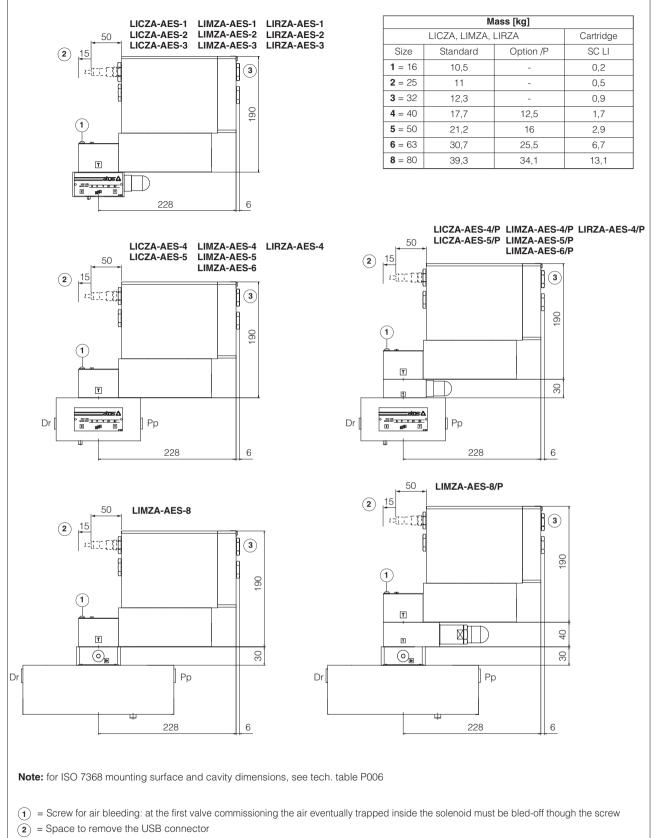
Communication	То	be ordere	d separat	ely	Cable entrance		
interfaces		gland entrance	Thread quantity		overview	Notes	
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers	
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

23 FASTENING BOLTS AND SEALS

Туре	Size	Fastening bolts	Seals
	1 = 16	4 socket head screws M8x45 class 12.9 Tightening torque = 35 Nm	2 OR 108
LIMZA LICZA	2 = 25	4 socket head screws M12x45 class 12.9 Tightening torque = 125 Nm	2 OR 108
LIRZA	3 = 32	4 socket head screws M16x55 class 12.9 Tightening torque = 300 Nm	2 OR 2043
	4 = 40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	2 OR 3043
LIMZA LICZA	5 = 50	4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	2 OR 3043
LIMZA	6 = 63 4 socket head screws M30x90 class 12.9 Tightening torque = 2100 Nm		2 OR 3050
LIWZA	8 = 80	8 socket head screws M24x90 class 12.9 Tightening torque = 1000 Nm	2 OR 4075

24 COVERS DIMENSIONS [mm]

Size	AxA	ØB	С	D	Port Pp - Dr	ļ
1 = 16	65×80	3	4	40	-	
2 = 25	85x85	5	6	40	-	$\square Dr \qquad \bigcirc \mathbb{P} \qquad \mathbb$
3 = 32	100×100	5	6	50	-	
4 = 40	125x125	5	6	60	G 1/4"	ØB
5 = 50	140x140	6	4	70	G 1/4"	- 0 -++ 3.5 AxA 3.5
6 = 63	180x180	6	4	80	G 3/8"	Notes:
8 = 80	ø250	8	6	80	G 3/8"	size 1 cover is not squared but retangular, dimensions 65x80 size 8 cover is not squared but circular, dimension Ø250



(3) = The dimensions of cable glands must be considered (see tech table **KX800**)

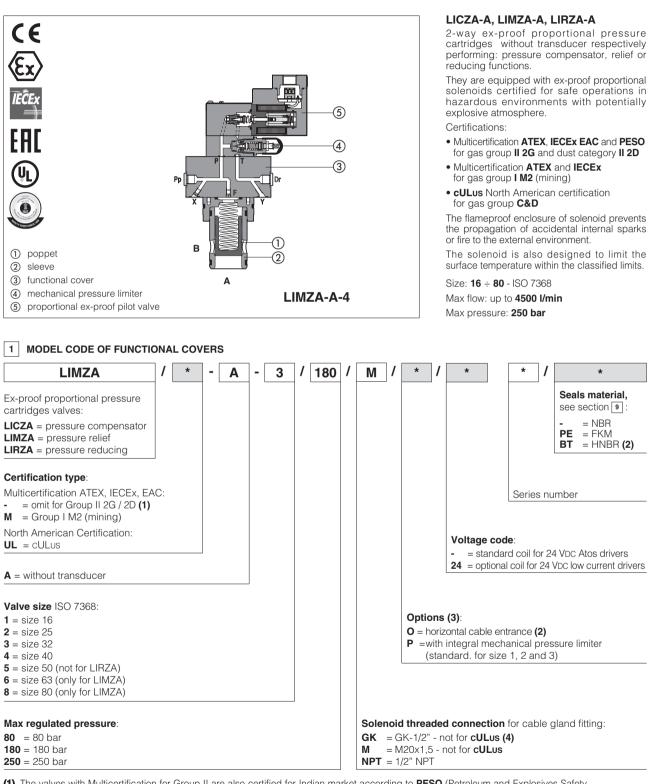
26 RELATED DOCUMENTATION

X010 X020 FX900 GS500	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO Operating and manintenance informationfor ex-proof proportional valves Programming tools	GS510 KX800 P006	Fieldbus Cable glands for ex-proof valves Mounting surfaces and cavities for cartridge valves
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atos°A

Ex-proof proportional pressure cartridges

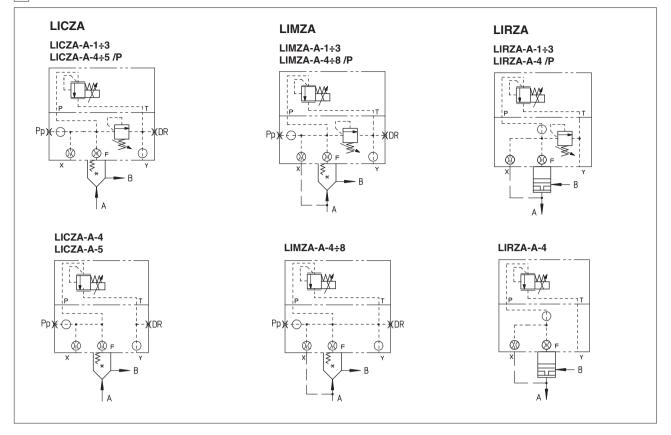
without transducer - ATEX, IECEx, EAC, PESO or cULus

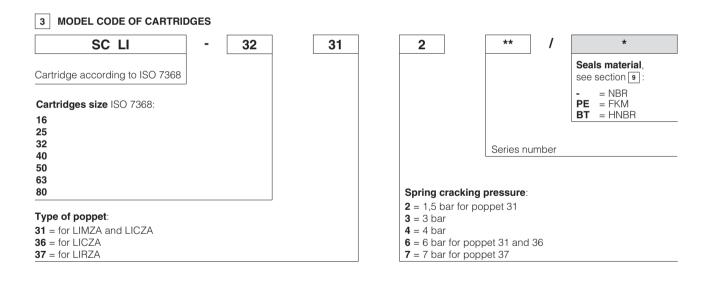


(1) The valves with Multicertification for Group II are also certified for Indian market according to **PESO** (Petroleum and Explosives Safety Organization). The PESO certificate can be downloaded from

(2) Not for multicertification M group I (mining) (3) Possible combined options: /OP (4) Approved only for italian market

🗥 The pressure at T port makes difficult the manual override operation that can be possible only if its value is lower than 50 bar





4 TYPE OF POPPET

Type of poppet	31	36	37
Functional sketch (Hydraulic symbol)			
Typical section			
Area ratio A: AP	1:1	1:1	1:1

5 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-AS-* /A	E-BM-AES-* /A		
Туре	digital	digital		
Format	DIN-rail panel			
Data sheet	G030	GS050		

6 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	150 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200h					
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model			LICZA				LIMZA					LIRZA						
Valve size [l/min]		1	2	3	4	5	1	2	3	4	5	6	8	1	2	3	4	
Max flow [bar]			200	400	750	1000	2000	200	400	750	1000	2000	3000	4500	160	300	550	800
Min regulated pressure				see section 15														
Max regulated pres. at port A [bar]			80	; 180; :	250				80	; 180; 2	250		80; 180; 250					
Max pressure			Ports: T, Y = 210															
Max pressure		[bar]	Ports: P, A, B, X = 315															
Response time 0-100% step signal (1) (depending on installation) [ms]		≤ 120 ÷ 430					≤ 120 ÷ 480						≤ 120 ÷ 380					
Hysteresis [% of regulated max pres.]		≤2				≤ 1,5						≤2						
Linearity [% of regulated max pres.]		≤ 3			≤ 3						≤3							
Repeatibility [% of regulated max pres.]		≤2			≤ 2				≤2									

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 5

(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

8 ELECTRICAL CHARACTERISTICS

Max. power	35	35W					
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account					
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved						
Duty factor	Continuous rating (ED=100%)	Continuous rating (ED=100%)					
Voltage code	standard	option /24					
Coil resistance R at 20°C	3,2 Ω	17,6 Ω					
Max. solenoid current	2,5 A	1,1 A					

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$					
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s					
Max fluid normal operation		ISO4406 class 18/16/13 NAS	see also filter section at KTF				
contamination level	longer life	ISO4406 class 16/14/11 NAS	catalog				
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard			
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524			
Flame resistant without wa	ter	FKM	HFDU, HFDR	100 10000			
Flame resistant with water	(1)	NBR, HNBR	HFC	ISO 12922			

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type	DF	ŻĄ	DPZA /M	DPZ	A/UL	
Certifications		tion Group II EAC PESO	Multicertification Group I ATEX IECEx	North American cULus		
Solenoid certified code	OZ	A-A	OZAM-A	OZA	-A/EC	
Type examination certificate (1)	ATEX: CESI 02 IECEx: IECEx C EAC: TC RU C- PESO P338131	ES 10.0010x	ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324 - E366100		
Method of protection	ATEX, EAC Ex II 2G Ex d I Ex II 2D Ex tb IIIC	IC T4/T3 Gb T135°C/T200°C Db	ATEX Ex M2 Ex db Mb IECEx	UL 1203 Class I, Div.I, Groups C & D Class I, Zone I, Groups IIA & IIB		
	IECEx Ex d IIC T4/T3 Gb Ex tb IIIC T135°C/T200°C Db EAC Ex II 2G Ex d IIC T4/T3 Gb		Ex db I Mb			
Temperature class	T4	Т3	-	T4	Т3	
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135 °C	≤ 200 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C	
Applicable standards	EN 60079-0 EN 60079-1 EN 60079-31		IEC 60079-0 IEC 60079-1 IEC 60079-31	UL 1203 and UL429, CSA 22.2 n°30-1986 CSA 22.2 n°139-13		
Cable entrance: threaded connection vertical (standard) or horizontal (option /O)		$\mathbf{M} = \mathbf{M}$	GK-1/2" 20x1,5 : 1/2" NPT	1/2"	NPT	

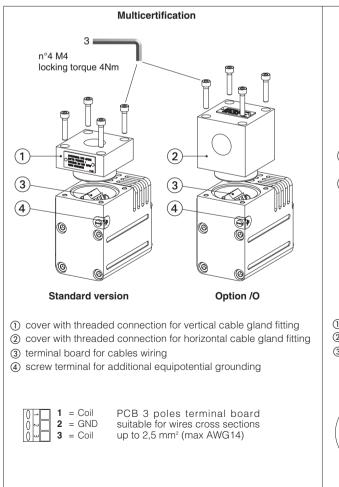
(1) The type examinator certificates can be downloaded from

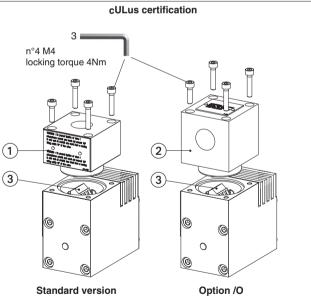
(2) The solenoids Group II and cULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

11 EX PROOF SOLENOIDS WIRING OF VALVES - A without integral driver





cover with threaded connection for vertical cable gland fitting
 cover with threaded connection for horizontal cable gland fitting
 terminal board for cables wiring

Pay
 Pay
 1 = Coil +
 2 = GND
 3 = Coil -

Pay attention to respect the polarity

 PCB 3 poles terminal board suggested cable section up to 1,5 mm² (max AWG16), see section 10 note 1

alternative GND screw terminal connected to solenoid housing

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper ConductorsBronze braided armor
- Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C)

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

12.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products. **Multicertification**

Max ambient temperature [°C]	Tempera	ture class	Max surface te	mperature [°C]	Min. cable temperature [°C]		
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II	
40 °C	-	T4	150 °C	135 °C	90 °C	90 °C	
45 °C	-	T4	-	135 °C	-	95 °C	
55 °C	-	Т3	-	200 °C	-	110 °C	
60 °C	-	-	150 °C	-	110 °C	-	
70 °C	N.A.	T3	N.A.	200 °C	N.A.	120 °C	

cULus certification

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature
55 °C	T4	135 °C	100 °C
70 °C	Т3	200 °C	100 °C

13 CABLE GLANDS - only Multicertification

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

14 OPTIONS

O = Horizontal cable entrance, to be selected in case of limited verical space.

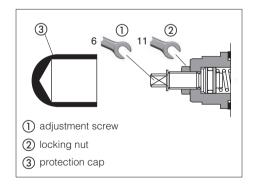
P = Integral mechanical pressure limiter (standard for size 1, 2 and 3)

The LICZA-A*, LIMZA-A* and LIRZA-A* standard size 1, 2, 3 and option /P are provided with mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

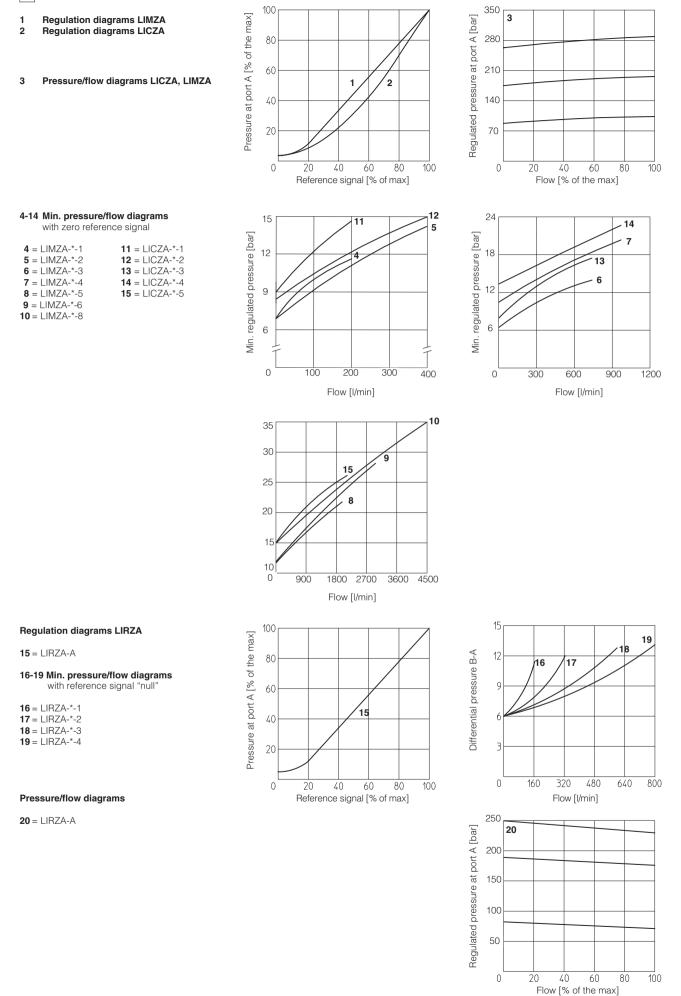
For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded.
- turn clockwise the adjustment screw () until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal.
- turn clockwise the adjustment screw (1) of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working.



14.1 Possible combined options: /OP

15 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

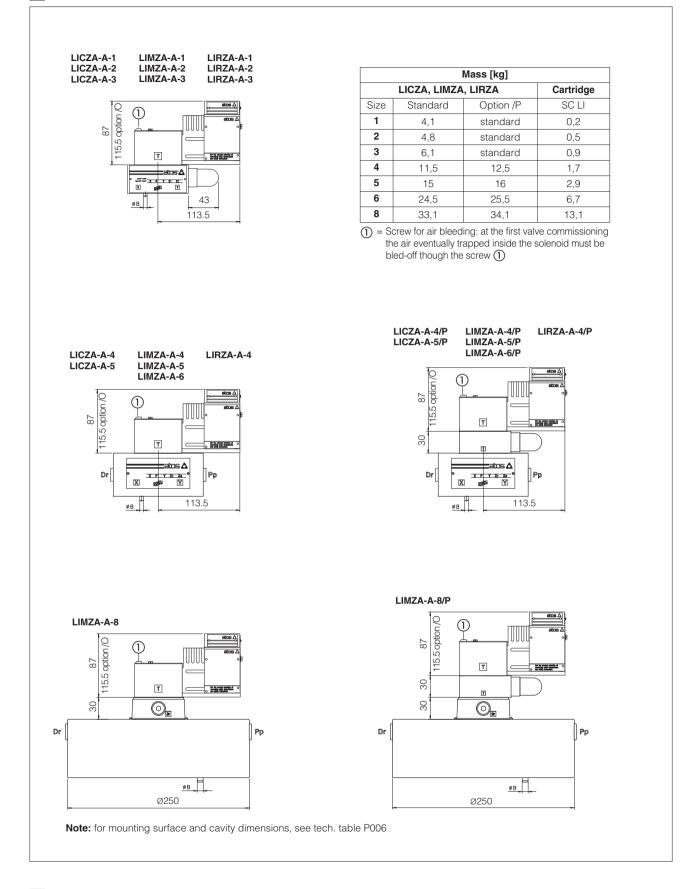


16 FASTENING BOLTS AND SEALS

Туре	Size	Fastening bolts	Seals
	1 = 16	4 socket head screws M8x45 class 12.9 Tightening torque = 35 Nm	2 OR 108
LIMZA LICZA	2 = 25	4 socket head screws M12x45 class 12.9 Tightening torque = 125 Nm	2 OR 108
LIRZA	3 = 32	4 socket head screws M16x55 class 12.9 Tightening torque = 300 Nm	2 OR 2043
	4 = 40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	2 OR 3043
LIMZA LICZA	5 = 50	4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	2 OR 3043
LIMZA	6 = 63 4 socket head screws M30x90 class 12.9 Tightening torque = 2100 Nm		2 OR 3050
LIMZA	8 = 80	8 socket head screws M24x90 class 12.9 Tightening torque = 1000 Nm	2 OR 4075

17 COVERS DIMENSIONS [mm]

Size	AxA	ØB	С	D	Port Pp - Dr	Į
1 = 16	65×80	3	4	40	-	atos:A
2 = 25	85x85	5	6	40	-	$\square Dr \mid \qquad \overset{@}{\qquad \underbrace{\mathbf{x} \ } \underbrace{\mathbf{r} \ } \underbrace{\mathbf{y}}^{\mathbf{r}} \qquad \overset{@}{\qquad } \qquad \overset{Dr}{\qquad } Pp$
3 = 32	100×100	5	6	50	-	
4 = 40	125x125	5	6	60	G 1/4"	
5 = 50	140x140	6	4	70	G 1/4"	3.5 AxA 3.5
6 = 63	180x180	6	4	80	G 3/8"	Notes:
8 = 80	ø250	8	6	80	G 3/8"	size 1 cover is not squared but retangular, dimensions 65x80 size 8 cover is not squared but circular, dimension ø250



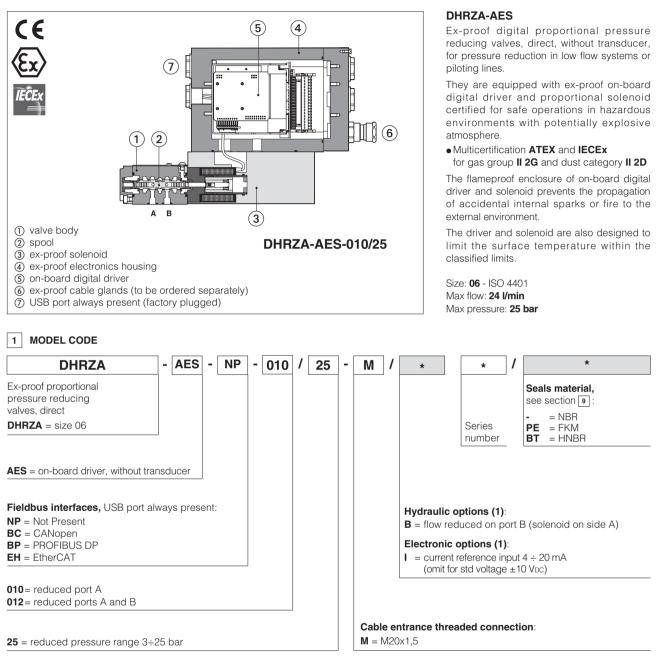
19 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments
X020	Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO
X030	Summary of Atos ex-proof components certified to cULus
FX900	Operating and manintenance information for ex-proof proportional valves
KX800	Cable glands for ex-proof valves
P006	Mounting surfaces and cavities for cartridge valves

atos

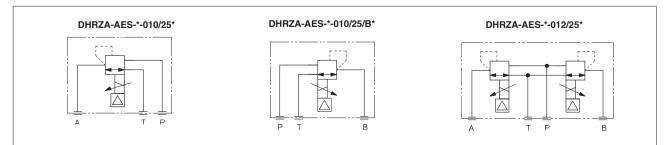
Ex-proof digital proportional reducing valves

direct, with on-board driver and without transducer - ATEX and IECEx



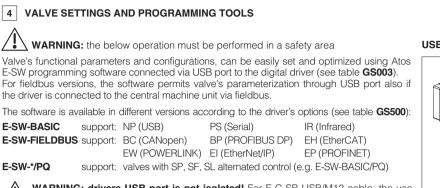
(1) Possible combined options: /BI

2 CONFIGURAZIONS AND HYDRAULIC SYMBOLS (rapresentation according to ISO 1219-1)



3 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

5 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

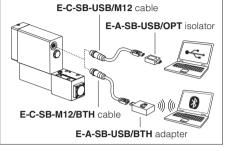
6 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	150 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

7 HYDRAULIC CHARACTERISTICS

Max regulated pressure (Q=1 l/min) [bar]	25
Min. regulated pressure (Q=1 I/min) [bar]	3
Max. pressure at port P [bar]	315
Max. pressure at port T [bar]	210
Max. flow [l/min]	24
Response time 0-100% step signal [ms] (depending on installation)	≤ 45
Hysteresis [% of the max pressure]	≤ 1,5
Linearity [% of the max pressure]	≤3
Repeatability [% of the max pressure]	≤2

USB or Bluetooth connection



8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal Rectified and filtered	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)					
Max power consumption	35 W	35 W					
Analog input signals	Voltage: range ±10 V Current: range ±20 r	/DC (24 VMAX tollerant) nA	Input impedance Input impedance				
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards			
Monitor outputs	Voltage: maximum ra	nge ± 5 Voc @ max	5 mA				
Enable input	Range: 0 ÷ 9 VDC (OFF	state), 15 ÷ 24 VDC (ON	state), 9 ÷ 15 VDC (not ac	cepted); Input impedance: $Ri > 87k\Omega$			
Fault output	Output range : 0 ÷ 24 external negative volta	Output range : $0 \div 24$ VDC (ON state \cong VL+ [logic power supply] ; OFF state \cong 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)					
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, current control monitoring, power supplies level, pressure transducer failure (/W option)						
Protection degree to DIN EN60529	IP66/67 with relevant cable gland						
Duty factor	Continuous rating (ED	=100%)					
Tropicalization	Tropical coating on el	ectronics PCB					
Additional characteristics	Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply						
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)						
Communication interface	USB CANopen PROFIBUS DP EtherCAT Atos ASCII coding EN50325-4 + DS408 EN50170-2/IEC61158 EC 61158						
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX			

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature		NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid	Max fluid normal operation		ISO4406 class 18/16/13 NAS1638 class 7 s			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM HFDU, HFDR		ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar

-max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type	DHRZA				
Certifications	Multicertification Group II ATEX IECEx				
Solenoid certified code	OZA-AES				
Type examination certificate (1)	ATEX: TUV IT 18 ATEX 068 X IECEx: IECEx TPS 19.0004X				
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db IECEx Ex db IIC T6/T5/T4 Gb Ex tb IIIC T85°C/T100°C/T135°C Db				
Temperature class	Т6	Т5		T4	
Surface temperature	≤ 85 °C	≤ 100	°C	≤ 135 °C	
Ambient temperature (2)	-40 ÷ +40 °C -40 ÷ +55 °C -		-40 ÷ +70 °C		
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079-31:2013 EN 60079-1 IEC 60079-1 IEC 60079-1				
Cable entrance: threaded connection	M = M20×1,5				

(1) The type examinator certificates can be downloaded from

(1) The driver and solenoids are certified for minimum ambient temperature -40°C. In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification.

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	T4	135 °C	110 °C

12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX600 Note:** a Loctite sealant type 545, should be used on the cable gland entry threads

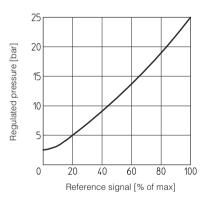
13 HYDRAULIC OPTIONS

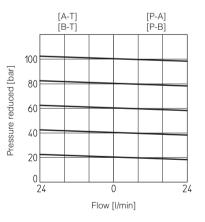
B = Solenoid, integral electronics and position transducer at side of port A of the main stage. For hydraulic configuration vs reference signal, see 15.1

14 ELECTRONIC OPTIONS

I = It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 Vbc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vbc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

15 DIAGRAMS based on mineral oil ISO VG 46 at 50°C





16 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

16.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

16.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

16.3 Flow reference input signal (INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDc.

16.4 Monitor output signal (MONITOR)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, default settings is $0 \div 5$ VDC (1V = 1A).

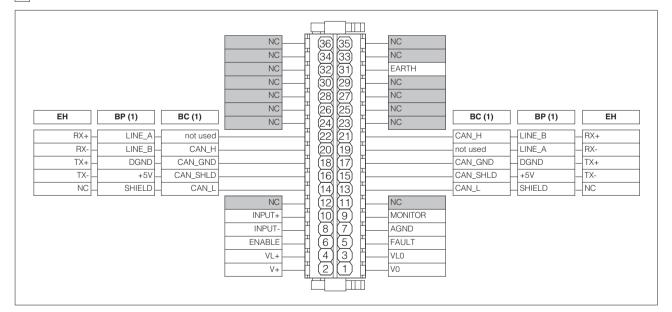
Output signal can be reconfigured via software, within a maximum range of ± 5 VDC.

16.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

16.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.



17 TERMINAL BOARD OVERVIEW

(1) For BC and BP executions the fieldbus connections have an internal pass-through connection

18 ELECTRONIC CONNECTIONS

18.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 Vbc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
Δ	6	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
	9	MONITOR	Monitor output signal: ±5 Vpc maximum range, referred to AGND Default is: ±5 Vpc	Output - analog signal Software selectable
	10	INPUT+	Reference input signal: ± 10 Vpc / ± 20 mA maximum range Defaults are: ± 10 Vpc for standard and 4 $\div 20$ mA for /I option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

18.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply		
	2	ID	Identification		
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -	(female)	
	5	D+	Data line +	(reinale)	

CABLE ENTRANCE

C2

PIN

13

15

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SIGNAL

CAN L

CAN_GND

not used

CAN_H

CAN_SHLD Shield

TECHNICAL SPECIFICATIONS

Bus line (low)

Bus line (high)

Signal zero data line

Pass-through connection (1)

18.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
(C1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) pin 19 and 22 can be fed with external +5V supply of CAN interface

18.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

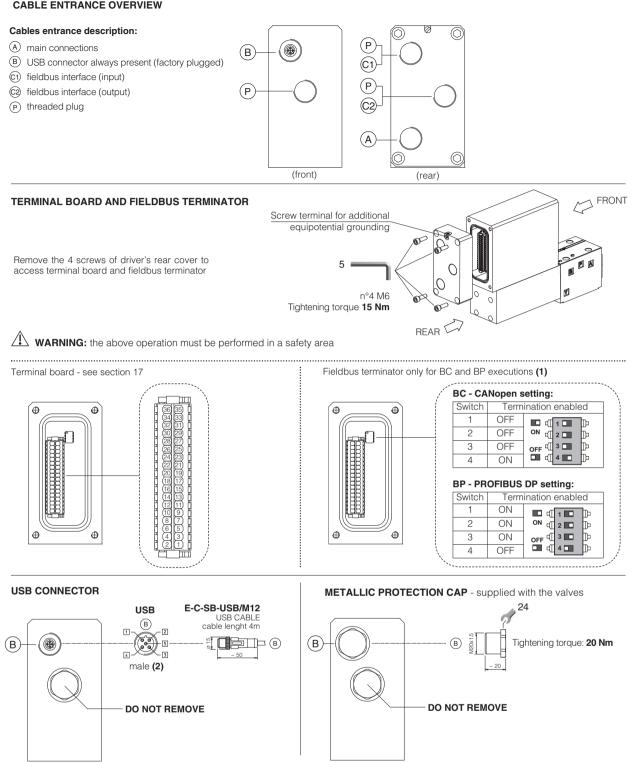
CABLE ENTRANCE PIN SIGNAL TECHNICAL SPECIFICATIONS 13 SHIELD +5V 15 Power supply C2 17 DGND Data line and termination signal zero 19 LINE_A Bus line (high) 21 LINE_B Bus line (low)

18.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver





(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

19.1 Cable glands and threaded plug - see tech table KX800

Communication		be ordere	ed separat	ely	Cable entrance	
interfaces	Cable	gland entrance		ed plug entrance	overview	Notes
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

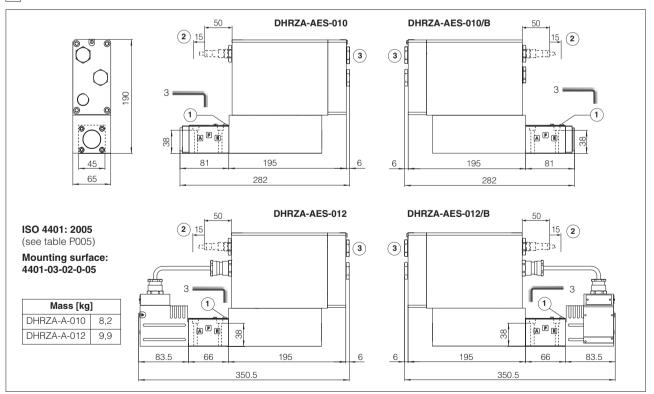
20 FASTENING BOLTS AND SEALS

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		Seals:
Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	0	4 OR 108; Diameter of ports P, A, B, T: \emptyset 7,5 mm (max) 1 OR 2025 Diameter of port Y: \emptyset = 3,2 mm (only for /Y option)

21 INSTALLATION DIMENSIONS FOR DHRZA [mm]



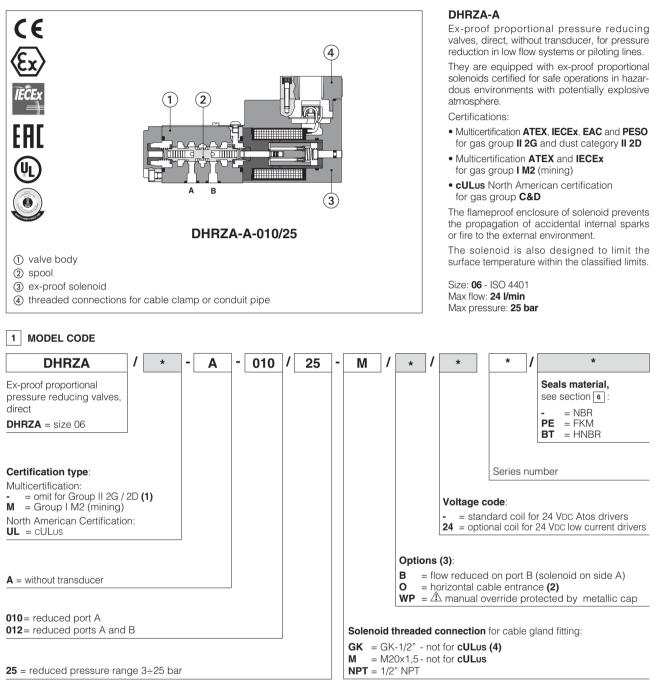
22 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments	GS510	Fieldbus
X020	Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO	KX800	Cable glands for ex-proof valves
FX900	Operating and manintenance informationfor ex-proof proportional valves	P005	Mounting surfaces for electrohydraulic valves
GS500	Programming tools		

atos

Ex-proof proportional reducing valves

direct, without transducer - ATEX, IECEx, EAC, PESO or cULus



(1) The valves with Multicertification for Group II are also certified for Indian market according to **PESO** (Petroleum and Explosives Safety Organization). The PESO certificate can be downloaded from

(2) Not for multicertification M group I (mining)

(3) Possible combined options: all combinations are available

2 ELECTRONIC DRIVERS

(4) Approved only for italian market

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-AS-* /A	E-BM-AES-* /A
Туре	digital	digital
Format	DIN-ra	il panel
Data sheet	G030	GS050

3 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	150 years, see technical table P007				
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200h				
Compliance	Explosion proof protection, see section 7 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

4 HYDRAULIC CHARACTERISTICS

Hydraulic symbols	T P		A T P B
DHRZA-	A-010/25*	DHRZA-A-010/25/B*	DHRZA-A-012/25*
Max regulated pressure (Q=1 l/min) [bar]		25	
Min. regulated pressure (Q=1 I/min) [bar]		3	
Max. pressure at port P [bar]		315	
Max. pressure at port T [bar]		210	
Max. flow [I/min]		24	
Response time 0-100% step signal [ms] (depending on installation)		≤ 45	
Hysteresis [% of the max pressure]		≤ 1,5	
Linearity [% of the max pressure]		≤3	
Repeatability [% of the max pressure]		≤2	

Above performance data refer to valves coupled with Atos electronic drivers, see section 2

5 ELECTRICAL CHARACTERISTICS

Max. power	35	35W			
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standar ISO 13732-1 and EN982 must be taken into account			
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved				
Duty factor	Continuous rating (ED=100%)	Continuous rating (ED=100%)			
Voltage code	standard	option /24			
Coil resistance R at 20°C	3,2 Ω	17,6 Ω			
Max. solenoid current	2,5 A	2,5 A 1,1 A			

6 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature		NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$			
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid normal operation contamination level longer life		ISO4406 class 18/16/13 NAS1638 class 7 s		see also filter section at KTF	
		ISO4406 class 16/14/11 NAS1	catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM HFDU, HFDR		ISO 12922	
Flame resistant with water (1)		NBR, HNBR	HFC	100 12922	

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

 ⁽¹⁾ Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

7 CERTIFICATION DATA

Valve type	DHRZA, DKZA		DHRZA /M , DKZA /M	DHRZA /UL , DKZA /UL	
Certifications	Multicertification Group II TEX IECEX EAC PESO		Multicertification Group I ATEX IECEx	North American cULus	
Solenoid certified code	OZ	A-A	OZAM-A	OZA	A/EC
Type examination certificate (1)	ATEX: CESI 02 ATEX 014 IECEx: IECEx CES 10.0010x EAC: TC RU C-IT. 08.B.01784 PESO: P338131		ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324 - E366100	
Method of protection	• ATEX, EAC Ex II 2G Ex d IIC T4/T3 Gb		ATEX Ex M2 Ex db Mb IECEx	UL 1203 Class I, Div.I, Groups C & D Class I, Zone I, Groups IIA & IIB	
			Ex db I Mb		
	• PESO Ex II 2G Ex d II	IC T4/T3 Gb			
Temperature class	T4	Т3	-	T4	Т3
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135 °C	≤ 200 °C
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C
Applicable standards	EN 60079-1 IEC 60079-1		IEC 60079-0 IEC 60079-1 IEC 60079-31	UL 1203 and UL429, CSA 22.2 n°30-1986 CSA 22.2 n°139-13	
Cable entrance: threaded connection vertical (standard) or horizontal (option /O)	M = M		GK-1/2" 20x1,5 : 1/2" NPT	1/2"	NPT

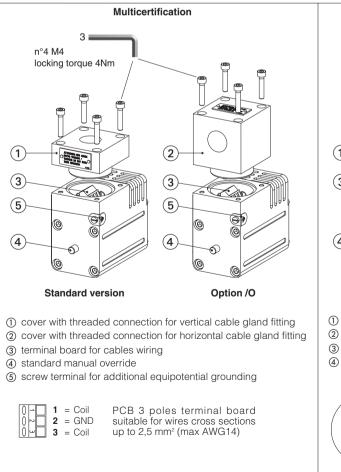
(1) The type examinator certificates can be downloaded from

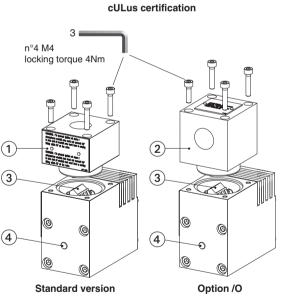
(2) The solenoids Group II and cULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

🕂 WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

8 EX PROOF SOLENOIDS WIRING





① cover with threaded connection for vertical cable gland fitting

- (2) cover with threaded connection for horizontal cable gland fitting
- terminal board for cables wiring
- (4) standard manual override

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Pay attention to respect the polarity 1 = Coil + PCB 3 poles terminal board sugge 2 = GND sted cable section up to 1,5 mm² 3 = Coil - (max AWG16), see section 9 note 1

alternative GND screw terminal connected to solenoid housing

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper Conductors
- Bronze braided armor

· Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C)

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

9.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Multicertification

Max ambient temperature [°C]	Temperature class		Max surface temperature [°C]		Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	135 °C	90 °C	90 °C
45 °C	-	T4	-	135 °C	-	95 °C
55 °C	-	T3	-	200 °C	-	110 °C
00 °C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	T3	N.A.	200 °C	N.A.	120 °C

cULus certification

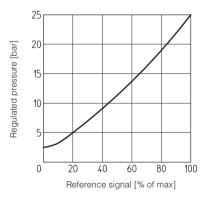
Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature
55 °C	Τ4	135 °C	100 °C
70 °C	Т3	200 °C	100 °C

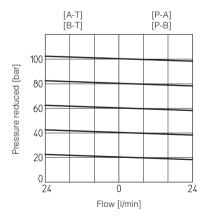
10 CABLE GLANDS - only Multicertification

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

11 DIAGRAMS based on mineral oil ISO VG 46 at 50°C

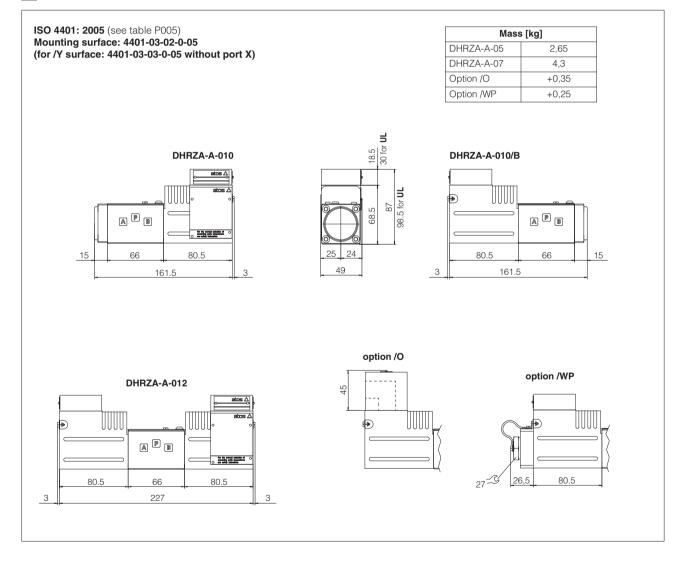




12 FASTENING BOLTS AND SEALS

	DHZA	DKZA
Ø	Fastening bolts:	Fastening bolts:
H H	4 socket head screws M5x50 class 12.9	4 socket head screws M6x40 class 12.9
	Tightening torque = 8 Nm	Tightening torque = 15 Nm
	Seals:	Seals:
\cap	4 OR 108;	5 OR 2050;
	Diameter of ports P, A, B, T: Ø 7,5 mm (max)	Diameter of ports P, A, B, T: Ø 11,5 mm (max)
	1 OR 2025 Diameter of port Y: $\emptyset = 3,2$ mm (only for /Y option)	1 OR 108 Diameter of port Y: $\emptyset = 5$ mm (only for /Y option)

13 INSTALLATION DIMENSIONS FOR DHRZO [mm]



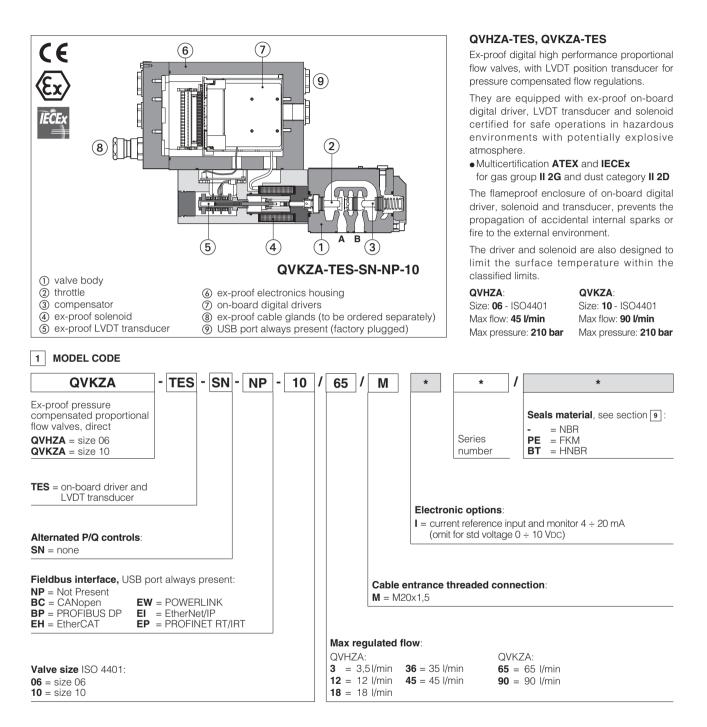
14 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments
X020	Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO
X030	Summary of Atos ex-proof components certified to cULus
FX900	Operating and manintenance information for ex-proof proportional valves
KX800	Cable glands for ex-proof valves
P005	Mounting surfaces for electrohydraulic valves

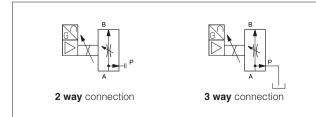
atos

Ex-proof digital proportional flow valves high performance

pressure compensated, with on-board driver and LVDT transducer - ATEX and IECEx



2 HYDRAULIC SYMBOLS



The valves can be used in 2 or 3 way connection, depending to the application requirements.

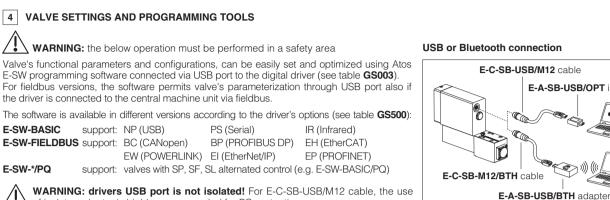
In 2 way the P port must not be connected (blocked)

In **3 way** the P port has to be connected to tank or to other user lines The port T must be always not connected (blocked)

3 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table FX900 and in the user manuals included in the E-SW-* programming software.

E-A-SB-USB/OPT isolator



of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

5 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

6 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	150 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +60^{\circ}C$ /PE option = $-20^{\circ}C \div +60^{\circ}C$ /BT option = $-40^{\circ}C \div +60^{\circ}C$					
Storage temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model	QVHZA				QVKZA			
Max regulated flow	[l/min]	3,5	12	18	35	45	65	90
Min regulated flow	[cm³/min]	15	20	30	50	60	85	100
Regulating ∆p	[bar]	4 -	- 6	10	- 12	15	6 - 8	10 - 12
Max flow on port A (1)	[l/min]		4	0	50	55	70	100
Max pressure	[bar]				210			
Response time 0÷100% step	o signal [ms]	≤ 30 ≤ 45					45	
Hysteresis		≤ 0,5 [% of the regulated max flow]						
Linearity		\leq 0,5 [% of the regulated max flow]						
Repeatability				≤ 0,1 [% o	f the regulated	max flow]		

(1) for different Δp , the max flow is in accordance to diagrams in section 14.3

8 ELECTRICAL CHARACTERISTICS

Power supplies		: +24 VDC : VRMS = 20 ÷ 32 VMA>	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)					
Max power consumption	35 W							
Analog input signals								
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards				
Monitor outputs		Dutput range: voltage ±10 VDC @ max 5 mA current ±20 mA @ max 500 Ω load resistance						
Enable input	Range: 0 ÷ 5 VDC (OFF	Range: $0 \div 5$ VDc (OFF state), $9 \div 24$ VDc (ON state), $5 \div 9$ VDc (not accepted); Input impedance: Ri > 10 k Ω						
Fault output		VDC (ON state > [pow age not allowed (e.g. du		ate < 1 V) @ max 50 mA;				
Alarms	Solenoid not connecte valve spool transduce		preak with current refere	nce signal, over/under temperature,				
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland						
Duty factor	Continuous rating (ED	=100%)						
Tropicalization	Tropical coating on el							
Additional characteristics		n of solenoid current su nst reverse polarity of p		rol by P.I.D. with rapid solenoid swit-				
Electromagnetic compatibility (EMC)	According to Directive	e 2014/30/UE (Immunity	: EN 61000-6-2; Emissio	n: EN 61000-6-3)				
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158				
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX				

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = -20° C ÷ $+60^{\circ}$ C, with HFC hydraulic fluids = -20° C ÷ $+50^{\circ}$ C FKM seals (/PE option) = -20° C ÷ $+80^{\circ}$ C HNBR seals (/BT option) = -40° C ÷ $+60^{\circ}$ C, with HFC hydraulic fluids = -40° C ÷ $+50^{\circ}$ C			
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	ISO4406 class 18/16/13 NAS1638 class 7		
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog		
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM HFDU, HFDR		ISO 12922	
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922	

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type	QVHZA, QVKZA					
Certifications		Multicertification Group II				
	ATEX IECEx					
Solenoid certified code		OZA	-TES			
Type examination certificate (1)	• ATEX: TUV IT 18 ATEX 068 X • IECEx: IECEx TPS 19.0004X					
Method of protection		ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db				
Temperature class	Т6	T5	;	T4		
Surface temperature	≤ 85 °C	≤ 100	°C	≤ 135 °C		
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +40 °C -40 ÷ +55 °C -4				
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 IE EN 60079-1 IEC 60079-1		IEC 60079-31			
Cable entrance: threaded connection	M = M20x1,5					

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C.

In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code. WARNING:

A service work performed on the valve by the end users or not qualified personnel invalidates the certification

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	x ambient temperature [°C] Temperature class		Min. cable temperature [°C]	
40 °C	T6	85 °C	80 °C	
55 °C	T5	100 °C	90 °C	
70 °C	Τ4	135 °C	110 °C	

12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table KX800 Note: a Loctite sealant type 545, should be used on the cable gland entry threads

13 **ELECTRONIC OPTIONS**

= It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 Vpc. Input signal can be reconfigured via software selecting I between voltage and current, within a maximum range of ±10 VDc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

14 DIAGRAMS - based on mineral oil ISO VG 46 at 50 °C

14.1 Regulation diagrams

90 35 Regulated flow [I/min] (reg Δp) Regulated flow [I/min] (reg Δp) 1 = QVHZA-*-06/3 28 77 2 = QVHZA-*-06/12 4 3 = QVHZA-*-06/18 2′ 4 = QVHZA-*-06/36 54 5 = QVHZA-*-06/45 6 6 = QVKZA-*-10/65 14 36 3 7 = QVKZA-*-10/90 5 2 7 18 0 + 0+0 20 20 100 40 60 80 100 40 60 80 Reference signal [% of max.] Reference signal [% of max.] 14.2 Regulated flow/outlet pressure diagrams 100r 100 2 1 with inlet pressure = 210 bar Regulated flow [%of the max] Regulated flow [%of the max] 80 8ſ 1 = OVH7A2 = QVKZA 60 60 Dotted line for 3-way versions 40 40 20 0+0 0 + 50 100 150 200 250 100 150 250 50 200 Pressure at port B [bar] Pressure at port B [bar] 14.3 Flow $A \rightarrow P/\Delta p$ diagrams 20 25 3-way configuration Differential pressure A →P [bar] Differential pressure A →P [bar 1 = QVHZA-*-06/3 20 16 3 QVHZA-*-06/12 2 = QVHZA-*-06/18 15 QVHZA-*-06/36 2 12 5 3 = QVHZA-*-06**/45** 4 = QVKZA-*-10/65 10 8 5 = QVKZA-*-10/90 4 5 L 0 1 0 +

20

Flow $A \rightarrow P$ [I/min]

30

40

50

10

20

40

60

Flow $A \rightarrow P$ [l/min]

80

100

15 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

15.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

15.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

15.3 Flow reference input signal (Q_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDC for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDC.

15.4 Flow monitor output signal (Q_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDC for standard and $4 \div 20$ mA for /l option.

Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDc or ± 20 mA.

15.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 5: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

15.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

EH, EW, EI, EP BP (1) RX- LINE_A RX- LINE_B TX+ DGND TX- +5V NC SHIELD	IN	NC 4 33 NC 4 3	NC EARTH EARTH NC ACD AGND FAULT VL0 V0	BC (1) CAN_H not used CAN_GND CAN_SHLD CAN_L	BP (1) LINE_B LINE_A DGND +5V SHIELD	EH, EW, EI, EP
--	----	---	--	---	---	----------------

16 TERMINAL BOARD OVERVIEW

(1) For BC and BP executions the fieldbus connections have an internal pass-through connection

17 ELECTRONIC CONNECTIONS

17.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 Vbc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
Λ	6	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
	9	Q_MONITOR	Flow monitor output signal: ±10 Vpc / ±20 mA maximum range, referred to AGND Defaults are: 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Output - analog signal Software selectable
	10	Q_INPUT+	Flow reference input signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND Defaults are: $0 \div 10$ Vpc for standard and $4 \div 20$ mA for /I option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

17.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply	1-2	
	2	ID	Identification	5	
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -	4 - <u>3</u>	
	5	D+	Data line +	(female)	

17.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
()1	18	CAN_GND	Signal zero data line
	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

17.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

17.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
(2)	17	DGND	Data line and termination signal zero
	19	LINE A	Bus line (high)

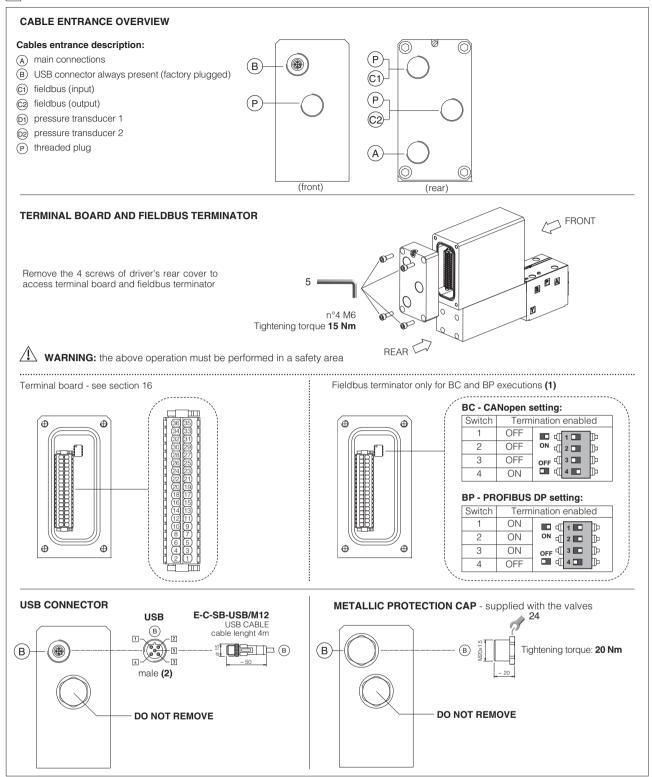
Bus line (low)

21

LINE_B

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	CAN_L	Bus line (low)
	15	CAN_SHLD	Shield
C2	17	CAN_GND	Signal zero data line
	19	not used	Pass-through connection (1)
	21	CAN_H	Bus line (high)



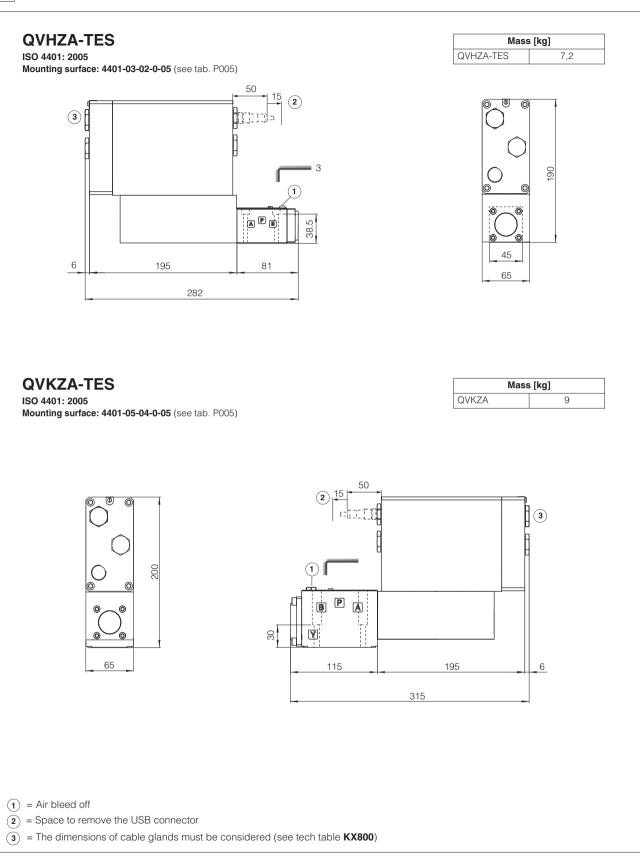
(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

18.1 Cable glands and threaded plug - see tech table KX800

Communication		be ordere		,	Cable entrance	Notes
interfaces		gland entrance		ed plug entrance	overview	INDLES
NP	1	A	none	none		Cable entrance A is open for costumers Cable entrance P are factory plugged
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

19 FASTENING BOLTS AND SEALS

	QVHZA	QVKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø7,5 mm (max)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max)



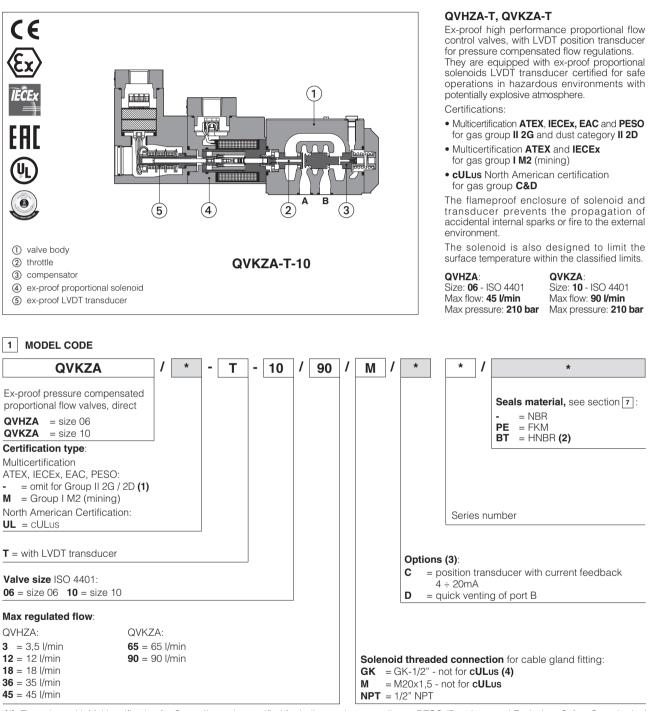
21 RELATED DOCUMENTATION

X010 X020 FX900 GS500 GS510	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO Operating and manintenance information for ex-proof proportional valves Programming tools Fieldbus	GX800 KX800 P005	Ex-proof pressure transducer type E-ATRA-7 Cable glands for ex-proof valves Mounting surfaces for electrohydraulic valves
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atos®

Ex-proof proportional flow valves high performance

pressure compensated, with LVDT transducer - ATEX, IECEx, EAC, PESO or cULus



(1) The valves with Multicertification for Group II are also certified for Indian market according to PESO (Petroleum and Explosives Safety Organization). The PESO certificate can be downloaded from

(2) Not for multicertification M group I (mining) (3) Possible combined options: /CD (4) Approved only for the Italian market

1 HYDRAULIC SYMBOLS The values can be used in 2 or 3 way connection, depending to the application requirements. 1 way connection 2 way connection 3 way connection

3 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-AS-* /A	E-BM-AES-* /A
Туре	digital	digital
Format	DIN-rai	il panel
Data sheet	G030	GS050

4 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	150 years, see technical table P007					
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$					
Storage temperature range	Standard = -20° C \div $+80^{\circ}$ C /PE option = -20° C \div $+80^{\circ}$ C /BT option = -40° C \div $+70^{\circ}$ C					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200h					
Compliance	Explosion proof protection, see section -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t" RoHs Directive 2011/65/EU as last update by 2015/65/EU					
	REACH Regulation (EC) n°1907/2006					

5 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		QVHZA					QVKZA	
Max regulated flow	[l/min]	3,5	12	18	35	45	65	90
Min regulated flow	[cm³/min]	15	20	30	50	60	85	100
Regulating ∆p	[bar]	4 - 6 10 - 12			- 12	15	6 - 8	10 - 12
Max flow on port A	[l/min]	40			50	55	70	100
Max pressure	[bar]				210			
Response time (1)	[ms]	≤ 30 ≤ 40					40	
Hysteresis		≤ 0,5 [% of the regulated max flow]						
Linearity		≤ 0,5 [% of the regulated max flow]						
Repeatability				≤ 0,1 [% o	f the regulated	max flow]		

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 3

(1) 0 ÷100 % step signal

6 ELECTRICAL CHARACTERISTICS

Max. power	35W
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved
Duty factor	Continuous rating (ED=100%)
Voltage code	standard
Coil resistance R at 20°C	3,2 Ω
Max. solenoid current	2,5 A

7 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature		NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM	HFDU, HFDR	100 10000		
Flame resistant with water	(1)	NBR, HNBR	NBR, HNBR HFC ISO 12922			

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

 ⁽¹⁾ Performance limitations in case of flame resistant fluids with water: -max operating pressure = 180 bar -max fluid temperature = 50°C

8 CERTIFICATION DATA

Valve type	QVHZA, QVKZA		QVHZA /M , QVHZA /M	QVHZA /UL	, qvhza /ul	
Certifications	Multicertification Group II ATEX IECEX EAC PESO		Multicertification Group I ATEX IECEx	North American cULus		
Solenoid cerified code	OZ	A-T	OZAM-T	OZA-T/EC		
Type examination certificate (1)	ATEX: CESI 02 ATEX 014 IECEx: IECEx CES 10.0010x EAC: TC RU C-IT. 08.B.01784 PESO: P338131		ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324 - E366100		
Method of protection	ATEX, EAC Ex II 2G Ex d IIC T6/T4/T3 Gb Ex II 2D Ex tb IIIC T85°C/T200°C Db IECEx Ex d IIC T6/T4/T3 Gb Ex tb IIIC T85°C/T200°C Db PESO Ex II 2G Ex d IIC T6/T4 Gb		ATEX Ex I M2 Ex db I Mb IECEx Ex db I Mb	UL 1203 Class I, Div.I, Groups C & D Class I, Zone I, Groups IIA & IIB		
Temperature class	T4	Т3	-	T4	Т3	
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135°C	≤ 200 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C	
Applicable standards	EN 60079-0 EN 60079-1 EN 60079-31		IEC 60079-0 IEC 60079-1 IEC 60079-31	CSA 22.2	and UL429, n°30-1986 n°139-13	
Cable entrance: threaded connection	GK = Gł M = M20 NPT = 1		Dx1,5	1/2" NPT		

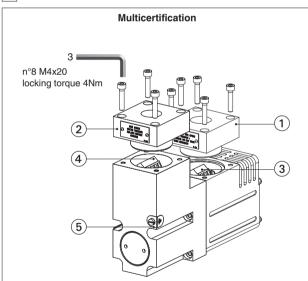
(1) The type examinator certificates can be downloaded from

(2) The solenoids Group II and cULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

/ WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

9 EX PROOF SOLENOIDS AND LVDT TRANSDUCER WIRING



- ① solenoid cover with threaded connection for cable gland fitting
- (2) transducer cover with threaded connection for cable gland fitting

PCB 3 poles terminal board

- (3) solenoid terminal board for cables wiring
- (4) transducer terminal board for cables wiring
- (5) screw terminal for additional equipotential grounding

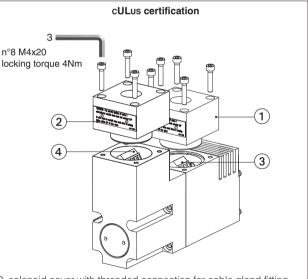
Solenoid wiring

- $\begin{array}{c|c} 0 \rightarrow & \mathbf{1} & = \text{Coil} \\ 0 \sim & \mathbf{2} & = \text{GND} \end{array}$
 - 2 = GND 3 = Coil suitable for wires cross sections up to 2,5 mm² (max AWG14)

Position transducer wiring

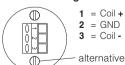
0-0	1 = Output signal
0~0	2 = Supply -15 V
0 -	3 = Supply +15 V
-10	4 = GND

PCB 4 poles terminal board suitable for wires cross sections up to 2,5 mm² (max AWG14)



- ① solenoid cover with threaded connection for cable gland fitting
- (2) transducer cover with threaded connection for cable gland fitting(3) solenoid terminal board for cables wiring
- (4) transducer terminal board for cables wiring

Solenoid wiring

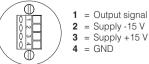


$\angle \mathbf{I}$ Pay attention to respect the polarity

PCB 3 poles terminal board suggested cable section up to 1,5 mm²
 (max AWG16), see section 10 note 1

alternative GND screw terminal connected to solenoid housing

Position transducer wiring



PCB 4 poles terminal board suggested cable section up to 1,5 mm² (max AWG16), see section 10 note 1

FX420

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper Conductors
- Bronze braided armor

Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C)

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

10.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products. **Multicertification**

Max ambient temperature [°C]	Tempera	ture class	Max surface temperature [°C] Min. cable temperative			nperature [°C]
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	135 °C	-	90 °C
60 °C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	Т3	N.A.	200 °C	N.A.	120 °C

cULus certification

Max ambient temperature [°C]	nbient temperature [°C] Temperature class Max surface temperature [°C]		Min. cable temperature
55 °C	T4	135 °C	100 °C
70 °C	Т3	200 °C	100 °C

11 CABLE GLANDS - only Multicertification

Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

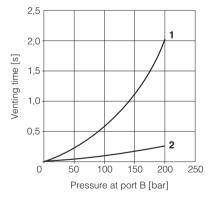
12 OPTIONS

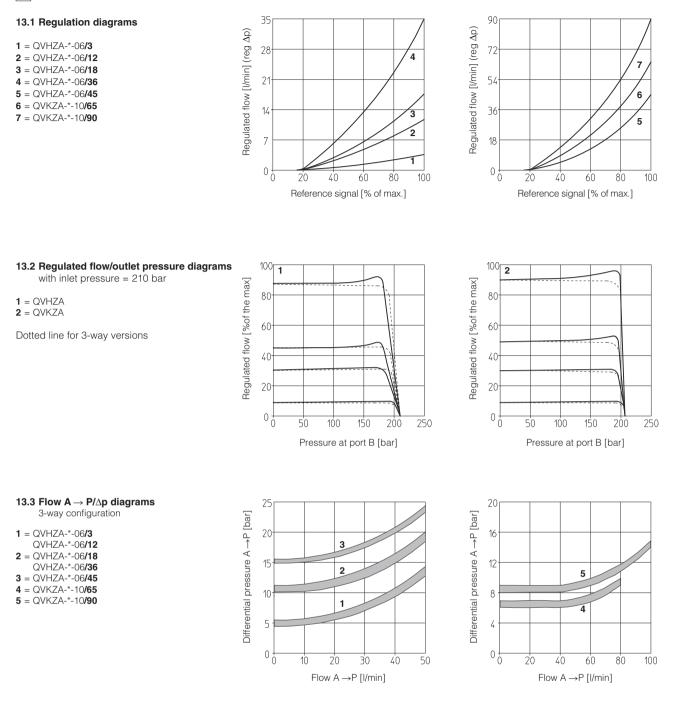
- **C** = Position transducer with current feedback 4÷20 mA, suggested in case of long distance between the electronic driver and the proportional valve
- D = This option provides a quick venting of the use port B when the valve is closed or de-energized. The valve must be connected in 3 way, with P port connected to tank. When the proportional throttle is fully closed, the valve's port B is internally connected to port P (tank), permitting a quickly decompression of the pressure in the use line. In the diagram aside are represented the venting times of QVHZA and QVKZA option /D

respect to standard versions:

1 = standard versions

2 = option /D

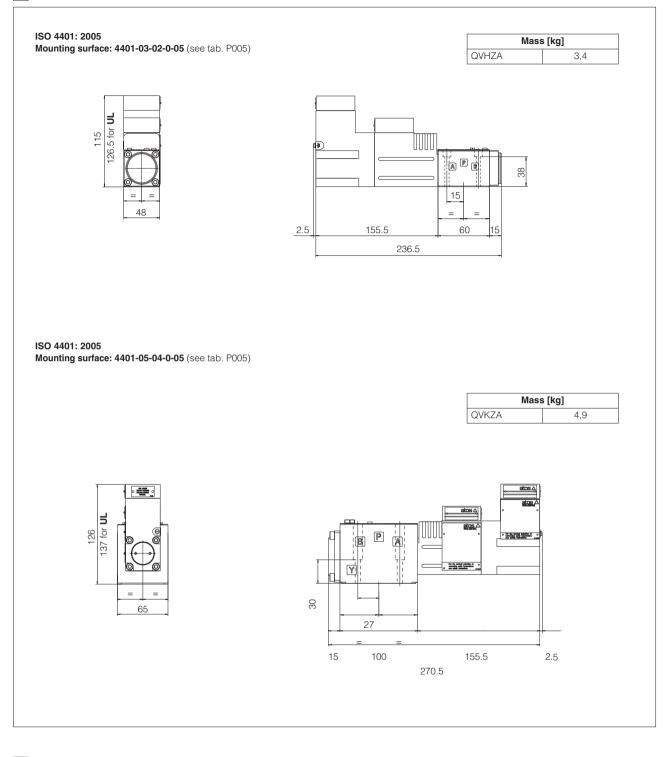




14 FASTENING BOLTS AND SEALS

	QVHZA	QVKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø7,5 mm (max)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max)

15 INSTALLATION DIMENSIONS FOR QVHZA [mm]



16 RELATED DOCUMENTATION

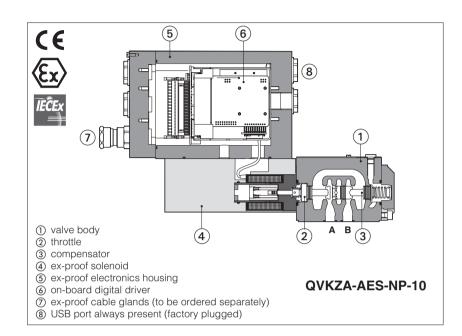
X010 Basics for electrohydraulics in hazardous environments
X020 Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESO
X030 Summary of Atos ex-proof components certified to cULus
FX900 Operating and manintenance information for ex-proof proportional valves
KX800 Cable glands for ex-proof valves
P005 Mounting surfaces for electrohydraulic valves

09/19

atos

Ex-proof digital proportional flow valves

pressure compensated with on-board driver and without transducer - ATEX and IECEx



QVHZA-AES, QVKZA-AES

Ex-proof digital proportional flow valves, without position transducer for pressure compensated flow regulations.

They are equipped with ex-proof on-board digital driver and solenoid certified for safe operations in hazardous environments with potentially explosive atmosphere.

Multicertification ATEX and IECEx

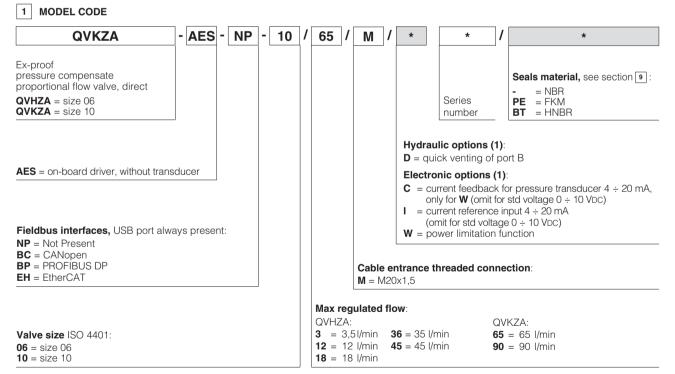
for gas group II 2G and dust category II 2D

The flameproof enclosure of on-board digital driver and solenoid prevents the propagation of accidental internal sparks or fire to the external environment.

The driver and solenoid are also designed to limit the surface temperature within the classified limits.

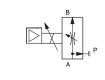
QVHZA:	(
Size: 06 - ISO4401	S
Max flow: 45 l/min	ſ
Max pressure: 210 bar	ſ

QVKZA: Size: 10 - ISO4401 Max flow: 90 l/min Max pressure: 210 bar



(1) For possible combined options, see section 15

2 HYDRAULIC SYMBOLS





The valves can be used in 2 or 3 way connection, depending to the application requirements.

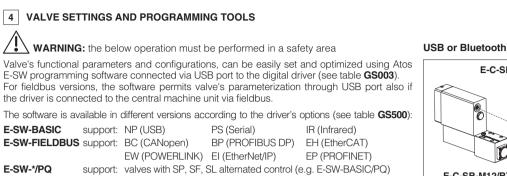
In **2 way** the P port must not be connected (blocked) In **3 way** the P port has to be connected to tank or to other user lines The port T must be always not connected (blocked)

2 way connection

3 way connection

3 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table FX900 and in the user manuals included in the E-SW-* programming software.



WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

5 FIELDBUS - see tech. table **GS510**

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

6 GENERAL CHARACTERISTICS

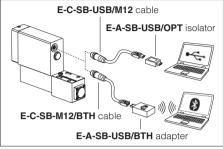
Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	150 years, see technical table P007				
Ambient temperature range	Standard = -20° C \div $+60^{\circ}$ C /PE option = -20° C \div $+60^{\circ}$ C /BT option = -40° C \div $+60^{\circ}$ C				
Storage temperature range	Standard = -20° C ÷ $+70^{\circ}$ C /PE option = -20° C ÷ $+70^{\circ}$ C /BT option = -40° C ÷ $+70^{\circ}$ C				
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h				
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006				

7	HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C
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Valve model				QVHZA			QV	KZA
Max regulated flow	[l/min]	3,5	12	18	35	45	65	90
Min regulated flow	[cm³/min]	15	20	30	50	60	85	100
Regulating ∆p	[bar]	4 - 6 10 - 12		- 12	15	6 - 8	10 - 12	
Max flow on port A (1)	[l/min]	40 50		50	55	70	100	
Max pressure	[bar]	210						
Response time 0÷100% step	o signal [ms]	≤ 35			≤	50		
Hysteresis		≤ 5 [% of the regulated max flow]						
Linearity		\leq 3 [% of the regulated max flow]						
Repeatability		≤ 1 [% of the regulated max flow]						

(1) for different Δp , the max flow is in accordance to diagrams in section 16.3

USB or Bluetooth connection



8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)						
Max power consumption	35 W						
Analog input signals	Voltage: range ±10 V Current: range ±20 n	/DC (24 VMAX tollerant)	Input impedance Input impedance				
Insulation class		curing surface tempera 82 must be taken into a		ils, the European standards			
Monitor outputs	Voltage: maximum rai	nge ± 5 Voc @ max	5 mA				
Enable input	Range: 0 ÷ 9 VDC (OFF	state), 15 ÷ 24 VDC (ON	state), 9 ÷ 15 VDC (not ac	cepted); Input impedance: $Ri > 87k\Omega$			
Fault output		VDC (ON state ≅ VL+ age not allowed (e.g. du		DFF state \cong 0 V) @ max 50 mA;			
Pressure transducer power supply (only /W option)	+24VDC @ max 100 r	nA (E-ATRA-7 see tech	table GX800)				
Alarms			reak with current referend el, pressure transducer	ce signal, over/under temperature, failure (/W option)			
Protection degree to DIN EN60529	IP66/67 with relevant	IP66/67 with relevant cable gland					
Duty factor	Continuous rating (ED	Continuous rating (ED=100%)					
Tropicalization	Tropical coating on ele	ectronics PCB					
Additional characteristics	Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply						
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)						
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT EC 61158			
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX			

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20÷100 mm²/s - max allowed ra	inge 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	ISO4406 class 16/14/11 NAS1638 class 5			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without wa	iter	FKM HFDU, HFDR		ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	1 130 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

Performance limitations in case of flame resistant fluids with water: -max operating pressure = 210 bar -max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type	QVHZA, QVKZA						
Certifications	Multicertification Group II						
		ATEX	IECEx				
Solenoid certified code		OZA	-AES				
Type examination certificate (1)	• ATEX: TUV IT 18 ATEX 06	ATEX: TUV IT 18 ATEX 068 X IECEx: IECEx TPS 19.0004X					
Method of protection	ATEX 2014/34/EU Ex II 2G Ex db IIC T6/T5/T4 Gb Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db Ex tb IIIC T85°C/T100°C/T135°C Db						
Temperature class	Т6	1	Г5	T4			
Surface temperature	≤ 85 °C	≤ 10	0° 00	≤ 135 °C			
Ambient temperature (2)	-40 ÷ +40 °C -40 ÷ +55 °C -40 ÷ +70						
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 IEC 60079 EN 60079-1 IEC 60079-1						
Cable entrance: threaded connection	M = M20x1,5						

(1) The type examinator certificates can be downloaded from

(2) The driver and solenoids are certified for minimum ambient temperature -40°C. In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

MARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	Τ4	135 °C	110 °C

12 CABLE GLANDS

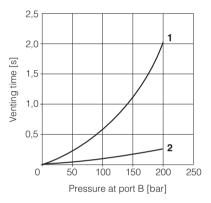
Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table KX600

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

13 HYDRAULIC OPTIONS

This option provides a quick venting of the use port B when the valve is closed or de-energized. The valve must be connected in 3 way, with P port connected to tank. When the proportional throttle is fully closed, the valve's port B is internally connected to port P (tank), permitting a quickly decompression of the pressure in the use line. In the diagram aside are represented the venting times of QVHZA and QVKZA option /D respect to standard versions:

- 1 = standard versions
- **2** = option /D



14 ELECTRONIC OPTIONS

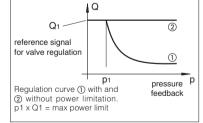
I = It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

C = Only in combination with option **/W**

- It is available to connect pressure transducer with 4 ÷ 20 mA current output signal, instead of the standard 0 ÷ 10Vbc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vbc or ±20 mA.
- W = Only for valves coupled with pressure compensator type HC-011 or KC-011 (see tech table D150). It provides the hydraulic power limitation function. The driver receives the flow reference signal by the analog input INPUT+ and a pressure transducer, installed in the hydraulic system, has to be connected to the driver's analog input TR. When the actual requested hydraulic power **pxQ** (TR x INPUT+) reaches the max power limit (p1xQ1), internally set by software, the driver automatically reduces the flow regulation of the valve. The higher is the pressure feedback the lower is the valve's regulated flow:

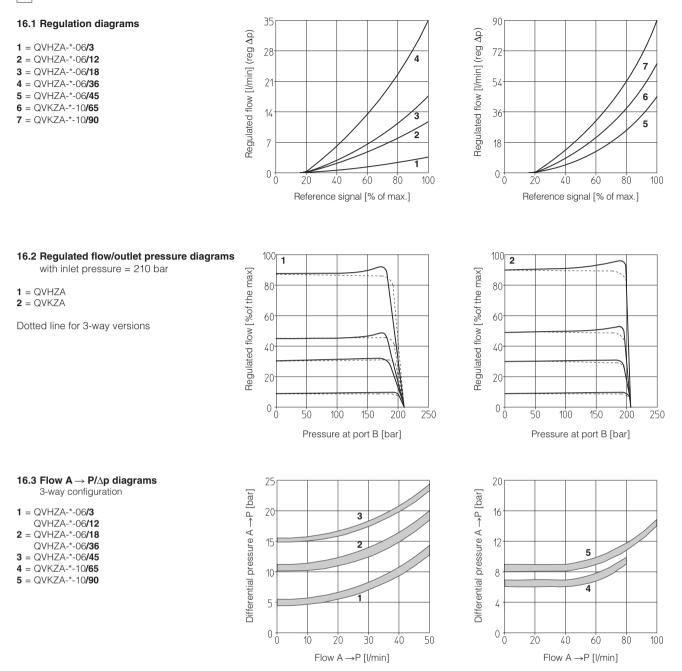
Flow regulation = Min (PowerLimit [sw setting] Transducer Pressure [TR] ; Flow Reference [INPUT+])





15 POSSIBLE COMBINED OPTIONS

/DI, /DW, /IW, /ICW, /ICWD



17 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

17.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

17.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics. USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

17.3 Flow reference input signal (INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDC for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDC.

17.4 Monitor output signals (MONITOR and MONITOR2)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, default settings is ±5 VDC (1V = 1A).

Output signal can be reconfigured via software, within a maximum range of ±5 VDC.

Option /W

The driver generates a second analog output signal (MONITOR2) proportional to the actual system pressure.

The output maximum range is ±5 VDC; default setting is 0 ÷ 5 VDC

17.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

17.6 Fault output signal (FAULT)

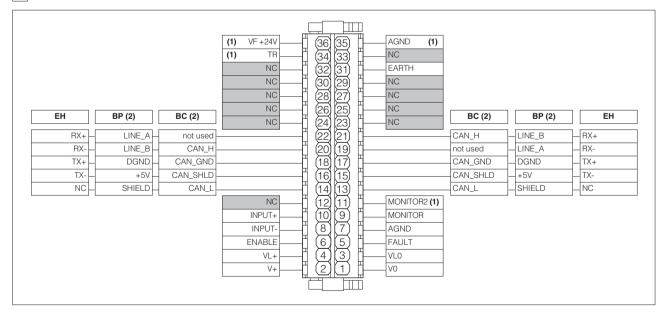
Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

17.7 Remote Pressure Transducer Input signal (TR) - only for /W option

Analog pressure transducers can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDc for standard and $4 \div 20$ mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ±20 mA. Note: transducer feedback can be read as a digital information through fieldbus communication - software selectable.

18 TERMINAL BOARD OVERVIEW



(1) Connections available only for /W option

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

19 ELECTRONIC CONNECTIONS

19.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vbc	Gnd - power supply
	2	V+	Power supply 24 Vbc	Input - power supply
	3	VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 VDc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
•	6	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
7 x	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
	9	MONITOR	Monitor output signal: ±5 Vpc maximum range, referred to AGND Default is: ±5 Vpc	Output - analog signal Software selectable
	10	INPUT+	Reference input signal: $\pm 10 \text{ Vpc} / \pm 20 \text{ mA}$ maximum range Defaults are: $0 \div 10 \text{ Vpc}$ for standard and $4 \div 20 \text{ mA}$ for /l option	Input - analog signal Software selectable
	11	MONITOR2	2nd monitor output signal: ±5 Vpc maximum range, referred to AGND (1) Default is: 0 ÷ 5 Vpc	Output - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

(1) 2nd monitor output signal is available only for /W option

19.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply		
	2	ID	Identification	(S S	
$ \mathbf{B} $	3	GND_USB	Signal zero data line		
	4	D-	Data line -		
	5	D+	Data line +	(female)	

CABLE ENTRANCE

C2

PIN

13

15

17

19

21

SIGNAL

CAN_L CAN_SHLD

CAN_GND

not used

CAN_H

TECHNICAL SPECIFICATIONS

Bus line (low)

Bus line (high)

Bus line (low)

Signal zero data line

Pass-through connection (1)

Shield

19.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
	16	CAN_SHLD	Shield
C1	18	CAN_GND	Signal zero data line
···	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

(1) pin 19 and 22 can be fed with external +5V supply of CAN interface

19.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

19.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	тх-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

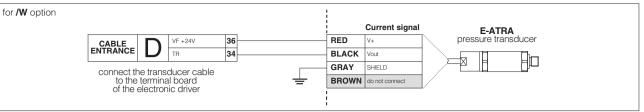
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

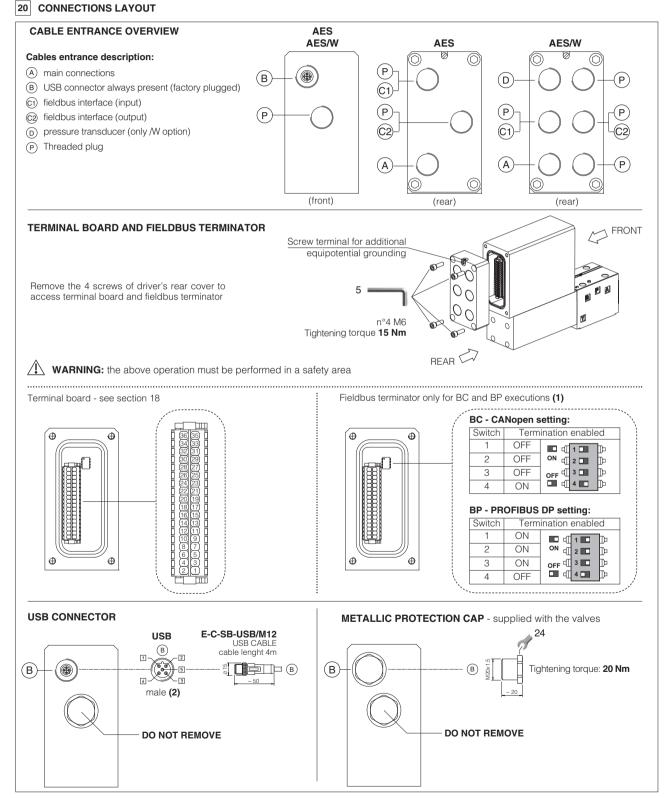
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	тх-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

19.6 Remote pressure transducer connector - only for /W option

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	Voltage	Current
	34	TR	Signal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect
	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/
	36	VF +24V	Power supply +24Vbc	Output - power supply	Connect	Connect

E-ATRA remote pressure transducer connection - see tech table GX800





(1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF (2) Pin layout always referred to driver's view

20.1 Cable glands and threaded plug for AES - see tech table KX800

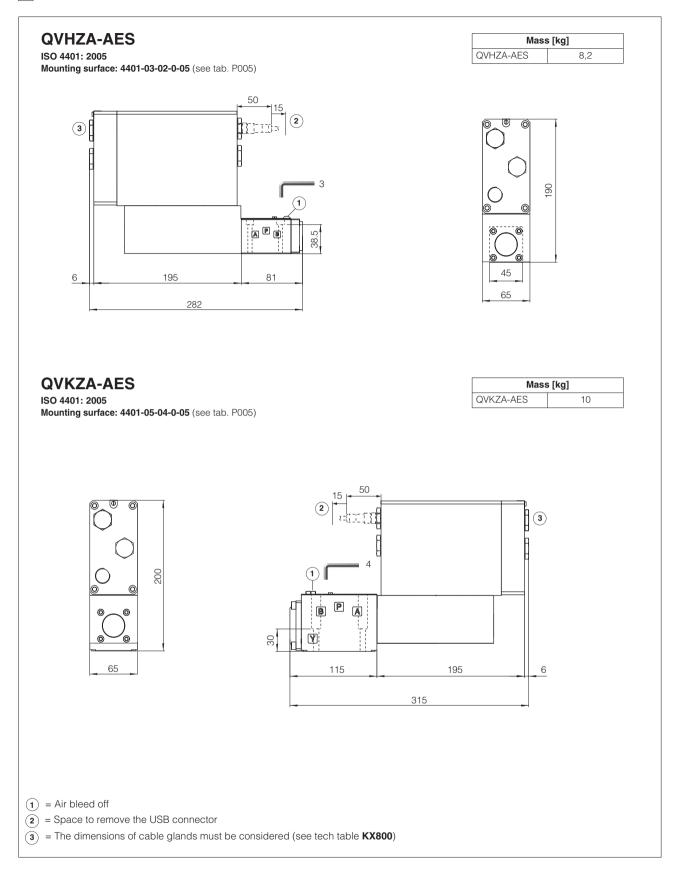
Communication interfaces		be ordere gland	ed separat Threade	-	Cable entrance overview	Notes
	quantity	entrance	quantity	entrance		
NP	1	A	none	none		Cable entrance P are factory plugged Cable entrance A is open for costumers
BC, BP, EH "via stub" connection	2	C1 A	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

20.2 Cable glands and threaded plug for AES with /W option - see tech table KX800

	То	be ordere	ed separat	ely	Cable entrance	
Communication interfaces		gland entrance		ed plug entrance	overview	Notes
NP	2	D	none	none		Cable entrance P are factory plugged Cable entrance A, D are open for costumers
BC, BP, EH "via stub" connection	3	D C1 A	1	C2		Cable entrance P are factory plugged Cable entrance A, C1, C2, D are open for costumers
BC, BP, EH "daisy chain" connection	4	D C1 - C2 A	none	none		Cable entrance P are factory plugged Cable entrance A, C1, C2, D are open for costumers

21 FASTENING BOLTS AND SEALS

	QVHZA	QVKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø 7,5 mm (max)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max)



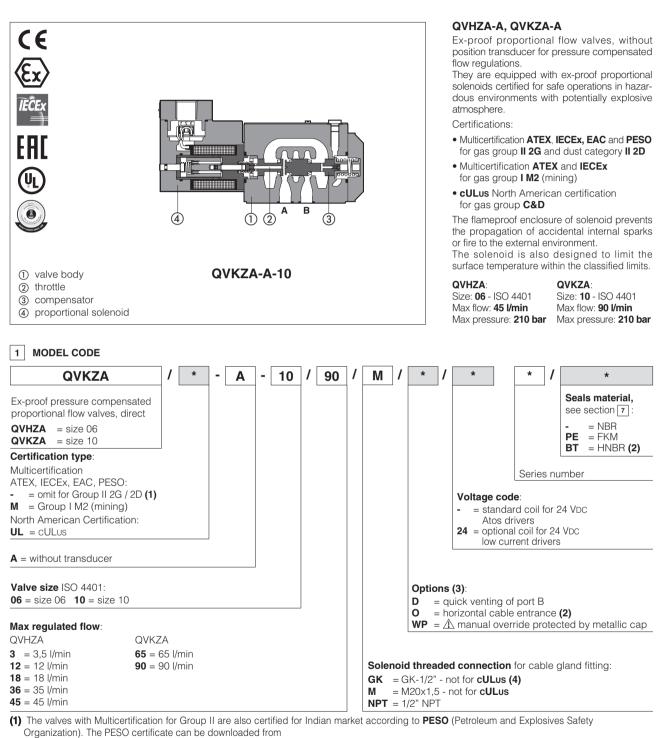
23 RELATED DOCUMENTATION

X010 X020 FX900 GS500	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO Operating and manintenance informationfor ex-proof proportional valves Programming tools	GS510 KX800 P005	Fieldbus Cable glands for ex-proof valves Mounting surfaces for electrohydraulic va
	Operating and manintenance informationfor ex-proof proportional valves Programming tools	P005	Mounting surfaces for electrohydraulic

atos

Ex-proof proportional flow valves

pressure compensated, without transducer - ATEX, IECEx, EAC, PESO or cULus



(2) Not for multicertification M group I (mining) (3) Possible combined options: /DO, /DWP, /DOWP, /OWP

(4) Approved only for the Italian market

2 HYDRAULIC SYMBOLS The valves can be used in 2 or 3 way connection, depending to the application requirements. In 2 way the P port must not be connected (blocked) In 3 way the P port has to be connected to tank or to other user lines The port T must be always not connected (blocked) 2 way connection 3 way connection For application examples of 2 and 3 way connections, see section

3 ELECTRONIC DRIVERS

Electronic drivers are factory set with max current limitation for ex-proof valves.

Please include in the driver order also the complete code of the connected ex-proof proportional valve.

Drivers model	E-BM-AS-* /A	E-BM-AES-* /A			
Туре	digital	digital			
Format	DIN-rail panel				
Data sheet	G030	GS050			

4 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd valves according to EN ISO 13849	150 years, see technical table P007				
Ambient temperature range	Standard = $-20^{\circ}C \div +70^{\circ}C$ /PE option = $-20^{\circ}C \div +70^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Storage temperature range	Standard = $-20^{\circ}C \div +80^{\circ}C$ /PE option = $-20^{\circ}C \div +80^{\circ}C$ /BT option = $-40^{\circ}C \div +70^{\circ}C$				
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200h				
Compliance	Explosion proof protection, see section -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006				

5 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		QVHZA					QVKZA	
Max regulated flow	[l/min]	3,5	12	18	35	45	65	90
Min regulated flow	[cm³/min]	15	20	30	50	60	85	100
Regulating ∆p	[bar]	4 - 6 10 - 12			- 12	15	6 - 8	10 - 12
Max flow on port A	[l/min]		Z	0	50	55	70	100
Max pressure	[bar]				210			
Response time (1)	[ms]			≤ 35			≤	50
Hysteresis		\leq 5 [% of the regulated max flow]						
Linearity		≤ 3 [% of the regulated max flow]						
Repeatability				≤ 1 [% of	the regulated r	nax flow]		

Note: above performance data refer to valves coupled with Atos electronic drivers, see section 3

(1) 0 ÷100 % step signal

6 ELECTRICAL CHARACTERISTICS

Max. power	35	35W			
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account			
Protection degree with relevant cable gland	Multicertification: IP66/67 to DIN EN60529 UL: raintight enclosure, UL approved				
Duty factor	Continuous rating (ED=100%)				
Voltage code	standard	option /24			
Coil resistance R at 20°C	3,2 Ω	3,2 Ω 17,6 Ω			
Max. solenoid current	2,5 A	1,1 A			

7 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$, with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Max fluid	normal operation	ISO4406 class 18/16/13 NAS	see also filter section at KTF			
contamination level	longer life	ISO4406 class 16/14/11 NAS	catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	100 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

⁽¹⁾ Performance limitations in case of flame resistant fluids with water:

⁻max operating pressure = 180 bar -max fluid temperature = 50°C

8 CERTIFICATION DATA

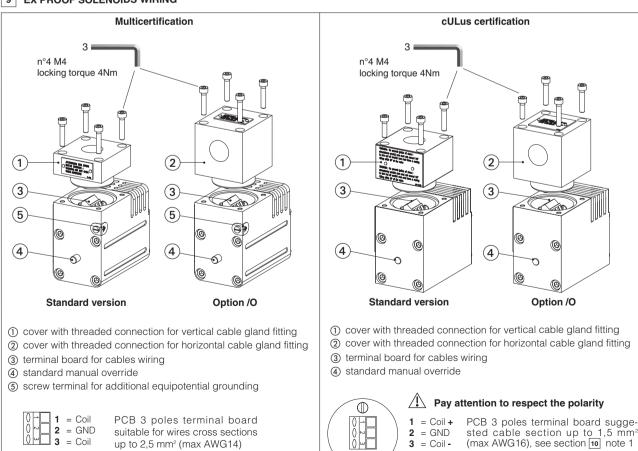
Valve type	QVHZA	, QVKZA	QVHZA /M , QVHZA /M	QVHZA /UL	qvhza /ul , qvhza /ul	
Certifications	Multicertifica	ation Group II	Multicertification Group I	North American		
	ATEX IECEx	EAC PESO	ATEX IECEx	cULus		
Solenoid certified code	OZ	A-A	OZAM-A	OZA	-A/EC	
Type examination certificate (1)	ATEX: CESI 02 ATEX 014 IECEx: IECEx CES 10.0010x EAC: TC RU C-IT. 08.B.01784 PESO: P338131		ATEX: CESI 03 ATEX 057x IECEx: IECEx CES 12.0007x	20170324	- E366100	
Method of protection	 ATEX, EAC ATEX, EAC Ex II 2G Ex d IIC T4/T3 Gb Ex III 2D Ex tb IIIC T135°C/T200°C Db IECEx Ex d IIC T4/T3 Gb Ex tb IIIC T135°C/T200°C Db PESO Ex II 2G Ex d IIC T4/T3 Gb 		ATEX Ex I M2 Ex db I Mb IECEx Ex db I Mb	UL 1203 Class I, Div.I, Groups C & Class I, Zone I, Groups II.		
Temperature class	T4	Т3	-	T4	Т3	
Surface temperature	≤ 135 °C	≤ 200 °C	≤ 150 °C	≤ 135 °C	≤ 200 °C	
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +70 °C	-20 ÷ +60 °C	-40 ÷ +55 °C	-40 ÷ +70 °C	
Applicable standards	EN 60079-0 EN 60079-1 EN 60079-31		IEC 60079-0 IEC 60079-1 IEC 60079-31	CSA 22.2	and UL429, n°30-1986 2 n°139-13	
Cable entrance: threaded connection vertical (standard) or horizontal (option /O)	GK = GK-1/2" M = M20x1,5 NPT = 1/2" NPT			1/2"	NPT	

(1) The type examinator certificates can be downloaded from

(2) The solenoids Group II and cULus are certified for minimum ambient temperature -40°C

In case the complete valve must withstand with minimum ambient temperature of -40°C, select /BT in the model code

WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification



9 EX PROOF SOLENOIDS WIRING

suitable for wires cross sections 3 = Coil up to 2,5 mm² (max AWG14)



0

 \square

3 = Coil -

alternative GND screw terminal connected to solenoid housing

Multicertification Group I and Group II

Power supply: section of coil connection wires = 2,5 mm²

Grounding: section of internal ground wire = 2,5 mm² section of external ground wire = 4 mm²

cULus certification:

- Suitable for use in Class I Division 1, Gas Groups C
- Armored Marine Shipboard Cable which meets UL 1309
- Tinned Stranded Copper ConductorsBronze braided armor
- Overall impervious sheath over the armor

Any Listed (UBVZ/ UBVZ7) Marine Shipboard Cable rated 300 V min, 15A min. 3C 2,5 mm² (14 AWG) having a suitable service temperature range of at least -25°C to +110°C ("/BT" Models require a temperature range from -40°C to +110°C)

Note 1: For Class I wiring the 3C 1,5 mm² AWG 16 cable size is admitted only if a fuse lower than 10 A is connected to the load side of the solenoid wiring.

10.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products. **Multicertification**

Max ambient temperature [°C]	Temperature class		Max surface temperature [°C]		Min. cable temperature [°C]	
	Goup I	Goup II	Goup I	Goup II	Goup I	Goup II
40 °C	-	T4	150 °C	135 °C	90 °C	90 °C
45 °C	-	T4	-	135 °C	-	95 °C
55 °C	-	T3	-	200 °C	-	110 °C
60 °C	-	-	150 °C	-	110 °C	-
70 °C	N.A.	Т3	N.A.	200 °C	N.A.	120 °C

cULus certification

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature	
55 °C	T4	135 °C	100 °C	
70 °C	T3	200 °C	100 °C	

11 CABLE GLANDS - only Multicertification

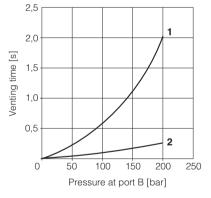
Cable glands with threaded connections GK-1/2", 1/2"NPT or M20x1,5 for standard or armoured cables have to be ordered separately, see tech. table **KX600**

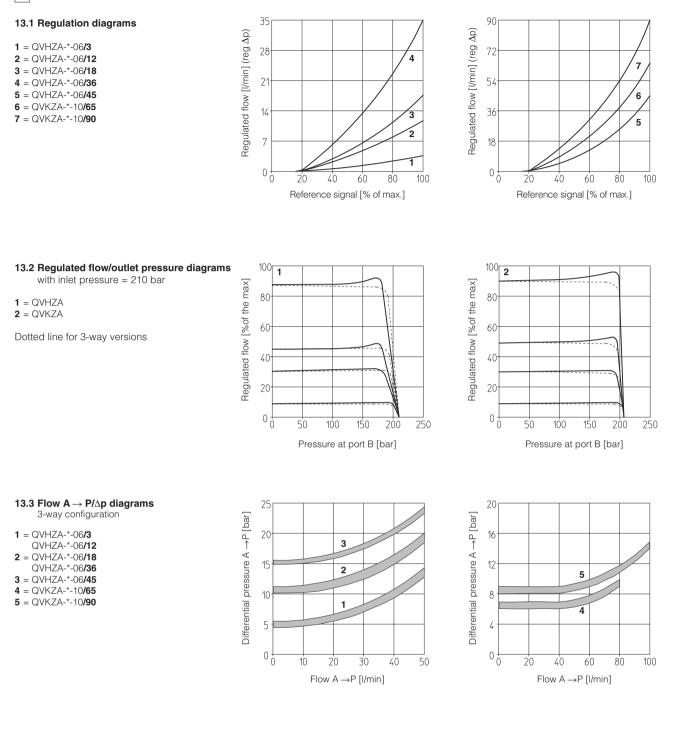
Note: a Loctite sealant type 545, should be used on the cable gland entry threads

12 OPTIONS

- D = This option provides a quick venting of the use port B when the valve is closed or de-energized. The valve must be connected in 3 way, with P port connected to tank. When the proportional throttle is fully closed, the valve's port B is internally connected to port P (tank), permitting a quickly decompression of the pressure in the use line. In the diagram aside are represented the venting times of QVHZA and QVKZA option /D
 - respect to standard versions:
 - 1 = standard versions
 - **2** = option /D
- **O** = Horizontal cable entrance , to be selected in case of limited verical space.

WP = Manual override protected by metallic cap.



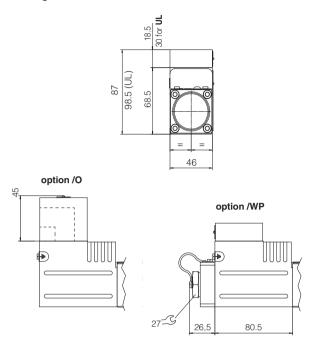


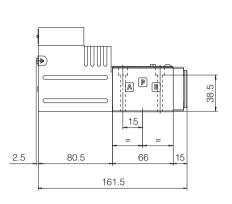
14 FASTENING BOLTS AND SEALS

	QVHZA	QVKZA
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm
0	Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø7,5 mm (max)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max)

QVHZA-A

ISO 4401: 2005 (see tab. P005) Mounting surface: 4401-03-02-0-05





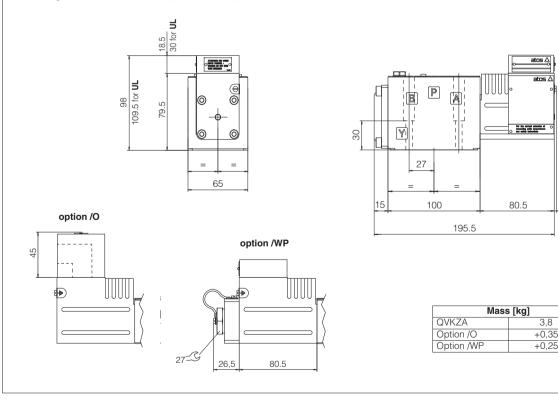
Mass [kg]					
QVHZA 2,3					
Option /O	+0,35				
Option /WP	+0,25				

2.5

QVKZA-A

ISO 4401: 2005

Mounting surface: 4401-05-04-0-05 (see tab. P005)



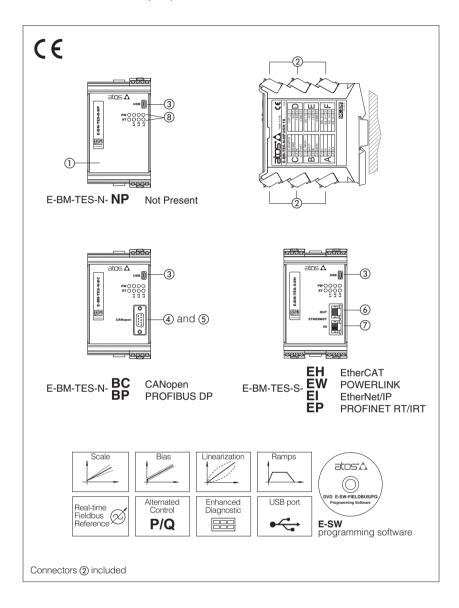
16 RELATED DOCUMENTATION

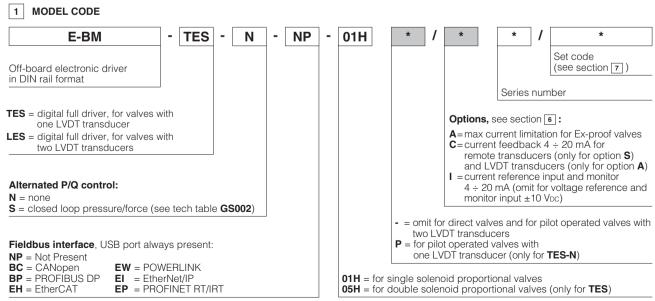
X010Basics for electrohydraulics in hazardous environmentsX020Summary of Atos ex-proof components certified to ATEX, IECEX, EAC, PESOX030Summary of Atos ex-proof components certified to cULusFX900Operating and manintenance information for ex-proof proportional valvesKX800Cable glands for ex-proof valvesP005Mounting surfaces for electrohydraulic valves

atos®

Digital E-BM-TES/LES drivers

DIN-rail format, for proportional valves with one or two LVDT transducers





E-BM-TES/LES

Digital drivers ① control in closed loop the position of the spool or poppet of direct and pilot operated proportional valves, according to the electronic reference input signal.

TES execution controls direct operated directional/flow valves with one LVDT transducer.

LES execution controls pilot operated directional valves with two LVDT transducers. Option S adds the closed loop control of pressure (SP) or force (SF and SL) to the basic functions of proportional directional valves flow regulation (see section 4). Atos PC software allows to customize the driver configuration to the specific application requirements.

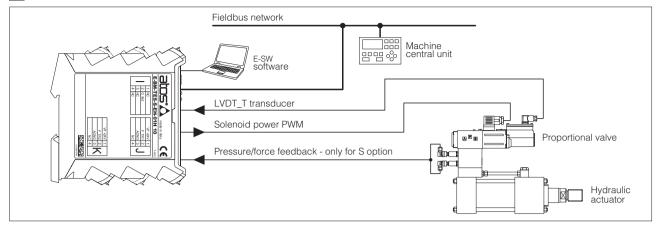
Electrical Features:

- up to 9 fast plug-in connectors (2)
- Mini USB port (3) always present
- DB9 fieldbus communication connector
 ④ for CANopen and ⑤ PROFIBUS DP
- RJ45 ethernet communication connectors
 (a) output and (b) input for EtherCAT, POWERLINK, EtherNet/IP, PROFINET
- 8 leds for diagnostics (8) (see 6.1)
- Electrical protection against reverse polarity of power supply
- Operating temperature range: -20 ÷ +50 °C
- Plastic box with IP20 protection degree and standard DIN-rail mounting
- CE mark according to EMC directive

Software Features:

- Intuitive graphic interface
- Setting of valve's functional parameters: bias, scale, ramps, dither
- Linearization function for hydraulic regulation
- Setting of PID gains
- Selection of analog IN / OUT range
- Complete diagnostic of driver status
- Internal oscilloscope function
- In field firmware update through USB port

2 BLOCK DIAGRAM EXAMPLE



3 VALVES RANGE

Valves	Directional			Flow	Directional	Cartridge
Standard	DHZO-T, DKZOR-T	DLHZO-T, DLKZOR-T	DPZO-T	QVHZO-T, QVKZOR-T	DPZO-L	LIQZO-L, LIQZP-L
Data sheet	F165	F180	F172	F1412	F175	F330, F340
Ex-proof	DHZA-T, DKZA-T	DLHZA-T, DLKZA-T	DPZA-T	QVHZA-T, QVKZA-T		
Data sheet	FX120	FX140	FX220	FX420	-	-
Driver model		E-BM-T	E-I	BM-LEB		

Option S not available

4 ALTERNATED P/Q CONTROL - only for S option

S option on digital drivers adds the closed loop control of pressure (SP) or force (SF and SL) to the basic functions of proportional directional valves flow regulation.

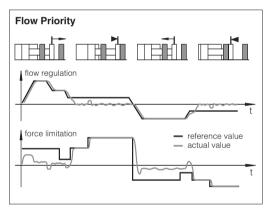
The alternated P/Q control operates according to the two electronic reference signals by a dedicated algorithm that automatically selects which control will be active time by time. The dynamics of the switching between the two controls can be regulated thanks to specific software setting, in order to avoid instability or vibrations.

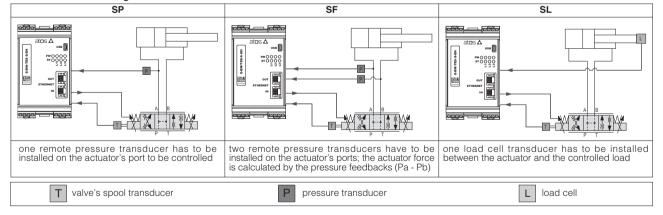
Flow regulation is active when the actual system pressure/force is lower than the relevant input reference signal - the valve works normally to regulate the flow by controlling in closed-loop the spool/poppet position through the integral LVDT transducer. Pressure/force control is activated when the actual system pressure/force, measured by remote transducers, grows up to the relevant input reference signal - the driver reduces the valve's flow regulation in order to keep steady the system pressure/force. If the pressure/force tends to decrease under its input reference signal, the flow control returns active.

The dynamic response of pressure/force control can be adapted to different system's characteristics, by setting the internal PID parameters using Atos PC software. Up to 4 different PIDs are selectable to optimize the system dynamic response accor-

ding to different hydraulic working conditions.







SP - flow/pressure control

Adds pressure control to standard flow control and permits to limit the max force in one direction controlling in closed loop the pressure acting on one side of the hydraulic actuator. A single pressure transducer has to be installed on hydraulic line to be controlled.

SF – flow/force control

Adds force control to standard flow control and permits to limit the max force in two directions controlling in closed loop the delta pressure acting on both sides of the hydraulic actuator. Two pressure transducers have to be installed on both hydraulic line.

SL - flow/force control

Adds force control to standard flow control and permits to limit the max force in one or two directions controlling in closed loop the force performed by the hydraulic actuator. A load cell has to be installed on hydraulic actuator.

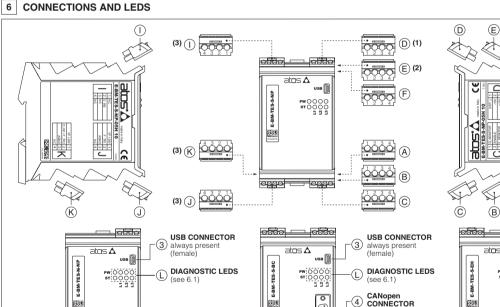
General Notes:

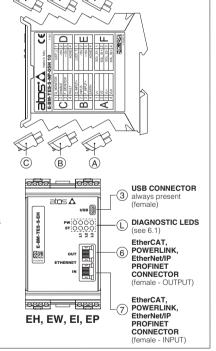
- auxiliary check valves are recommended in case of specific hydraulic configuration requirements in absence of power supply or fault see tech table EY105
- for additional information about alternated P/Q controls configuration please refer to tech table GS002
- Atos technical service is available for additional evaluations related to specific applications usage

5 MAIN CHARACTERISTICS

Power supplies	(see 8.1, 8.2)	Nominal Rectified and filtered	: +24 Vdc : Vrms = 20 ÷ 32 VmA	x (ripple max 10 % VPP)			
Max power consumption		50 W					
Current supplied to solence	ids	IMAX = 3.0 A for standa IMAX = 2.5 A for ex-pro					
Analog input signals	(see 8.3, 8.4)	Voltage: range ±10 V Current: range ±20 n	$\begin{array}{llllllllllllllllllllllllllllllllllll$				
Monitor outputs	(see 8.5, 8.6)		voltage ±10 Vbc @ current ±20 mA @ r	max 5 mA max 500 Ω load resistan	ce		
Enable input Digital inputs	(see 8.7) (see 8.11)	Range: 0 ÷ 5 Vpc (OFI	F state), 9 ÷ 24 Vpc (ON	I state), 5 ÷ 9 Vpc (not ac	ccepted); Input impedance: Ri > 10 k Ω		
Fault output	(see 8.8)	Output range: 0 ÷ 24 external negative volta	VDC (ON state > [powe age not allowed (e.g. du	er supply - 2 V] ; OFF sta ue to inductive loads)	ate < 1 V) @ max 50 mA;		
Alarms			Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, valve spool transducer malfunctions, alarms history storage function				
Pressure/Force transducer (only for S option)	rs power supply	+24Vpc @ max 100 mA (E-ATR-8 see tech table GS465)					
Format		Plastic box ; IP20 protection degree ; L 35 - H 7,5 mm DIN-rail mounting as per EN60715					
Operating temperature		-20 ÷ +50 °C (storage -25 ÷ +85 °C)					
Mass		Approx. 400 g					
Additional characteristics		8 leds for diagnostic;	protection against reve	rse polarity of power sup	pply		
Electromagnetic compatibili	ty (EMC)	According to Directive	2014/30/UE (Immunity	: EN 61000-6-2; Emissic	on: EN 61000-6-3)		
Compliance		RoHs Directive 2011/6 REACH Regulation (E	5/EU as last update by C) n°1907/2006	2015/65/EU			
Communication interface		USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158		
Communication physical layer		not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX		
Recommended wiring cab	le			or logic - 1,5 mm ² manual manual for the transducers dates the t	ax 50 m for power supply tasheet		
Max conductor size	(see 12)	2,5 mm ²					
		1					

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 Vbc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.





F

(1) D connector is available only for TES-N versions 01HP / 05HP and LES-* (2) E connector is available only for TES-* versions 01H / 05H and LES-* (3) I, J and K connectors are available only for TES-S and LES-S

0000

NP

(4) To interface with Siemens 6ES7972-0BA12-0XA connector, it is mandatory to use also one of the following adapters to avoid interference with the USB connector: DG909MF1 - the connector will be oriented upwards

DG909MF3 - the connector will be oriented downwards

6.1 Diagnostic LEDs (L)

A,B,C,D,E,F,I,J,K connectors included

Eight leds show driver operative conditions for immediate basic diagnostics. Please refer to the driver user manual for detailed information.

FIELDBUS	NP	BC	BP	EH	EW	EI	EP	PW L1 L2 L3
LEDS	Not Present	CANopen	PROFIBUS DP	EtherCAT	POWERLINK	EtherNet/IP	PROFINET	
L1	VALVE STATUS			LINK/ACT				
L2	NETWORK STATUS			NETWORK STATUS				
L3	SOLENOID STATUS			LINK/ACT				
PW	OFF = Power s	upply OFF	ON = Pow	ower supply ON				
ST	OFF = Fault pre	esent	ON = No fa	= No fault				ST

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(5)

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- 0999

BC, BP

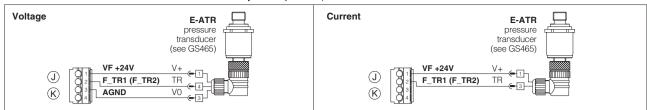
(male)

PROFIBUS DP CONNECTOR (4) (female)

CONNECTOR	PIN	ALTERNATED N none	P/Q CONTROL S pressure/force	TECHNICAL SPECIFICATIONS	NOTES
	A1	V+		Power supply 24 VDc (see 8.1)	Input - power supply
А	A2	VO		Power supply 0 Vbc (see 8.1)	Gnd - power supply
	A3	VL+		Power supply 24 Vbc for driver's logic and communication (see 8.2)	Input - power supply
	A4	VL0		Power supply 0 VDC for driver's logic and communication (see 8.2)	Gnd - power supply
	B1	Q_INPUT+		Flow reference input signal: ± 10 Vpc / ± 20 mA maximum range Default are ± 10 Vpc for standard and 4 $\div 20$ mA for /l option (see 8.3)	Input - analog signal Software selectable
_	B2	INPUT-		Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
B	B3	NC		Do not connect	
	03		F_INPUT+	Pressure/Force reference input signal ± 10 Vpc / ± 20 mA maximum range Default are ± 10 Vpc for standard and $4 \div 20$ mA for /l option (see 8.4)	Input - analog signal Software selectable
	B4	EARTH		Connect to system ground	
	C1	Q_MONITOR		Flow monitor output signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND. Default are ± 10 Vpc for standard and 4 $\div 20$ mA for /l option (see 8.5)	Output - analog signal Software selectable
	C2	ENABLE		Enable (24 Vbc) or disable (0 Vbc) the controller, referred to VL0 (see 8.7)	Input - on/off signal
С		NC		Do not connect	
	C3		F_MONITOR	Pressure/Force monitor output signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND Default are ± 10 Vpc for standard and $4 \div 20$ mA for /l option (see 8.6)	Output - analog signal Software selectable
	C4	FAULT	I	Fault (0 VDc) or normal working (24 VDc), referred to VL0 (see 8.8)	Output - on/off signal
	D1	LVDT_L		Main stage valve position transducer signal (see 8.9)	Input - analog signal
	D2	-15V		Main stage valve position transducer power supply -15V	Output power supply
D (1)	D3	+15V		Main stage valve position transducer power supply +15V	Output power supply
	D4	AGND		Common gnd for transducer power and monitor outputs	Common gnd
	E1	LVDT_T		Direct valve or pilot valve position transducer signal (see 8.9)	Input - analog signal
F	E2	-15V		Direct valve or pilot valve position transducer power supply -15V	Output power supply
E (2)	E3	+15V		Direct valve or pilot valve position transducer power supply +15V	Output power supply
	E4	AGND		Common gnd for transducer power and monitor outputs	Common gnd
	F1	SOL_S1-		Negative current to solenoid S1	Output - power PWM
F	F2	SOL_S1+		Positive current to solenoid S1	Output - power PWM
1	F3	SOL_S2-		Negative current to solenoid S2	Output - power PWM
	F4	SOL_S2+		Positive current to solenoid S2	Output - power PWM
	11		NC	Do not connect	
I	12	-	D_IN0	NP execution: multiple pressure/force PID selection, referred to VL0 (see 8.11) Fieldbus execution: general purpose digital input 0 ÷ 24Vbc, referred to VL0 (see 8.11)	Input - on/off signal
	13		NC	Do not connect	
	14	NC		Do not connect	
	J1		VF +24V	Power supply: +24Vbc or OFF (default OFF)	Output - power supply Software selectable
J	J2		F_TR1	1st signal pressure/force transducer: $\pm 10 \text{ Vpc} / \pm 20 \text{ mA maximum range}$ Default are $\pm 10 \text{ Vpc}$ for standard and 4 $\div 20 \text{ mA for /C option}$ (see 8.10)	Input - analog signal Software selectable
	J3	AGND		Common gnd for transducer power and signals	Common gnd
	J4	NC		Do not connect	
	K1		VF +24V	Power supply: +24Vbc or OFF (default OFF)	Output - power supply Software selectable
К			F_TR2	2nd signal pressure transducer (only for SF): $\pm 10 \text{ Vpc} / \pm 20 \text{ mA maximum range}$ Default are $\pm 10 \text{ Vpc}$ for standard and 4 $\div 20 \text{ mA for /C option}$ (see 8.10)	Input - analog signal Software selectable
	K2		D_IN1	NP execution: multiple pressure/force PID selection (only for SP and SL), referred to VL0 (see 8.11) Fieldbus execution: general purpose digital input 0 ÷ 24Vbc, referred to VL0 (see 8.11)	Input - on/off signal
	КЗ		AGND	Common gnd for transducer power and signals	Common gnd
	K4		NC	Do not connect	

(1) D connector is available only for TES-N versions 01HP / 05HP and LES-* (2) E connector is available only for TES-* versions 01H / 05H and LES-*

6.3 Pressure/force transducers connection - example - only for S option



6.4 Communication connectors (3 - (4 - (5 - (6 - (7)

3	③ USB connector - Mini USB type B always present					
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)				
1	+5V_USB	Power supply				
2	D-	Data line -				
3	D+	Data line +				
4	ID	Identification				
5	GND_USB	Signal zero data line				

5	5 BP fieldbus execution, connector - DB9 - 9 pin					
PIN	SIGNAL TECHNICAL SPECIFICATION (1)					
1	SHIELD					
3	LINE-B Bus line (low)					
5	DGND Data line and termination signal zero					
6	+5V	Termination supply signal				
8	LINE-A	Bus line (high)				

(1) shield connection on connector's housing is recommended

7 SET CODE

The basic calibration of electronic driver is factory preset, according to the proportional valve to be coupled. These pre-calibrations are identified by the set code at the end of driver's model code (see section 1). For correct set code selection, please include in the driver order also the complete code of the coupled proportional valve. For further information about set code, please contact Atos technical office.

8 SIGNALS SPECIFICATIONS

Atos digital drivers are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive).

Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **F003** and in the user manuals included in the E-SW-* programming software.

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

8.1 Power supply (V+ and V0)

The power supply (pin A1 and A2) must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

8.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply (pin A3 and A4) for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic, allow to remove solenoid power supply from pin A1 and A2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

8.3 Flow reference input signals (Q_INPUT+)

The driver is designed to receive an analog reference input signal (pin B1) for the valve's spool position.

Reference input signal is factory preset according to selected valve code, defaults are ± 10 Vbc for standard and $4 \div 20$ mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 Vbc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ Vbc.

8.4 Pressure or force reference input signal (F_INPUT+) - only for S option

Functionality of pressure or force input reference signal (pin B3), is used as reference for the driver pressure/force closed loop, see section $\boxed{4}$. Reference input signal is factory preset according to selected valve code, defaults are ±10 Vbc for standard and 4 ÷ 20 mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vbc or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range 0 ÷ 24 Vbc.

4	④ BC fieldbus execution, connector - DB9 - 9 pin				
PIN	SIGNAL TECHNICAL SPECIFICATION (1)				
2	CAN_L	Bus line (low)			
3	CAN_GND	Signal zero data line			
5	CAN_SHLD Shield				
7	CAN_H	CAN_H Bus line (high)			

6 7 EH, EW, EI, EP fieldbus execution, connector - RJ45 - 8 pin						
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)				
1	TX+	Transmitter	-	white/orange		
2	RX+	Receiver	-	white/green		
3	TX-	Transmitter	-	orange		
6	RX-	Receiver	-	green		

8.5 Flow monitor output signal (Q MONITOR)

The driver generates an analog output signal (pin C1) proportional to the actual spool position; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, valve spool position). Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ± 20 mA.

8.6 Pressure or force monitor output signal (F_MONITOR) - only for S option

The driver generates an analog output signal (C3) proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 Vpc for standard and 4 ÷ 20 mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vpc or ± 20 mA

8.7 Enable input signal (ENABLE)

To enable the driver, supply 24 Vbc on pin C2: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as digital input by software selection.

8.8 Fault output signal (FAULT)

Fault output signal (pin C4) indicates fault conditions of the driver (solenoid short circuits/not connected, reference or transducer signal cable broken, maximum error exceeded, etc.). Fault presence corresponds to 0 Vpc, normal working corresponds to 24 Vpc. Fault status is not affected by the status of the Enable input signal.

Fault output signal can be used as digital output by software selection.

8.9 Main stage and direct or pilot position transducer input signals (LVDT_L and LVDT_T)

Main stage (LVDT_L pin D1) and direct or pilot (LVDT_T pin E1) position transducer integrated to the valve have to be directly connected to the driver using ± 15 Vpc supply output available at pin D2, D3 and pin E2, E3. Note: transducer input signals working range is ± 10 Vpc for standard or 4 \div 20 mA for /C option and **cannot** be reconfigured via software

(input signals setting depends to the driver set code).

8.10 Remote pressure/force transducer input signals (F_TR1 and F_TR2) - only for S option

Analog remote pressure transducers or load cell can be directly connected to the driver. Analog input signal is factory preset according to selected driver code, defaults are ±10 Vpc for standard and 4 ÷ 20 mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vbc or ± 20 mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see tech table GS002).

8.11 Multiple PID selection or digital input signals (D_IN0 and D_IN1) - only for S option

Two on-off input signals are available on the connectors I and K. For NP executions pin I2 and/or pin K2 are used to select one of the four pressure (force) PID parameters setting, stored into the driver. Switching the active setting of pressure PID during the machine cycle allows to optimize the system dynamic response in different hydraulic working conditions (volume, flow, etc.). Supply a 24 Vpc or a 0 Vpc on pin I2 and/or pin K2, to select one of the PID settings as indicated by binary code table at side. Gray code can be selected by software. For fieldbus executions pin I2 and/or K2 can be used as generic purpose on-off input signals.

		PID SET SELECTION						
PIN	SET 1	SET 2	SET 3	SET 4				
12	0	24 Vpc	0	24 Vdc				
K2	0	0	24 Vdc	24 VDC				

8.12 Possible combined options: /AC, /AI, /ACI, /CI - combined options /CI is available only for E-BM-TES/LES-S.

9 VALVE SETTINGS AND PROGRAMMING TOOLS

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table GS003). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is av	allable in	different versions acc	cording to the driver's o	options (see table GS500):
E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)
E-SW-*/PQ	support:	valves with SP. SF. S	SL alternated control (e	e.a. E-SW-BASIC/PQ)

WARNING: drivers USB port is not isolated! For E-C-SB-USB/BM cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

Free programming software, web download:

.. . . .

E-SW-BASIC web download = software can be downloaded upon web registration at ; service and DVD not included Upon web registration user receive via email the Activation Code (software free license) and login data to access Atos Download Area

DVD programming software, to be ordered separately:

- DVD first supply = software has to be activated via web registration at ; 1 year service included E-SW-*/PQ Upon web registration user receive via email the Activation Code (software license) and login data to access Atos Download Area E-SW-*-N/PQ DVD next supplies = only for supplies after the first; service not included, web registration not allowed
- Software has to be activated with Activation Code received upon first supply web registration

Atos Download Area: direct access to latest releases of E-SW software, manuals, USB drivers and fieldbus configuration files at USB

Adapters, Cables and Terminators, can be ordered separately

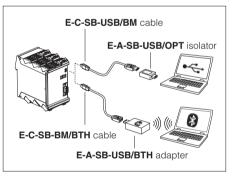
10 MAIN SOFTWARE PARAMETER SETTINGS

For basic information about main setting parameters by E-SW programming software, see tech table GS003

For detailed descriptions of settings, wirings and installation procedures, please refer to the user manual included in the E-SW programming software:

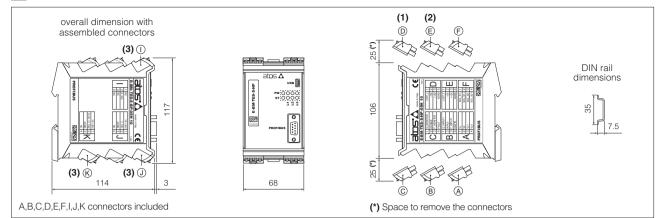
E-MAN-BM-LES - user manual for E-BM-TES-N and E-BM-LES-N digital drivers E-MAN-BM-LES-S - user manual for E-BM-TES-S and E-BM-LES-S digital drivers

USB or Bluetooth connection

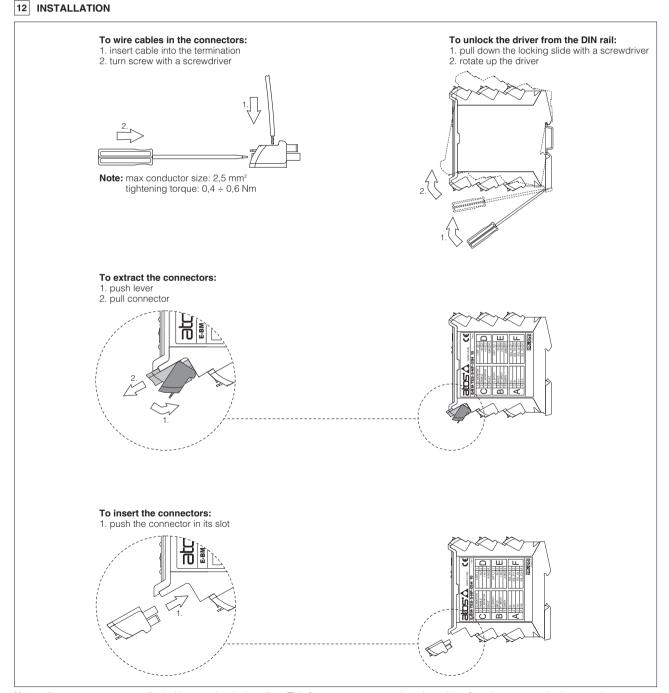




11 OVERALL DIMENSIONS [mm]



(1) D connector is available only for TES-N versions 01HP / 05HP and LES-*
(2) E connector is available only for TES-* versions 01H / 05H and LES-*
(3) I, J and K connectors are available only for TES-S and LES-S

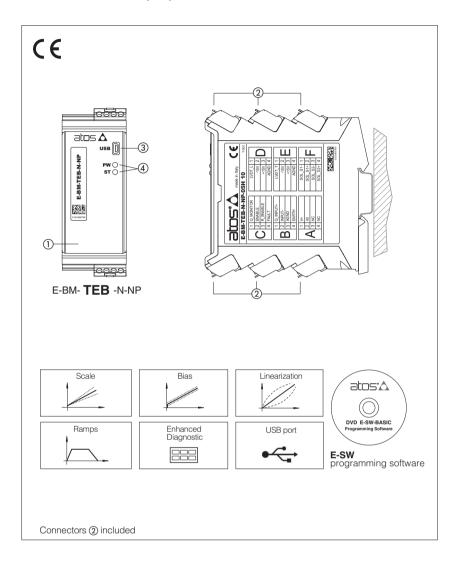


Note: all connectors are supplied with a mechanical coding. This feature ensures a unique insertion of each connector in the own slot. (e.g. connector A can not be inserted into connector slot of B,C,D,E,F,I,J,K)

atos°A

Digital E-BM-TEB/LEB drivers

DIN-rail format, for proportional valves with one or two LVDT transducers



1 MODEL CODE

E-BM	- T	ΈB] - [Ν	-	NP	-	01H	*	/	*	*	/	*
Off-board electronic driver in DIN rail format														Set code (see section 6)
												Seri	es nur	mber
TEB = digital basic driver, for valves one LVDT transducer LEB = digital basic driver, for valves two LVDT transducers											A=max C=curre sduc I =curre 4 ÷ 2	ent feedb cers only ent refere	imitati back 4 in cor ence ir mit for	on for Ex-proof valves ÷ 20 mA for LVDT tran- mbination with option A hput and monitor r voltage reference and
Alternated P/Q control: N = none													l for p	ilot operated valves with
									P = fo	r pilo	DT transc t operate DT transc	d valves		TEB)
Fieldbus interface, USB port alway	ys pre	esent	:						r single s					s (only for TEB)

E-BM-TEB/LEB

Digital drivers ① control in closed loop the position of the spool or poppet of direct and pilot operated proportional valves, according to the electronic reference input signal.

TEB execution controls direct operated directional/flow valves with one LVDT transducer.

LEB execution controls pilot operated directional valves with two LVDT transducers. Atos PC software allows to customize the driver configuration to the specific application requirements.

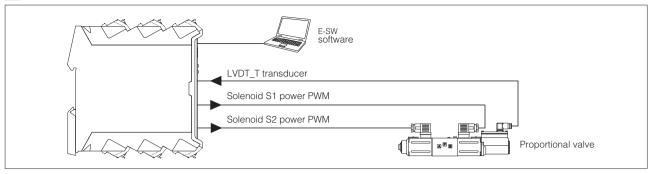
Electrical Features:

- 6 fast plug-in connectors (2)
- Mini USB port (3) always present
- 2 leds for diagnostics ④ (see 5.1)
- Electrical protection against reverse polarity of power supply
- Operating temperature range: -20 ÷ +60 °C
- Plastic box with IP20 protection degree and standard DIN-rail mounting
- CE mark according to EMC directive

Software Features:

- Intuitive graphic interface
- Setting of valve's functional parameters: bias, scale, ramps, dither
- Linearization function for hydraulic regulation
- Setting of PID gains
- Selection of analog IN / OUT range
- Complete diagnostic of driver status
- Internal oscilloscope function
- In field firmware update through USB port

2 BLOCK DIAGRAM EXAMPLE



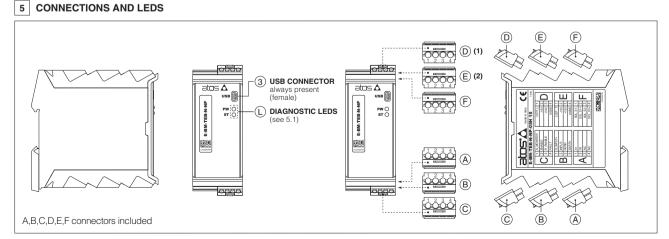
3 VALVES RANGE

Valves		Directional		Flow	Directional	Cartridge
Standard Data sheet	DHZO-T, DKZOR-T F165	DLHZO-T, DLKZOR-T F180	DPZO-T F172	QVHZO-T, QVKZOR-T F412	DPZO-L F175	LIQZO-L, LIQZP-L F330, F340
Ex-proof Data sheet	DHZA-T, DKZA-T FX120	DLHZA-T, DLKZA-T FX140	DPZA-T FX220	QVHZA-T, QVKZA-T FX420	-	-
Driver model		E-BM-T	E-I	BM-LEB		

4 MAIN CHARACTERISTICS

Power supply	(see 7.1)	Nominal: +24 VbcRectified and filtered: VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)
Max power consumption		50 W
Current supplied to solenoid	S	IMAX = 3.0 A for standard driver IMAX = 2.5 A for ex-proof driver (/A option)
Analog input signal	(see 7.2)	$ \begin{array}{llllllllllllllllllllllllllllllllllll$
Monitor output	(see 7.3)	Output range: voltage ±10 Vpc @ max 5 mA current ±20 mA @ max 500 Ω load resistance
Enable input	(see 7.4)	Range: $0 \div 5$ Vpc (OFF state), $9 \div 24$ Vpc (ON state), $5 \div 9$ Vpc (not accepted); Input impedance: Ri > 10 k Ω
	(see 7.5) (see 7.6)	Output range: 0 ÷ 24 Vbc (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)
Alarms		Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, valve spool transducer malfunctions, alarms history storage function
Format		Plastic box ; IP20 protection degree ; L 35 - H 7,5 mm DIN-rail mounting as per EN60715
Operating temperature		-20 ÷ +60 °C (storage -25 ÷ +85 °C)
Mass		Approx. 400 g
Additional characteristics		2 leds for diagnostic; protection against reverse polarity of power supply
Electromagnetic compatibility	(EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)
Compliance		RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006
Communication interface		USB Atos ASCII coding
Communication physical lay	er	USB 2.0 + USB OTG not insulated
Recommended wiring cable		LiYCY shielded cables: 0,5 mm ² max 50 m for logic - 1,5 mm ² max 50 m for power supply Note: for transducers wiring cable please consult the transducers datasheet
Max conductor size	(see 11)	2,5 mm ²

Note: a maximum time of 400 ms have be considered between the driver energizing with the 24 V_{DC} power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.



(1) D connector is available only for TEB-N versions 01HP / 05HP and LEB-N (2) E connector is available only for TEB-N versions 01H / 05H and LEB-N $\,$

5.1 Diagnostic LEDs (L)

Two leds show driver operative conditions for immediate basic diagnostics. Please refer to the driver user manual for detailed information.

LEDS	DESCRIPTION		USB
PW	OFF = Power supply OFF	ON = Power supply ON	Z PW O
ST	OFF = Fault present	ON = No fault	ST O

5.2 Connectors - 4 pin

CONNECTOR	PIN	SIGNALS	TECHNICAL SPECIFICATIONS	NOTES			
	A1	V+	Power supply 24 Vbc (see 7.1)	Input - power supply			
Λ	A2	VO	Power supply 0 VDc (see 7.1)	Gnd - power supply			
A	A3	NC	Do not connect				
	A4	NC	Do not connect				
	B1	Q_INPUT+	Flow reference input signal: ± 10 Vpc / ± 20 mA maximum range Default are ± 10 Vpc for standard and $4 \div 20$ mA for /l option (see 7.2)	Input - analog signal Software selectable			
B	B2	INPUT-	Negative reference input signal for Q_INPUT+	Input - analog signal			
D	B3	AGND	Common gnd for monitor output	Common gnd			
	B4	EARTH	Connect to system ground				
	C1	Q_MONITOR	Flow monitor output signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND Default are ± 10 Vpc for standard and $4 \div 20$ mA for /l option (see 7.3)	Output - analog signal Software selectable			
С	C2	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the controller, referred to V0 $$ (see 7.4)	Input - on/off signal			
	C3	R_ENABLE	Repeat enable, output repeater signal of enable input, referred to V0 (see 7.5)	Output - on/off signal			
	C4	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to V0 (see 7.6)	Output - on/off signal			
	D1	LVDT_L	VDT_L Main stage valve position transducer signal (see 7.7)				
	D2	-15V	Main stage valve position transducer power supply -15V	Output power supply			
D (1)	D3	+15V	Main stage valve position transducer power supply +15V	Output power supply			
	D4	AGND	Common gnd for transducer power	Common gnd			
	E1	LVDT_T	Direct valve or pilot valve position transducer signal (see 7.7)	Input - analog signal			
E (2)	E2	-15V	Direct valve or pilot valve stage position transducer power supply -15V	Output power supply			
L (2)	E3	+15V	Direct valve or pilot valve tage position transducer power supply +15V	Output power supply			
	E4	AGND	Common gnd for transducer power	Common gnd			
	F1	SOL_S1-	Negative current to solenoid S1	Output - power PWM			
F	F2	SOL_S1+	Positive current to solenoid S1	Output - power PWM			
	F3	SOL_S2-	Negative current to solenoid S2	Output - power PWM			
	F4	SOL_S2+	Positive current to solenoid S2	Output - power PWM			

(1) D connector is available only for TEB-N versions ${\rm 01HP}\,/\,{\rm 05HP}$ and LEB-N

(2) E connector is available only for TEB-N versions 01H / 05H and LEB-N

6 SET CODE

The basic calibration of electronic driver is factory preset, according to the proportional valve to be coupled. These pre-calibrations are identified by the set code at the end of driver's model code (see section 1). For correct set code selection, please include in the driver order also the complete code of the coupled proportional valve. For further information about set code, please contact Atos technical office.

7 SIGNALS SPECIFICATIONS

Atos digital drivers are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive).

Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table F003 and in the user manuals included in the E-SW-* programming software.

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and componentshydraulics, ISO 4413).

7.1 Power supply (V+ and V0)

The power supply (pin A1 and A2) must be appropriately stabilized or rectified and filtered: apply at least a 10000 µF/40 V capacitance to single phase rectifiers or a 4700 µF/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

7.2 Flow reference input signal (Q_INPUT+)

The driver is designed to receive an analog reference input signal (pin B1) for the valve's spool position. Reference input signal is factory preset according to selected valve code, defaults are ±10 Vbc for standard and 4 ÷ 20 mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ± 20 mA.

7.3 Flow monitor output signal (Q MONITOR)

The driver generates an analog output signal (pin C1) proportional to the actual spool position; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, valve spool position). Monitor output signal is factory preset according to selected valve code, defaults are ±10 Vpc for standard and 4 ÷ 20 mA for /l option.

Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ± 20 mA.

7.4 Enable input signal (ENABLE)

To enable the driver, supply 24 Vbc on pin C2: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition does not comply with norms IEC 61508 and ISO 13849.

7.5 Repeat enable output signal (R_ENABLE)

Repeat enable (pin C3) is used as output repeater signal of enable input signal (see 7.4).

7.6 Fault output signal (FAULT)

Fault output signal (pin C4) indicates fault conditions of the driver (solenoid short circuits/not connected, reference or transducer signal cable broken, maximum error exceeded, etc.). Fault presence corresponds to 0 Vbc, normal working corresponds to 24 Vbc. Fault status is not affected by the status of the Enable input signal.

7.7 Main stage and direct or pilot position transducer input signals (LVDT L and LVDT T)

Main stage (LVDT L pin D1) and direct or pilot (LVDT T pin E1) position transducer integrated to the valve have to be directly connected to the driver using ±15 Vpc supply output available at pin D2, D3 and pin E2, E3.

Note: transducer input signals working range is ±10 Vpc for standard or 4 ÷ 20 mA for /C option and cannot be reconfigured via software (input signals setting depends to the driver set code).

7.8 Possible combined options: /AC, /AI, /ACI

8 VALVE SETTINGS AND PROGRAMMING TOOLS

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table GS003). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)
E-SW-*/PQ	support:	valves with SP, SF, S	SL alternated control (e	e.g. E-SW-BASIC/PQ)

WARNING: drivers USB port is not isolated! For E-C-SB-USB/BM cable, the use of

isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

Free programming software, web download:

E-SW-BASIC web download = software can be downloaded upon web registration at ; service and DVD not included Upon web registration user receive via email the Activation Code (software free license) and login data to access Atos Download Area

DVD programming software, to be ordered separately:

- E-SW-*/PQ DVD first supply = software has to be activated via web registration at ; 1 year service included Upon web registration user receive via email the Activation Code (software license) and login data to access Atos Download Area
- E-SW-*-N/PQ DVD next supplies = only for supplies after the first; service not included, web registration not allowed Software has to be activated with Activation Code received upon first supply web registration

Atos Download Area: direct access to latest releases of E-SW software, manuals, USB drivers and fieldbus configuration files at USB

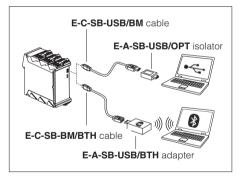
Adapters, Cables and Terminators, can be ordered separately

9 MAIN SOFTWARE PARAMETER SETTINGS

For basic information about main setting parameters by E-SW programming software, see tech table GS003

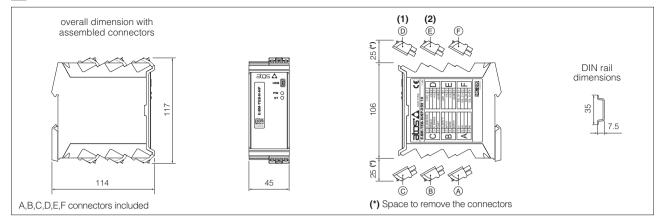
For detailed descriptions of settings, wirings and installation procedures, please refer to the user manual included in the E-SW programming software: E-MAN-BM-LEB - user manual for E-BM-TEB and E-BM-LEB digital drivers

USB or Bluetooth connection

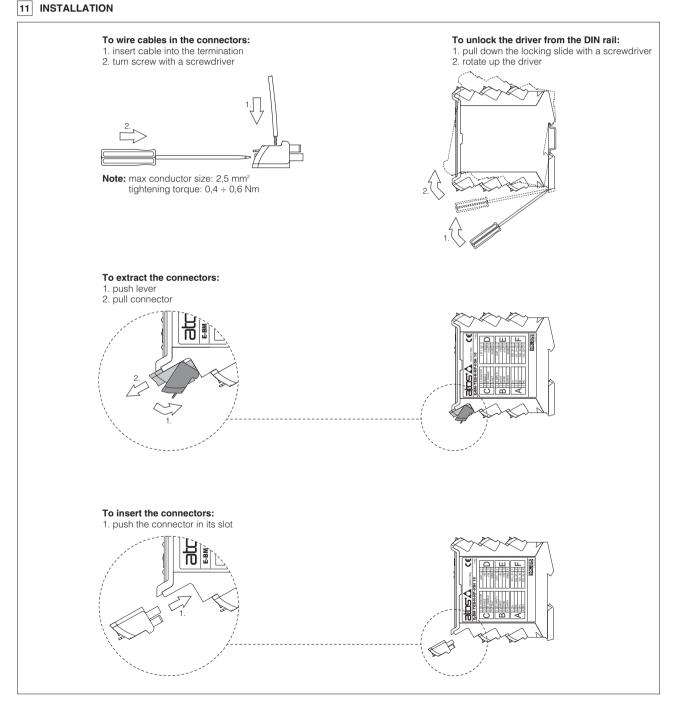




10 OVERALL DIMENSIONS [mm]



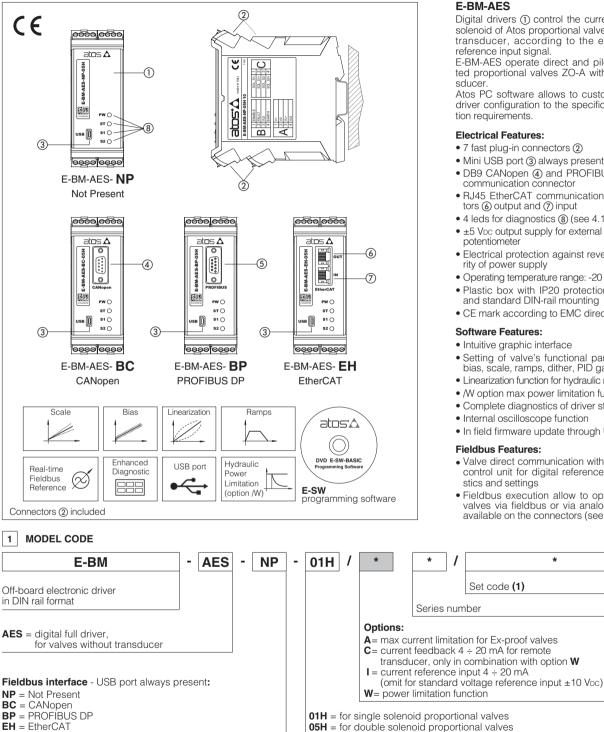
(1) D connector is available only for TEB-N versions 01HP / 05HP and LEB-N (2) E connector is available only for TEB-N versions 01H / 05H and LEB-N



Note: all connectors are supplied with a mechanical coding. This feature ensures a unique insertion of each connector in the own slot. (e.g. connector A can not be inserted into connector slot of B,C,D,E,F)

Digital electronic E-BM-AES drivers

DIN-rail format, for proportional valves without transducer



(1) set code identifies the corrispondence between the driver and the relevant valve

2 VALVES RANGE

Valves	Pressure					Direction	al	Cartridge	Flow
Standard Data sheet	RZMO FS007, FS065	RZGO FS015, FS070	AGMZO FS035	AGRCZO FS050	DHRZO TF040	DHZO, DKZOR FS160	DPZO FS170	LICZO, LIMZO, LIRZO FS300	QVHZO, QVKZOR FS410
Ex-proof	RZMA	RZGA	AGMZA	AGRCZA	DHRZA	DHZA, DKZA	DPZA	LICZA, LIMZA, LIRZA	QVHZA, QVKZA
Data sheet	FX010	FX040	FX010	FX040	FX070	FX100	FX200	FX300	FX400
Driver model		E-BM-AES							

E-BM-AES

Digital drivers (1) control the current to the solenoid of Atos proportional valves without transducer, according to the electronic reference input signal.

E-BM-AES operate direct and pilot operated proportional valves ZO-A without tran-

Atos PC software allows to customize the driver configuration to the specific application requirements.

Electrical Features:

- 7 fast plug-in connectors (2)
- Mini USB port (3) always present
- DB9 CANopen (a) and PROFIBUS DP (5) communication connector
- RJ45 EtherCAT communication connectors (6) output and (7) input
- 4 leds for diagnostics (8) (see 4.1)
- ±5 Vpc output supply for external reference
- · Electrical protection against reverse polarity of power supply
- Operating temperature range: -20 ÷ +60 °C
- Plastic box with IP20 protection degree and standard DIN-rail mounting CE mark according to EMC directive

- Intuitive graphic interface
- Setting of valve's functional parameters: bias, scale, ramps, dither, PID gains
- Linearization function for hydraulic regulation
- /W option max power limitation function
- Complete diagnostics of driver status
- Internal oscilloscope function
- In field firmware update through USB port

Fieldbus Features:

- Valve direct communication with machine control unit for digital reference, diagnostics and settings
- Fieldbus execution allow to operate the valves via fieldbus or via analog signals available on the connectors (see 4.2)

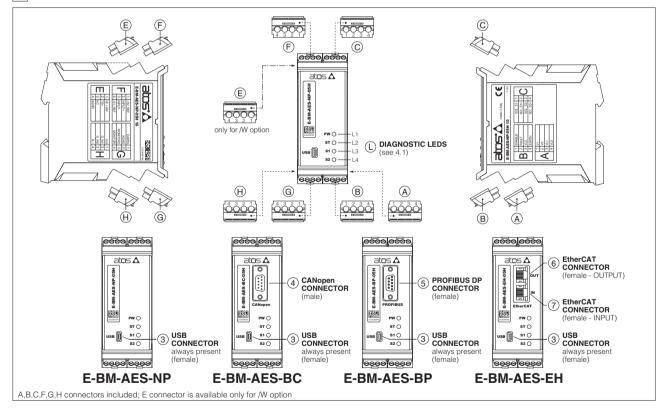
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3 MAIN CHARACTERISTICS

Power supply (see 5.1, 5.2)	Nominal Rectified and filtered	: +24 Vdc : Vrms = 20 ÷ 32 Vmax (rip	ple max 10 % Vpp)					
Max power consumption	50 W	50 W						
Current supplied to solenoids			andard proportional valves (3, <-proof proportional valves (3,					
Analog input signals (see 5.3)		nge ±10 Vbc Input impedar nge ±20 mA Input impedar						
Monitor output (see 5.4)	Voltage: maximum rai	nge ±5 Vpc @max 5 mA						
Enable input (see 5.5)	Range : 0 ÷ 9 Voc (Of	FF state), 15 ÷ 24 Vpc (ON st	tate), 9 ÷ 15 Vpc (not accepted	l); Input impedance: Ri > 87 k Ω				
Output supply (see 5.8)	±5 Vpc @ max 10 mA	: output supply for external p	ootentiometer					
Fault output (see 5.6)	Output range : 0 ÷ 24 external negative volta	VDC (ON state \cong VL+ [logic age not allowed (e.g. due to	c power supply] ; OFF state ≅ inductive loads)	0 V) @ max 50 mA;				
Pressure transducer power supply (only for /W option)	+24VDC @ max 100 r	mA (E-ATR-8 see tech tabl	e GS465)					
Alarms	Solenoid not connecte power supplies level, j	d/short circuit, cable break pressure transducer failure	with current reference signal, c	ver/under temperature,				
Format	Plastic box ; IP20 prote	ection degree ; L 35 - H 7,5	mm DIN-rail mounting as per B	EN60715				
Operating temperature	-20 ÷ +60 °C (storage	e -25 ÷ +85 °C)						
Mass	Approx. 330 g							
Additional characteristics	Short circuit protection protection against reve	n of solenoid current supply; erse polarity of power supply	current control by P.I.D. with ra	apid solenoid switching;				
Electromagnetic compatibility (EMC)	According to Directive	2014/30/UE (Immunity: EN	61000-6-2; Emission: EN 6100	D-6-3)				
Compliance	RoHs Directive 2011/6 REACH Regulation (E0	5/EU as last update by 2015 C) n°1907/2006	5/65/EU					
Communication interface	USB CANopen PROFIBUS DP EtherCAT Atos ASCII coding EN50325-4 + DS408 EN50170-2/IEC61158 IEC61158							
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet 100 Base TX				
Recommended wiring cable	LiYCY shielded cables	s: 0,5 mm² max 50 m for log	gic - 1,5 mm ² max 50 m for p	ower supply and solenoids				
Max conductor size (see 9)	2,5 mm ²							

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 Vbc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

4 CONNECTIONS AND LEDS



4.1 Diagnostic LEDs L

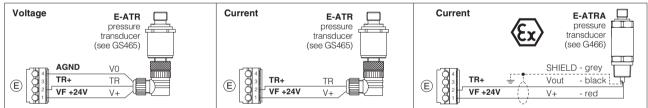
Four leds show driver operative conditions for immediate basic diagnostics. Please refer to the driver user manual for detailed information.

LED	COLOR	FUNCTION	FLASH RATE	DESCRIPTION	
L1	GREEN	PW	OFF	Power supply OFF	
	GHEEN	1 1 1	ON	Power supply ON	st 0 - L2
12	GREEN	ST	OFF	Fault present	USB S1 O L3
LZ	GHEEN	51	ON	No fault	320 L4
L3 and L4	YELLOW	S1 and S2	OFF	PWM command OFF	0000000000
	TLLLOW	51 and 52	ON	PWM command ON	

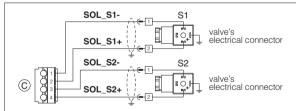
4.2 Connectors - 4 pin

CONNECTOR	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	A1	V+	Power supply 24 Vbc (see 5.1)	Input - power supply
Δ	A2	V0	Power supply 0 Vbc (see 5.1)	Gnd - power supply
~	A3	VL+	Power supply 24 Vpc for driver's logic and communication (see 5.2)	Input - power supply
-	A4	VL0	Power supply 0 Vpc for driver's logic and communication (see 5.2)	Gnd - power supply
	B1	ENABLE	Enable (24 Vbc) or disable (0 Vbc) the driver, referred to VL0 (see 5.5)	Input - on/off signal
B	B2	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0 (see 5.6)	Output - on/off signal
D	B3	VL0	Ground for ENABLE and FAULT	Gnd - digital signals
	B4	EARTH	Connect to system ground	
	C1	SOL_S1-	Negative current to solenoid S1	Output - power PWM
\mathbf{C}	C2	SOL_S1+	Positive current to solenoid S1	Output - power PWM
U	C3	SOL_S2-	Negative current to solenoid S2	Output - power PWM
	C4	SOL_S2+	Positive current to solenoid S2	Output - power PWM
	E1	VF +24V	Power supply +24 VDc	Output - power suppl
F	E2	TR+	Positive pressure transducer input signal: $\pm 10 \text{ Vpc} / \pm 20 \text{ mA maximum range}$ (see 5.7) Default are 0 \div 10 Vpc for standard and 4 \div 20 mA for /C option	Input - analog signal Software selectable
available only	E3	NC	Do not connect	
for /W option	E4	AGND	Common GND for transducer power, signals and external potentiometer	
	F1	+5V_REF	External potentiometer power supply +5 VDc @ 10mA (see 5.8)	Output - power suppl
F	F2	INPUT+	Positive reference input signal: ± 10 Vpc / ± 20 mA maximum range (see 5.3) Default are ± 10 Vpc for standard and $4 \div 20$ mA for /l option	Input - analog signal Software selectable
•	F3	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
-	F4	-5V_REF	External potentiometer power supply -5 VDc @ 10mA (see 5.8)	Output - power suppl
	G1	EARTH	Connect to system ground	
	G2	AGND	Analog ground for MONITOR and external potentiometer	Gnd - analog signal
G	G3	MONITOR2	Only for /W option, 2nd monitor output signal: ±5 Vbc maximum range (see 5.4) Default is 0 ÷ 5 Vbc	Output - analog signa Software selectable
	G4	MONITOR	Monitor output signal: ±5 Vbc maximum range (see 5.4) Default is ±5 Vbc (1V = 1A)	Output - analog signa Software selectable
	H1	VL0	Power supply 0 Vpc for digital input (see 5.2)	Gnd - power supply
LI I	H2	D_IN1	Digital input 0 ÷ 24Vpc, referred to VL0	Input - on/off signal
	H3	D_IN0	Digital input 0 ÷ 24Vpc, referred to VL0	Input - on/off signal
	H4	VL+	Power supply 24 Vbc for digital input (see 5.2)	Output - power supply

Pressure transducer connections - only for /W option



Coils connection

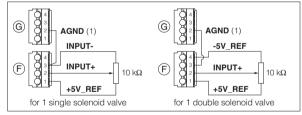


4.3 Communication connectors ③ - ④ - ⑤ - ⑥ - ⑦

3	③ USB connector - Mini USB type B always present					
PIN	SIGNAL TECHNICAL SPECIFICATION (1)					
1	+5V_USB Power supply					
2	D- Data line -					
3	D+	Data line +				
4	ID	Identification				
5	GND_USB	Signal zero data line				
5	5 BP fieldbus execution, connector - DB9 - 9 pin					

(5)	BP fieldbus	BP fieldbus execution, connector - DB9 - 9 pin			
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	SHIELD				
3	LINE-B	Bus line (low)			
5	DGND Data line and termination signal zero +5V Termination supply signal				
6					
8	LINE-A	Bus line (high)			

Potentiometer connection



(1) As alternative the AGND on pin E4 can be used (only /W option)

4	④ BC fieldbus execution, connector - DB9 - 9 pin				
PIN	SIGNAL TECHNICAL SPECIFICATION (1)				
2	CAN_L	Bus line (low)			
3	CAN_GND	Signal zero data line			
5	CAN_SHLD Shield				
7	CAN_H	Bus line (high)			

⑥ ⑦ EH fieldbus execution, connector - RJ45 - 8 pin						
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)				
1	TX+	Transmitter	-	white/orange		
2	RX+	Receiver	-	white/green		
3	TX-	Transmitter	-	orange		
6	RX-	Receiver	-	green		

(1) shield connection on connector's housing is recommended

5 SIGNALS SPECIFICATIONS

Atos digital drivers are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **F003** and in the user manuals included in the E-SW-* programming software.

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and componentshydraulics, EN-982)

5.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

In case of double power supply see 5.2.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

5.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered; apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers. The separate power supply for driver's logic on pin A3 and A4, allow to remove solenoid power supply from pin A1 and A2 maintaining active the diagnostics, USB and fieldbus communications.

/ A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

5.3 Reference input signal (INPUT+)

The driver controls in closed loop the current to the valve proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are ±10 Vbc for standard and 4 ÷ 20 mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vbc or ± 20 mA. Drivers with fieldbus interface (BC, BP, EH) can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range 0 ÷ 24Vbc.

5.4 Monitor output signals (MONITOR and MONITOR2)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference). Monitor output signal is factory preset according to selected valve code, default settings is ± 5 Vpc (1V = 1A).

Output signal can be reconfigured via software, within a maximum range of ± 5 Vpc.

Option /W

The driver generates a second analog output signal (MONITOR2) proportional to the actual system pressure. The output maximum range is ±5 Vpc; default setting is 0 ÷ 5 Vpc.

5.5 Enable input signal (ENABLE)

To enable the driver, supply 24 V_{DC} on pin B1: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

5.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal broken for 4 ÷ 20 mA input, etc.). Fault presence corresponds to 0 Vbc, normal working corresponds to 24 Vbc. Fault status is not affected by the Enable input signal.

5.7 Remote pressure transducer input signal (TR+) - only for /W option

Analog pressure transducers can be directly connected to the driver.

Analog input signal is factory preset according to selected driver code, defaults are 0 ÷ 10 Vbc for standard and 4 ÷ 20 mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vpc or ± 20 mA. Note: transducer feedback can be read as a digital information through fieldbus communication - software selectable.

5.8 Output supply for external potentiometer (±5V_REF) - not available for EH version

The reference analog signal can be generated by one external potentiometer directly connected to the driver, using the ±5 VDC supply output available at pin F1 and F4.

Note: using an external potentiometer, the reference input signal must be set via software at ±5 Vbc (default ±10 Vbc, see 5.3)

5.9 Possible combined options: /AI, /AW, /IW, /AIW, /ACW, /CIW, /ACIW, /CW

6 VALVE SETTINGS AND PROGRAMMING TOOLS

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table GS003). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)
E-SW-FIELDBUS	support:	BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)	EI (EtherNet/IP)	EP (PROFINET)
E-SW-*/PQ	support:	valves with SP. SF. S	SL alternated control (e	a, E-SW-BASIC/PQ)

WARNING: drivers USB port is not isolated! For E-C-SB-USB/BM cable, the use of isolator adapter is highly recommended for PC protection

Free programming software, web download:

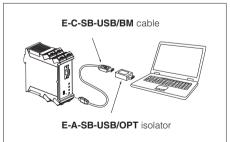
E-SW-BASIC web download = software can be downloaded upon web registration at ; service and DVD not included Upon web registration user receive via email the Activation Code (software free license) and login data to access Atos Download Area

DVD programming software, to be ordered separately:

- E-SW-*/PQ DVD first supply = software has to be activated via web registration at ; 1 year service included Upon web registration user receive via email the Activation Code (software license) and login data to access Atos Download Area
- E-SW-*-N/PQ DVD next supplies = only for supplies after the first; service not included, web registration not allowed Software has to be activated with Activation Code received upon first supply web registration

Atos Download Area: direct access to latest releases of E-SW software, manuals, USB drivers and fieldbus configuration files at USB Adapters, Cables and Terminators, can be ordered separately

USB connection



7 MAIN SOFTWARE PARAMETER SETTINGS

The following is a brief description of the main settings and features of digital drivers.

For a detailed descriptions of available settings, wirings and installation procedures, please refer to the user manual included in the E-SW programming software:

E-MAN-BM-AES - user manual for E-BM-AES

7.1 Scale

Scale function allows to set the maximum current supplied to the solenoid, corresponding to the max valve regulation, at maximum reference signal value.

This regulation allows to adapt the maximum current supplied from the driver to the specific nominal current of the proportional valves to which the driver is coupled; it is also useful to reduce the maximum valve regulation in front of maximum reference signal.

Two different Scale regulations are available for double solenoid valves: ScaleA for positive reference signal and ScaleB for negative reference signal.

7.2 Bias and Threshold

Proportional valves may be provided with a dead band in the hydraulic regulation corresponding to their switch-off status.

This dead band discontinuity in the valve's regulation can be compensated by activating the Bias function, which adds a fixed preset Bias value to the reference signal (analog or fieldbus external input).

The Bias function is activated when the reference signal overcomes the Threshold value, preset into the driver.

The Bias setting allows to calibrate the Bias current to the specific proportional valve to which the driver is coupled.

The Threshold setting is useful to avoid undesired valve regulation at zero reference signal when electric noise is present on the analog input signal: smaller threshold reduces the reference signal dead band, greater values are less affected by electric noise presence.

If fieldbus reference signal is active (see 5.3), threshold should be set to zero.

Two different Bias regulations are available for double solenoid valves: positive reference signals activate BiasA and negative reference signals activate BiasB.

Refer to the programming manuals for a detailed description of other software selectable Bias functions.

7.3 Offset

Proportional valves may be provided with zero overlapping in the hydraulic regulation corresponding to zero reference input signal (valve's central spool position).

The Offset function allows to calibrate the Offset current, required to obtain valve's spool central position, to the specific hydraulic system setup (e.g. valve applied to cylinder with differential areas).

7.4 Ramps

The ramp generator allows to convert sudden change of electronic reference signal into smooth time-dependent increasing/decreasing of the current supplied to the solenoid.

- Different ramp mode can be set:
- single ramp for any reference variation
 two ramps for increasing and for decreasing reference variations
- two ramps for increasing and for decreasing reference variations

- four ramps for positive/negative signal values and increasing/decreasing reference variations Ramp generator is useful for application where smooth hydraulic actuation is necessary to avoid machine vibration and shocks.

If the proportional valve is driven by a closed loop controller, the ramps can lead to unstable behaviour, for these applications ramp function can be software disabled (default setting).

7.5 Linearization - E-SW level 2 functionality

Linearization function allows to set the relation between the reference input signal and the controlled valve's regulation.

Linearization is useful for applications where it is required to linearize the valve's regulation in a defined working condition.

7.6 Variable Dither

The dither is the frequency modulation of the current supplied to the solenoid. To reduce the hysteresis should be selected a lower value of frequency, despite a lower regulation stability, because a small vibration in the valve regulating parts considerably reduces static friction effects.

To improve the regulation stability, should be selected a high value of frequency, despite a higher hysteresis. This solution in some application can lead to vibration and noise. Normally, the right setting is a compromise and depends on system setup.

E-BM-AES drivers allow to realize a variable dither frequency that linearly depends on the demanded current: variable dither frequency allows an higher degree to optimize the valve hysteresis.

7.7 Hydraulic Power Limitation - only for /W option

Digital E-BM-AES drivers with /W option electronically perform hydraulic power limitation on:

- direct and pilot operated flow control valves
- direct and pilot operated directional control valves + mechanical pressure compensator

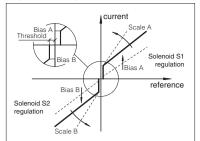
- variable displacement pumps with proportional flow regulator (e.g. PVPC-*-LQZ, tech table A170)

The driver receives the flow reference signal by the analog external input INPUT+ (see 5.3) and a pressure transducer, installed in the hydraulic system, has to be connected to the driver's analog input TR (see 5.7).

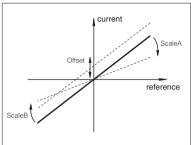
When the actual requested hydraulic power pxQ (TR x INPUT+) reaches the max power limit (p1xQ1), internally set by software, the driver automatically reduces the flow regulation of the valve. The higher is the pressure feedback the lower is the valve's regulated flow:

Flow regulation = Min (<u>PowerLimit [sw setting]</u>; Flow Reference [INPUT+]) Transducer Pressure [TR]

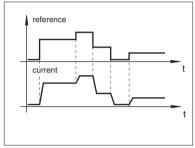
7.1, 7.2 - Scale, Bias & Threshold



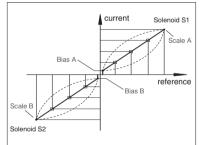




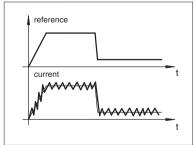




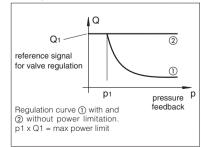
7.5 - Linearization



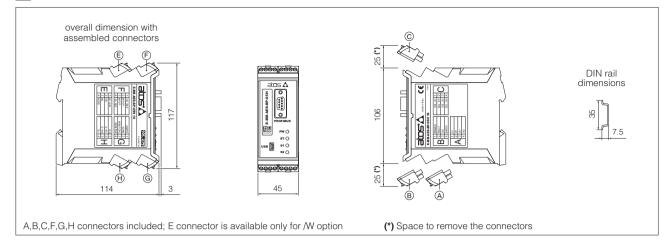
7.6 - Variable Dither



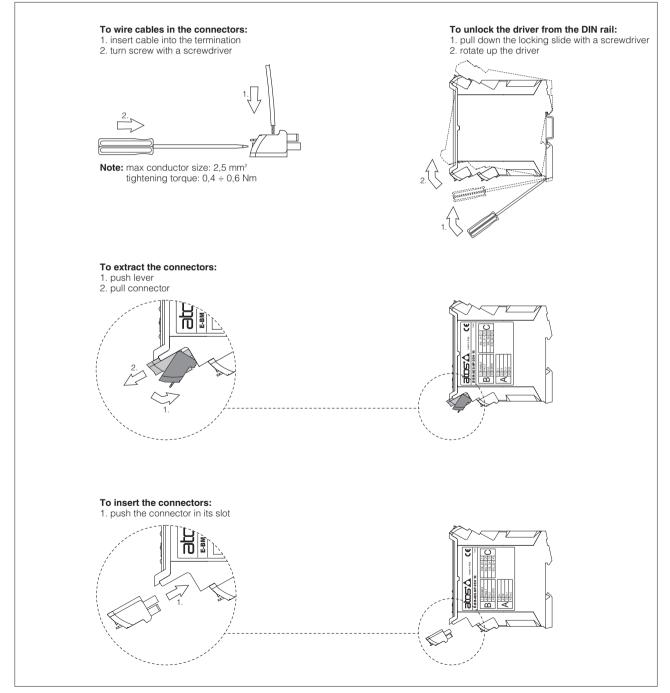
7.7 - Hydraulic Power Limitation



8 OVERALL DIMENSIONS [mm]



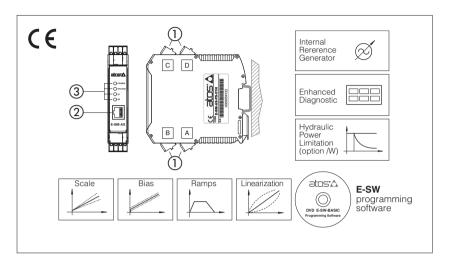
9 INSTALLATION



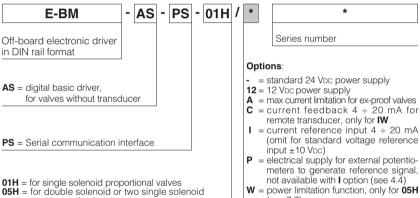
Note: all connectors are supplied with a mechanical coding. This feature ensures a unique insertion of each connector in the own slot (eg. connector A can not be inserted into connector slot of B, C, E, F, G, H)

Digital electronic E-BM-AS drivers

DIN-rail format, for proportional valves without transducer



1 MODEL CODE



proportional valves

- (omit for standard voltage reference
- meters to generate reference signal, not available with I option (see 4.4) power limitation function, only for 05H
- (see 7.7)

E-BM-AS

Digital drivers control the current to the solenoid of Atos proportional valves without transducer, according to the electronic reference input signal.

The solenoid proportionally transforms the current into a force, acting on the valve spool or poppet, against a reacting spring, thus providing the hydraulic regulation. E-BM-AS can drive up to two single or one double solenoid proportional valves.

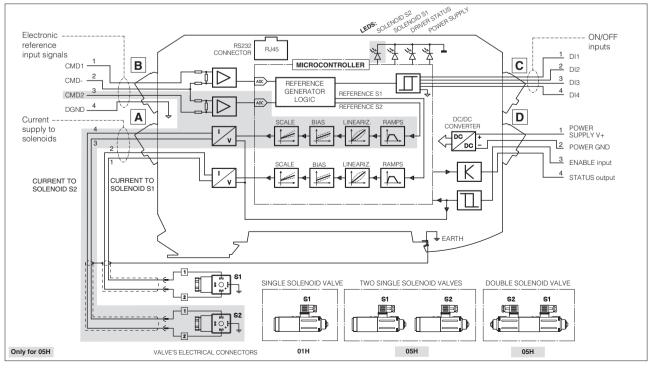
Electrical Features:

- 4 fast plug-in connectors (1)
- RJ45 connector (2) for RS232 Serial communication to program the driver with the Atos PC software
- 4 leds for diagnostics (3) (see section 10)
- ±5 Vpc output supply for external reference potentiometers (/P option)
- · Electrical protection against reverse polarity of power supply
- Operating temperature range: -20 ÷ +60 °C
- Plastic box with IP20 protection degree • and standard DIN-rail mounting
- CE mark according to EMC directive

Software Features:

- Intuitive graphic interface
- Setting of valve's functional parameters: • bias, scale, ramps, dither
- Linearization function for the hydraulic regulation
- 2 selectable modes for electronic reference signal: external analog input or internal generation
- /W option max power limitation function
- Complete diagnostics of driver status

2 BLOCK DIAGRAM



3 MAIN CHARACTERISTICS

	Standard Nominal: +24 VDC Rectified and filtered: VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)
Power supply (see 4.1)	option /12 Nominal: +12 VDC Rectified and filtered: VRMS = 20 ÷ 32 VMAX (hpple max 10 % VPP) Rectified and filtered: VRMS = 10 ÷ 14 VMAX (ripple max 10 % VPP)
Max power consumption	50 W01H single solenoid valve and 05H double solenoid valve100 W05H two single solenoid valves
Current supplied to solenoids	$\begin{array}{l} \mbox{IMAX} = 2.7 \mbox{ A with } +24 \mbox{ VDC } \mbox{ power supply for standard proportional valves (3,2 Ω solenoid) \\ \mbox{IMAX} = 3.3 \mbox{ A with } +12 \mbox{ VDC } \mbox{ power supply for proportional valves with } /6 \mbox{ option (2,1 Ω solenoid) \\ \mbox{IMAX} = 2.5 \mbox{ A with } +24 \mbox{ VDC } \mbox{ power supply for ex-proof proportional valves (3,2 Ω solenoid) \\ \mbox{IMAX} = 2.5 \mbox{ A with } +24 \mbox{ VDC } \mbox{ power supply for ex-proof proportional valves (3,2 Ω solenoid) \\ \mbox{IMAX} = 2.5 \mbox{ A with } +24 \mbox{ VDC } \mbox{ power supply for ex-proof proportional valves (3,2 Ω solenoid) \\ \mbox{ option } \mbox{ A option } A option$
Analog input signal (see 4.2)	Voltage: range ± 10 VDCInput impedance: Ri > 50 k Ω Current: range ± 20 mAInput impedance: Ri = 500 Ω
Enable and optical insulated ON/OFF inputs (see 4.5, 4.7)	$\begin{array}{l} \mbox{Range: } 0 \div 24 \mbox{ VDC } (\mbox{ OFF state: } 0 \div 5 \mbox{ VDC } ; \mbox{ON state: } 9 \div 24 \mbox{ VDC }) \\ \mbox{Input impedance: } Ri > 10 \mbox{ k}\Omega \end{array}$
Output supply (see 4.4)	±5 VDC @ max 10 mA : output supply for external potentiometers (only for /P option)
Status output (see 4.6)	Output range : 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 1,4 A
Alarms	Solenoid not connected, short circuit and cable break with current reference signal
Format	Plastic box ; IP20 protection degree ; L 35 - H 7,5 mm rail mounting as per EN60715
Operating temperature	-20 ÷ +60 °C (-20 ÷ +40 °C for 05H version if drive two single solenoid proportional valves; storage -25 ÷ +85 °C)
Mass	130 g
Additional characteristics	Short circuit protection of current output to solenoids; protection against reverse polarity of power supply
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE - Immunity: EN 61000-6-2 (2005); Emission: EN 61000-6-4 (2001)
Compliance	RoHs Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006
Communication interface	RS232 serial connection (not insulated), Atos protocol with ASCII coding (see section 9)
Recommended wiring cable	LiYCY shielded cables: 0,5 mm ² for length up to 40 m [1,5 mm ² for power supply and solenoids]
Max conductor size (see section 12)	2,5 mm ²

4 SIGNALS SPECIFICATIONS

4.1 Power supply

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse for 01H single solenoid valve and 05H double solenoid valve 5 A time lag fuse for 05H two single solenoid valves

Option /12

This driver execution is designed to receive a 12 VDC power supply and it is commonly used in mobile application.

A safety fuse is required in series to each driver power supply:

A safety fuse is required in series to each power supply:	4 A time lag fuse for 01H single solenoid valve and 05H double solenoid valve
 2	6,3 A time lag fuse for 05H two single solenoid valves

4.2 Reference Input Signals (pin B1 and B3, both referred to pin B2)

The driver proportionally transforms the external reference input signal into the current supplied to the solenoid. The driver is designed to receive one (01H) or two (05H) analog reference inputs (CMD1 on pin B1, CMD2 on pin B3); both signals are referred to a common electric ground (CMD- on pin B2). CMD1 has to be used in case of 05H version that drives one double solenoid valve. CMD2 has to be used in case of 05H version that drives two single solenoid valves or transducer input for *I*/W option (see 4.3). The input range is software selectable among voltage ($0 \div \pm 10$ VDC) or current ($4 \div 20$ mA with cable break detection or $0 \div \pm 20$ mA). Defaults for standard: $0 \div 10$ VDc for two position valves; $0 \div \pm 10$ VDc for three position valves (see valve's tech. table). Default for *I*/I option: $4 \div 20$ mA (see valve's tech. table) Other ranges can be set by software. Internal reference generation is software selectable (see 7.6).

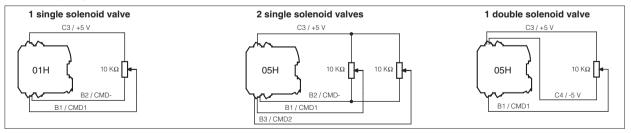
Note: software selection of analog input range (voltage or current) is applied to both signals CMD1 and CMD2.

4.3 Pressure Input Signal (pin B3 referred to pin B2) only for, /W option)

When hydraulic power limitation is active (see 7.7), input signal CMD2 must be connected to an external pressure transducer installed on the hydraulic system; maximum input range 0 ÷ 10 VDC.

4.4 Output supply Signal for external reference potentiometers (/P option)

The reference analog signals can be generated by one (01H) or two (05H) external potentiometers directly connected to the driver, using the ±5 VDC supply output available at pin C3 and C4. Reference input signal can be set up via software to ±5 VDC, in order to match potentiometer output signal.



4.5 Enable Input Signal (pin D3 referred to pin D2)

Enable input signal allows to enable/disable the current supply to the solenoids, without removing the electrical power supply to the driver; it is used to maintain active the serial connection and the other driver functions when the valve must be disabled for safety reasons. To enable the driver, supply a 24VDC on pin D3 referred to pin D2.

4.6 Status Output Signal (pin D4 referred to pin D2)

Status output signal indicates fault conditions of the driver (short circuits, solenoids not connected, cable broken for 4 ÷ 20mA input) and is not affected by Enable input signal status: fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. When hydraulic power limitation function is active (see 7.7), status output signal can be software configured to indicate power limitation status: not active (0 VDC) or active (24 VDC).

4.7 ON/OFF Input Signals (pin C1...C4 referred to DGND pin B4)

Analog Drivers Compatibility - default for series 12 or higher

The four ON/OFF digital input signals (DI) can be used to activate compatibility functionalities with E-BM-AC and E-ME-AC analog drivers (see section 5). If digital inputs are not connected, the driver behavior corresponds to an E-BM-AS series 11 or lower or

Internal Reference Generation - software selectable

When the driver is configured in internal reference generation mode (see 7.6), the 4 ON/OFF input signals (DI) are used to select the active reference signal, among the available stored values. If the 4 ON/OFF input signals (DI) are not active, the driver can be commanded by external analog reference. The polarity of the digital inputs can be customized: active status = 24 VDC is the default setting. Note: for /P option DI3 and DI4 are not available

4.8 Possible combined options:

/12W, /12PW, /12CIW, /AW, /ACIW, /APW, /CIW, /PW only for 05H /12I, /12P, /AI, /AP for 01H and 05H

5 ANALOG DRIVERS COMPATIBILITY - only for E-BM-AS series 12 or higher

E-BM-AS digital inputs (DI1..DI4) activate compatibility functionalities with E-BM-AC and E-ME-AC analog drivers:

REFERENCE COMPATIBILITY

uts Signals	Digital driver	Analog driver	24 VDC to DI1:	0 VDC to DI1:			
24 VDC		E-BM-AC 05F E-BM-AC 011F E-ME-AC 01F	01H				
0 Vdc	E-BM-AS 01H		Current 4 ÷ 20 mA / 0 ÷ 100%	See section 4.2			
0 Vdc	E-BM-AS 05H		05H Voltage + 5 Vpc / + 100%	See Section 4.2			
0 Vdc		E-ME-AC 05F	Current 4 ÷ 20 mA / 0 ÷ 100%				
	24 VDC 0 VDC 0 VDC	24 VDC 0 VDC 0 VDC E-BM-AS 01H E-BM-AS 05H	24 VDC E-BM-AS 01H E-BM-AC 01F 0 VDC E-BM-AS 05H E-BM-AC 01F 0 VDc E-BM-AS 05H E-BM-AC 01F 0 VDc E-BM-AS 05H E-BM-AC 01F	24 Vpc 01H 0 Vpc E-BM-AS 01H 0 Vpc E-BM-AS 05H E-BM-AS 05H E-BM-AC 01F E-BM-AC 01F Current 4 ÷ 20 mA / 0 ÷ 100% 0 Vpc E-BM-AS 05H E-BM-AC 01F 05H Voltage ± 5 Vpc / ± 100%			

Note: set 0 VDC to DI1 and power-off/on the driver to restore latest settings

REFERENCE INVERSION

Digital Inpu	uts Signals	Digital driver	Analog driver	24 VDC to DI2:	0 VDC to DI2:
DI1	24 VDC	E-BM-AS 05H		Voltage 0 ÷ 5 Vpc / 0 ÷ -100% Current 4 ÷ 20 mA / 0 ÷ -100%	Voltage 0 ÷ 5 Vpc / 0 ÷ 100% Current 4 ÷ 20 mA / 0 ÷ 100%
DI2	24 VDC				
DI3	0 Vdc				
DI4	0 Vdc				

Note: to enable reference inversion, set 24 VDC to DI1 before driver power-on

RAMP SWITCH OFF

Digital Inputs Signals		Digital driver	Analog driver	24 VDC to DI3:	0 VDC to DI3:
DI1	24 VDC	E-BM-AS 01H	E-ME-AC 01F E-ME-AC 05F		Down activity d
DI2	0 Vdc			Ramp excluded	
DI3	24 VDC	E-BM-AS 05H		hamp excluded	Ramp activated
DI4	0 Vdc				

Notes: to enable ramp switch off, set 24 VDC to DI1 before driver power-on; DI3 not available for /P option

011F CONFIGURATION

[Digital inpu	uts dignals	Digital driver	Analog driver	24 VDC to DI4:	0 VDC to DI4:
	DI1	(*)				
	DI2	(*)	E-BM-AS 05H	E-BM-AC 011F	Driver configuration 011F	Driver configuration 05H
	DI3	(*)	L-DIVI-AS USI I			
ſ	DI4	24 VDC			(*) = don't care	(*) = don't care

Notes: set 0 VDC to DI4 and power-off/on the driver to restore latest settings; DI4 not available for /P option

6 VALVE SETTINGS AND PROGRAMMING TOOLS

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via RS232 serial port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500): support: NP (USB) E-SW-BASIC PS (Serial) IR (Infrared) BP (PROFIBUS DP) E-SW-FIELDBUS support: BC (CANopen) EH (EtherCAT) EW (POWERLINK) EI (EtherNet/IP) EP (PROFINET) E-SW-*/PQ support: valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

WARNING: drivers RS232 port is not isolated!

Free programming software, web download:

E-SW-BASIC

web download = software can be downloaded upon web registration at ; service and DVD not included Upon web registration user receive via email the Activation Code (software free license) and login data to access Atos Download Area

DVD programming software, to be ordered separately:

DVD first supply = software has to be activated via web registration at ; 1 year service included E-SW-*/PQ Jpon web

registration user receive via email the Activation Code (software license) and login data to access Atos Download Area

E-SW-*-N/PQ DVD next supplies = only for supplies after the first; service not included, web registration not allowed Software has to be activated with Activation Code received upon first supply web registration

Atos Download Area: direct access to latest releases of E-SW software, manuals, USB drivers and fieldbus configuration files at USB

Adapters, Cables and Terminators, can be ordered separately

Connection

E-A-PS-USB/DB9 USB to serial adapter

E-C-PS-DB9/RJ45 serial cable

6

7 MAIN SOFTWARE PARAMETER SETTINGS

The following is a brief description of the main settings and features of digital drivers. For a detailed descriptions of available settings, wirings and installation procedures, please refer to the user manual included in the E-SW programming software: E-MAN-BM-AS - user manual for E-BM-AS

7.1 Scale

Scale function allows to set the maximum current supplied to the solenoid, corresponding to the max valve regulation, at maximum reference signal value.

This regulation allows to adapt the maximum current supplied from the driver to the specific nominal current of the proportional valves to which the driver is coupled; it is also useful to reduce the maximum valve regulation in front of maximum reference signal.

For double solenoid valves two different Scale regulations are available:

ScaleA for positive reference signal and ScaleB for negative reference signal

7.2 Bias and Threshold

Proportional valves may be provided with a dead band in the hydraulic regulation corresponding to their switch-off status.

This dead band discontinuity in the valve's regulation can be compensated by activating the Bias function, which adds a fixed preset Bias value to the reference signal (external input or internally generated).

The Bias function is activated when the reference signal overcome the Threshold value, preset into the driver.

The Bias setting allows to calibrate the Bias current supplied to the solenoid of the specific proportional valve to which the driver is coupled.

The Threshold setting is useful to avoid undesired valve regulation at zero reference signal when electric noise is present on the analog input signal: smaller threshold reduces the reference signal dead band, greater values are less affected by electric noise presence.

If internal reference generation is active (see 7.6), threshold should be set to 0.

For double solenoid valves two different Bias regulations are available: positive reference signal activates BiasA for solenoid S1 and negative reference signal activates BiasB for solenoid S2

7.3 Ramps

The ramp generator allows to convert sudden change of electronic reference signal into smooth time-dependent increasing/decreasing of the current supplied to the solenoid. Different ramp mode can be set:

- single ramp for any reference variation
- two ramps for increasing and for decreasing reference variations

- four ramps for positive/negative signal values and increasing/decreasing reference variations Ramp generator is useful for application where smooth hydraulic actuation is necessary to avoid machine vibration and shocks.

If the proportional valve is driven by a closed loop controller, the ramps can lead to unstable behaviour, for these applications ramp function can be software disabled (default setting)

7.4 Dither

The dither is an high frequency modulation of the current supplied to the solenoid, to reduce the hysteresis of the valve's regulation: a small vibration in the valve's regulating parts considerably reduces static friction effects.

Dither frequency can be set in a range from 80 to 500 Hz (default value is 200Hz).

Lower dither setting reduces the hysteresis but also reduces the regulation stability. In some application this can lead to vibration and noise: right setting usually depends on system setup. Default dither is a valid setting for a wide range of hydraulic applications

7.5 Linearization

Linearization function allows to set the relation between the reference input signal and the current supplied to the solenoid.

Linearization is useful for applications where it is required to linearize the valve's regulation in a defined working condition (e.g. maximum pressure control at defined working flow)

7.6 Internal Reference Generation

Internal generation of reference values is software selectable.

In this mode the 4 digital inputs of the driver (DI1..DI4) allow to activate the desired internal reference signal, among the different driver's stored values: external control unit can thus manage complex machine profile by simple switching the reference signal, by 4 digital inputs (see 4.7).

The digital inputs are software configurable into 2 different reference selection mode:

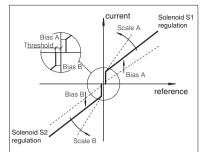
- Standard mode
- each digital input corresponds to a different value; up to 4 different internal values are available (2+2 with E-BM-AS-PS-05H driving two single solenoid valves)
- Binarv mode

each digital input combination corresponds to a different value; up to 15 different internal values are available (3+3 with E-BM-AS-PS-05H when driving two single solenoid valves)

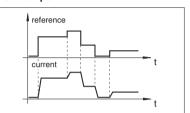
A dedicated ramp time value can be set by software for each available stored reference value.

Note: with all input signals (DI) set to zero, the driver can be commanded by external analog reference also if internal reference generation is selected (for more information please refer to the programming manual E-MAN-BM-AS).

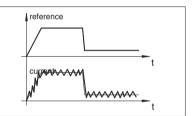
7.1, 7.2 - Scale, Bias & Threshold



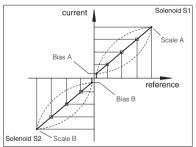
7.3 - Ramps



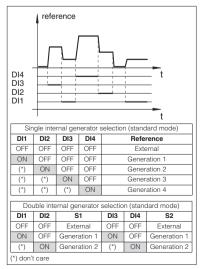
7.4 - Dither



7.5 - Linearization



7.6 - Internal Reference Generation



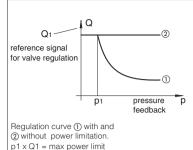
7.7 Hydraulic Power Limitation (/W option, only for drivers E-BM-AS-PS-05H)

- E-BM-AS drivers with /W option electronically perform hydraulic power limitation on:
- direct and pilot operated flow control valves
- direct and pilot operated directional control valves + mechanical pressure compensator
- variable displacement pumps with proportional flow regulator
- (e.g. PVPC-*-LQZ, tech. table A170)

The driver receives the flow reference signal by the analog external input CMD1 (see 4.2) or by the internal generator (see 7.6) and a pressure transducer, installed in the hydraulic system, has to be connected to the driver's analog input CMD2.

When the actual requested hydraulic power $\mathbf{p} \times \mathbf{Q}$ (CMD2xCMD1) reaches the max power limit (p1xQ1), internally set by software, the driver automatically reduces the flow regulation of the valve. The higher is the pressure feedback the lower is the valve's regulated flow:

Flow regulation = Min (PowerLimit [sw setting] Transducer Pressure [CMD2]; Flow Reference [CMD1])



8 CONNECTIONS

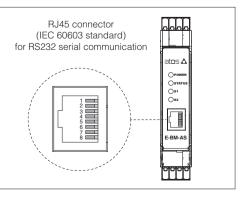
The 4 fast plug-in connectors (A,B,C,D), included in the supply, provide simple wirings, easy driver's replacement and the possibility to test the signals directly on the connectors.

CONNECTOR	PIN	SIGNAL	TECHNICAL	SPECIFICATIONS	NC	TES	
	A1	SOL S1	Current to solenoid S1				
Α	A2	30L 31					
A	A3	SOL S2			Output - power PWM		
	A4	50L 52	Current to solenoid S2 (only for 05H version))			
	B1	CMD1	Reference analog input: ±10 Vpc / ± 20 mA				
			Standard	/P option (see 4.4)			
В	B2	CMD-	Zero signal, ground for reference signals	Reference for ±5 Vpc output (AGND)	Input - analog signal		
	B3	CMD2 (1)	Reference analog input: ± 10 Vpc / ± 20 mA maximum range software selectable (see 4.2)				
	B4	DGND	Optical insulated ground for on/off inputs (D				
			Standard	/P option (see 4.4)	Standard	Option /P	
	C1	DI1		Optical insulated on/off input 0 ÷ 24 VDc referred to pin B4 DGND (see 4.7)	Input - on/	loff cignal	
С	C2	DI2	Optical insulated on/off input 0 ÷ 24 Vbc	For analog driver compatibility see section 5	input - on/	on signai	
	C3	DI3	referred to pin B4 DGND (see 4.7) For analog driver compatibility see section 5	+5 Vbc @ 10 mA output supply to pin B2 (AGND)		Output - reference	
	C4	DI4	-	-5 VDC @ 10 mA output supply to pin B2 (AGND)	on/off	analog	
	D1	V+	Power supply 24 Vbc (see 4.1)		Input no	vor oupply	
D	D2	VO	Power supply 0 Vbc		1 input - pov	wer supply	
U	D3	ENABLE	Enable (24 VDC) or disable (0 VDC) the driver	r (see 4.5)	Input - on/	off signal	
	D4	STATUS	Fault (default) or software selected output (s	see 4.6)	Output - on/off signal		

(1) Only for 05H version, when used to drive two single solenoid valves or transducer input for /W option **WARNING:** if CMD2 is not used has to be connect to CMD- (ground)

9 RJ45 CONNECTOR

RJ45 CONNECTOR				
PIN	SIGNAL	DESCRIPTION		
1	/	Not connected		
2	/	Not connected		
3	/	Not connected		
4	GND	Signal zero data line		
5	RX	Driver receiving data line		
6	TX	Driver transmitting data line		
7	/	Not connected		
8	/	Not connected		



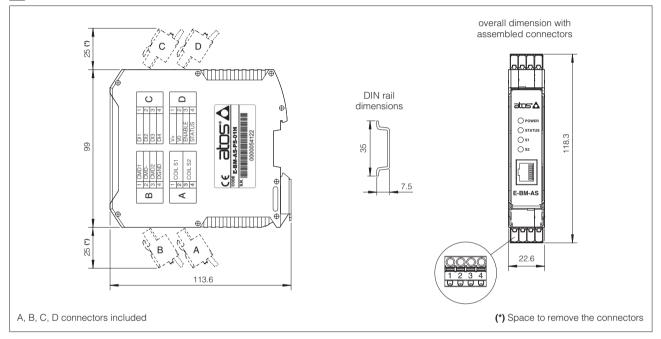
7.7 - Hydraulic Power Limitation

10 DIAGNOSTIC LEDS

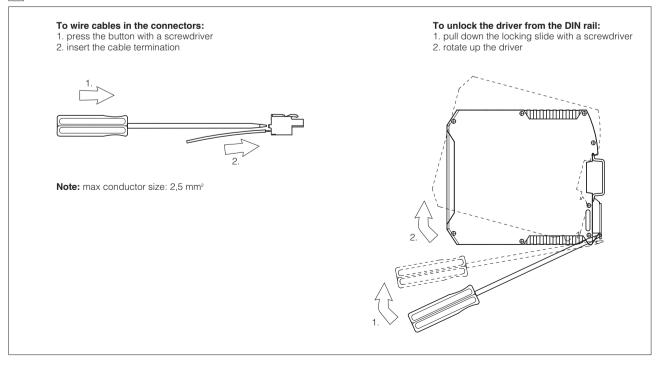
Four leds show driver operative conditions for immediate basic diagnostics. Please refer to the driver user manual for detailed information.

LED	COLOR	FUNCTION	FLASH RATE	DESCRIPTION	
L1	GREEN	POWER	OFF	Power supply OFF	
			ON	Power supply ON	
L2	GREEN	STATUS	OFF or ON	Fault conditions	
			Slow blinking	Driver disabled	
			Fast blinking	Driver enabled	atos 🛆 -
L3 and L4	YELLOW	S1 and S2	OFF	PWM command OFF	L1 — Opower L2 — Ostatus
			ON	PWM command ON	L3 Os1
			Slow blinking	Coil not connected	
			Fast blinking	Short circuit on the solenoid	~ ~

11 OVERALL DIMENSIONS [mm]



12 INSTALLATION



Алматы (7273)495-231 Ангарск (3955)60-70-56 Архангельск (8182)63-90-72 Астрахань (8512)99-46-04 Барнаул (3852)73-04-60 Белгород (4722)40-23-64 Благовещенск (4162)22-76-07 Брянск (4832)59-03-52 Владивосток (423)249-28-31 Владикавказ (8672)28-90-48 Владикавказ (8672)28-90-48 Волгоград (844)278-03-48 Волгоград (844)278-03-48 Волгоград (8172)26-41-59 Ворогда (8172)26-41-59 Воронеж (473)204-51-73 Екатеринбург (343)384-55-89 Иваново (4932)77-34-06 Ижевск (3412)26-03-58 Иркутск (395)279-98-46 Казань (843)206-01-48 Калининград (4012)72-03-81 Калуга (4842)92-23-67 Кемерово (3842)65-04-62 Киров (8332)68-02-04 Коломна (4966)23-41-49 Кострома (4942)77-07-48 Краснодар (861)203-40-90 Красноярск (391)204-63-61 Курск (4712)77-13-04 Курган (3522)50-90-47 Липецк (4742)52-20-81

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